

Model Question Paper with effect from 2023-24(CBCS Scheme)

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**Fifth Semester B.E. Degree Examination**  
**Digital Signal Processing**

Time: 03 Hours

Max. Marks: 100

Note: Answer any FIVE full questions, choosing at least ONE question from each MODULE.

Sl No	Questions	BTL	Marks
<b>Module 1</b>			
<b>Q1</b>	<b>a</b>	Determine the energy and power of the unit step sequence.	L2 4
	<b>b</b>	Consider an LTI system with input $x(n]$ & unit impulse response $h(n]$ given below, Compute $y(n]$ , $x(n) = 2^n u(-n]$ & $h(n) = u(n]$ .	L3 8
	<b>c</b>	Define signal with example. Explain Classification of signals with examples also define Elementary Discrete-Time Signals.	L2 8
<b>OR</b>			
<b>Q2</b>	<b>a</b>	Determine the response of the following systems to the input signal $x(n) =  n $ $-3 \leq n \leq 3$ $0$ , otherwise a) $y(n) = x(n)$ b) $y(n) = x(n-1)$ c) $y(n) = x(n+1)$ d) $y(n) = 1/3 [x(n+1) + x(n)+x(n-1)]$	L2 4
	<b>b</b>	The impulse response of a linear time-invariant system is $h(n) = \{1, 2, 1, -1\}$ . Determine the response of the system to the input signal $x(n) = \{1, 2, 3, 1\}$ .	L3 8
	<b>c</b>	Define system with example. Explain Classification of Discrete-Time system with examples.	L2 8
<b>Module 2</b>			
<b>Q3</b>	<b>a</b>	Determine the z-transform of the signal $x(n) = a^n u(n) = \begin{cases} n, & n \geq 0 \\ 0, & n < 0 \end{cases}$ and $x(n) = -a^n u(-n-1) = \begin{cases} 0, & n > 0 \\ -a^n, & n \leq -1 \end{cases}$	L3 8
	<b>b</b>	Determine the z-transforms of the following finite-duration signals. $x_1(n) = \{1, 2, 5, 7, 0, 1\}$ (b) $x_2(n) = \{1, 2, 5, 7, 0, 1\}$ .	L3 4
	<b>c</b>	Mention the properties of Z transform with equations.	L2 8
<b>OR</b>			
<b>Q4</b>	<b>a</b>	Perform Circular convolution of the following sequences using concentric circle method: $x_1(n) = \{2, 1, 2, 1\}$ , $x_2(n) = \{1, 2, 3, 4\}$ .	L3 8
	<b>b</b>	Find the DFT of the sequence $x(n) = \delta(n) + 2\delta(n-2) + \delta(n-3)$ .	L3 4
	<b>c</b>	Explain Frequency Domain Sampling and Reconstruction of Discrete Time Signals with the help of necessary equations.	L2 8
<b>Module 3</b>			
<b>Q5</b>	<b>a</b>	State and prove the following properties: i) Circular Time shift Property      ii) Circular Frequency shift Property iii) Parsevals theorem                      iv) Complex conjugate property	L2 10
	<b>b</b>	Use the 8 point radix-2 DIT-FFT algorithm to find the DFT of the sequence $x(n) = \{1, 1, 1, 1, 0, 0, 0, 0\}$ .	L3 10
<b>OR</b>			

Q6	a	Illustrate the Inverse Decimation in Time FFT algorithm with the help of necessary equations and signal flow representation	L2	10
	b	Using linear convolution find $y(n) = x(n) * h(n)$ for the sequences $x(n) = \{1, 2, -1, 2, 3, -2, -3, -1, 1, 1, 2, -1\}$ & $h(n) = \{1, 2\}$ . Compare the result by solving the problem using overlap save & overlap add method.	L3	10
<b>Module 4</b>				
Q7	a	The desired frequency response of a low pass filter is given by $H_d(e^{j\omega}) = H_d(\omega) = \begin{cases} e^{-j3\omega} & , \quad  \omega  < 3\pi/4 \\ 0 & , \quad 3\pi/4 <  \omega  < \pi \end{cases}$ Determine the frequency response of the FIR filter if Hamming window is used with $M=7$ .	L3	10
	b	Mention different windows with equations used in design of FIR filters.	L2	5
	c	Realize the system function $H(z) = 1 + 3/2 z^{-1} + 4/5 z^{-2} + 5/9 z^{-3} + 1/9 z^{-4}$ using direct form .	L2	5
<b>OR</b>				
Q8	a	A filter is to be designed with the desired frequency response $H_d(e^{j\omega}) = H_d(\omega) = \begin{cases} 0 & , \quad -\pi/4 < \omega < \pi/4 \\ e^{-j2\omega} & , \quad \pi/4 <  \omega  < \pi \end{cases}$ Find the frequency response of the FIR filter designed using a rectangular window defined below: $w_R(n) = 1, 0 \leq n \leq 4$ $0, \text{ otherwise}$	L3	10
	b	Mention the Design steps followed in design of Linear Phase FIR Filter.	L2	5
	c	Realize a cascade form FIR filter for the following system function. $H(z) = (1 + 1/4 z^{-1} + z^{-2}) (1 + 1/8 z^{-1} + z^{-2})$ .	L2	5
<b>Module 5</b>				
Q9	a	Design a digital lowpass Butterworth filter with the following specifications: 1. 3 dB attenuation at the passband frequency of 1.5 kHz 2. 10 dB stopband attenuation at the frequency of 3 kHz 3. Sampling frequency of 8,000 Hz.	L3	8
	b	The normalized low pass filter with a cutoff frequency of 1 rad/sec is given as: $H_P(s) = 1/(s+1)$ Use the given $H_P(s)$ and the BLT to design a corresponding digital IIR lowpass filter with a cutoff frequency of 15 Hz and a sampling rate of 90 Hz.	L3	7
	c	Explain Bilinear Transformation design procedure in designing IIR filters.	L2	5
<b>OR</b>				
Q10	a	Obtain analog lowpass prototype transformation to the low pass, high pass, band pass filter, band stop filters.	L2	8
	b	Obtain direct form I and direct form II for the system described by $y(n) = -0.1y(n-1) + 0.2y(n-2) + 3x(n) + 3.6x(n-1) + 0.6x(n-2)$ .	L3	7
	c	Given the following IIR filter: $y(n) = 0.2x(n) + 0.4x(n-1) + 0.5y(n-1)$ , Determine the transfer function, nonzero coefficients, and impulse response.	L2	5