

USN 

--	--	--	--	--	--	--	--	--	--

**Seventh Semester B.E. Degree (CBCS) Examination  
Control Engineering**

Time: 3 hrs.

Max. Marks: 80

**Note: Answer any FIVE full questions, choosing one full question from each module.**

**MODULE – I**

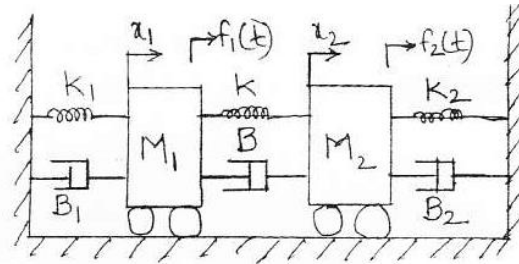
- 1 a With an example for both explain the working of open loop and closed loop control systems. (08 Marks)
- b List the advantages and disadvantages of open loop and closed loop control systems. (08 Marks)

**OR**

- 2 a Explain the requirements of Ideal control system (08 Marks)
- b With help of block diagram explain proportional plus integral controller. (08 Marks)

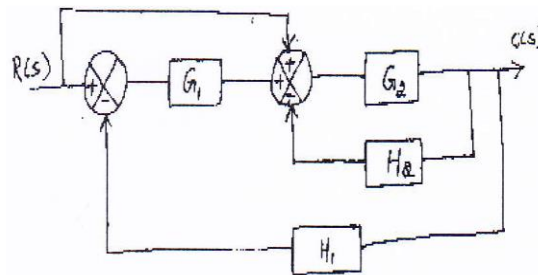
**MODULE – II**

- 3 a Obtain the transfer function of armature controlled DC motor. (08 Marks)
- b Write the differential equations governing the mechanical system shown figure. (08 Marks)  
Also draw F-V and F-I analogous circuits.

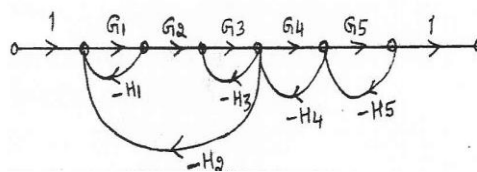


**OR**

- 4 a Reduce the block diagram in fig and obtain its transfer function. (08 Marks)



- b Obtain the overall transfer function for the given SFG. (08 Marks)



**MODULE – III**

- 5 a A system has the following transfer function, (10 Marks)

Important Note: 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. 2. Any revealing of identification, appeal to evaluator and /or equations written e.g. 38+2 = 40, will be treated as malpractice.

$$\frac{C(s)}{R(s)} = \frac{20}{s + 10}$$

Determine its unit impulse, step and ramp response with zero initial conditions. Sketch the responses

- b** Derive an expression for response of 1st order system for unit step input (06 Marks)

**OR**

- 6 a** Sketch the root locus plot for  $G(s)H(s) = \frac{K}{s(s+2)(s+4)(s+6)}$ . For what values of K the system becomes unstable. (16 Marks)

**MODULE – IV**

- 7 a** Draw the Nyquist plot for a given open loop transfer function,  $G(s)H(s) = \frac{5}{s(1-s)}$ . Comment on stability of the control system. (16 Marks)

**OR**

- 8 a** Sketch the Bode plot for the transfer function  $G(s)H(s) = \frac{75(1+0.2s)}{s(s^2+16s+100)}$ . (16 Marks)

**MODULE – V**

- 9 a** Explain the series compensation with neat block diagram. (06 Marks)
- b** Construct a state model using phase variables if the system is described by the differential equation  $y'''(t) + 4y''(t) + 7y'(t) + 2y(t) = 5u(t)$ . (10 Marks)

**OR**

- 10 a** Define the following terms (a) state variables, (b) state space, (d) state trajectory (06 Marks)
- b** Find the observability of the state model using Kalman's test and Gilbert's test (10 Marks)

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \dot{x}_3 \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -2 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, Y = [3 \quad 4 \quad 1] \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$