# Scheme of Teaching and Examination and Syllabus M.Tech POWER EECRTONICS (EPE)

Eligibility: Bachelor's degree in Engineering or Technology in

- (a) Electrical and Electronics Engineering (b) Electronics and Communication Engineering
- (c) Electronics and Telecommunication Engineering (d) Telecommunication Engineering
- (e) Electronics and Instrumentation Engineering (f) Instrumentation Engineering
- (g) Biomedical Engineering (h) Medical Electronics (i) AMIE in appropriate branch
- (i) GATE: EC, IT, EE

(Effective from Academic year 2016-17)

BOARD OF STUDIES IN ELECTRICAL AND ELECTRONICS ENGINEERING December 2016

SCHEME OF TEACHING AND EXAMINATION - 2016-17

#### M.Tech POWER EECRTONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)

 $(Total\ number\ of\ credits\ prescribed\ for\ the\ programme\ -\ 85)$ 

#### I SEMESTER

			Teaching Hours / Week Examination						
Sl. No	Course Code	Title	Theory	Practical/ Field work/ Assignment	Duration in hours	I.A. Marks	Theory/ Practical Marks	Total Marks	Credits
1	16EEE11	Applied Mathematics	04		03	20	80	100	4
2	16EPE12	Power Semiconductor Devices and Components	04		03	20	80	100	4
3	16EPE13	Power Electronic Converters	04		03	20	80	100	4
4	16EPE14	Modelling and Design of Controllers	04		03	20	80	100	4
5	16EPE15X	Elective -1	03		03	20	80	100	3
6	16EPEL16	Power Electronics Laboratory - 1	-	3	03	20	80	100	2
7	16EPE17	Seminar	-	3	-	100	-	100	1
TOTAL		19	06	18	220	480	700	22	

Number of credits completed at the end of I semester: 22

		-
E	lective -	

Course Code under 16EPE15X	Title
16EPE151	Embedded Systems
16EPE152	Power System Harmonics
16EPE153	Advanced Control Systems
16EPE154	EMC in Power Electronics

SCHEME OF TEACHING AND EXAMINATION - 2016-17

#### M.Tech POWER EECRTONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)

(Total number of credits prescribed for the programme - 85)

#### II SEMESTER

			Teaching Hours /Week		Examination				
Sl. No	Course Code	Title	Theory	Practical/ Field work/ Assignment	Duration in hours	I.A. Marks	Theory/ Practical Marks	Total Marks	Credits
1	16EPE21	Electric Drives	04		03	20	80	100	4
2	16EPE22	Switched - Mode Power Supplies	04		03	20	80	100	4
3	16EPE23	Modelling and Analysis of Electrical Machines	04		03	20	80	100	4
4	16EPE24	FACTS Controllers	04		03	20	80	100	4
5	16EPE25X	Elective - 2	03		03	20	80	100	3
6	16EPEL26	Power Electronics Laboratory - 2	-	3	03	20	80	100	2
7	16EPE27	Seminar	ı	3	-	100	-	100	1
	TOTAL		19	06	18	220	480	700	22

Number of credits completed at the end of II semester: 22+22=44

#### **Elective - 2**

Course Code under 16EPE25X	Title
16EPE251	Converters for Solar and Wind Power Systems
16EPE252	Uninterruptible Power Supply
16EPE253	Power Quality Problems and Mitigation
16EPE254	Hybrid Electric Vehicles

**Note: Project Phase-1:** 6-week duration shall be carried out between 2<sup>nd</sup> and 3<sup>rd</sup> Semester vacation. Candidates in consultation with the guide shall carry out literature survey/ visit industries to finalize the topic of Project.

SCHEME OF TEACHING AND EXAMINATION - 2016-17

#### M.Tech POWER EECRTONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)

(Total number of credits prescribed for the programme - 85)

#### III SEMESTER

		Teaching Hours /Week		Examination					
Sl. No	Course Code	Title	Theory	Practical/ Field work/ Assignment	Duration in hours	I.A. Marks	Theory/ Practical Marks	Total Marks	Credits
		Seminar / Presentation on							
1	1 16EPE31	Internship.				25		25	
1		(After 8 weeks from the date				25		25	
		of commencement)							20
2	16EPE32	Report on Internship				25		25	
3 16EPE33	Evaluation and Viva-Voce of					50	50		
	10EPE33	Internship					50	50	
4	16EPE34	Evaluation of Project phase -1				50		50	1
TOTAL					100	50	150	21	

Number of credits completed at the end of III semester: 22+22+21=65

#### Note:

Internship of 16 weeks shall be carried out during III semester.

Major part of the Project work shall also be carried out during the III semester in consultation with the Guide/s.

SCHEME OF TEACHING AND EXAMINATION - 2016-17

### M.Tech POWER EECRTONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)

(Total number of credits prescribed for the programme - 85)

#### **IV SEMESTER**

		Title	Teaching Hours /Week		Examination				s
Sl. No	Course Code		Theory	Practical/ Field work/ Assignment	Duration in hours	I.A. Marks	Theory/ Practical Marks	Total Marks	Credits
1	16EPE41	HVDC power Transmission	04		03	20	80	100	4
2	16EPE42X	Elective - 3	03		03	20	80	100	3
3	16EPE43	Evaluation of Project phase - 2				50	-	50	3
4	16EPE44	Evaluation of Project and Viva-Voce					100 + 100	200	10
TOTAL		07		06 90 360 450			450	20	

Number of credits completed at the end of IV semester: 22+22+21+20=85

н	lective	_	-
	CLLVC	-	- 1

Course Code under 16EPE42X	Title
16EPE421	Digital Power Electronics
16EPE422	MPPT in Solar Systems
16EPE423	Multi-Terminal DC Grids
16EPE424	Multilevel Converters for Industrial Applications

**Note: 1. Project Phase-1:** 6-week duration shall be carried out between 2<sup>nd</sup> and 3<sup>rd</sup> Semester vacation. Candidates in consultation with the guide shall carry out literature survey/ visit industries to finalize the topic of Project.

- **2. Project Phase-2:** 16-week duration during 4<sup>th</sup> semester. Evaluation shall be done by the committee comprising of HoD as Chairman, Guide and Senior faculty of the department.
- **3.Project Evaluation**: Evaluation shall be taken up at the end of 4<sup>th</sup> semester. Project work evaluation and Viva-Voce examination shall conducted
- 4. Project evaluation:
  - a. Internal Examiner shall carry out the evaluation for 100 marks.
  - b. External Examiner shall carry out the evaluation for 100 marks.
  - c .The average of marks allotted by the internal and external examiner shall be the final marks of the project evaluation.
  - d. Viva-Voce examination of Project work shall be conducted jointly by Internal and External examiner for 100 marks.

M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)					
	SEMESTER - I				
APPLIED MATHAMATICS (Core Course)					
Course Code	16EEE11	IA Marks	20		
Number of Lecture Hours/Week	04	Exam Hours	03		
Total Number of Lecture Hours	50	Exam Marks	80		
Credits - 04					

• The objectives of this course is to acquaint the students with principles of advanced mathematics through linear algebra, transform methods for differential equations, calculus of variations and linear and non-linear programming, that serve as an essential tool for applications of electrical engineering sciences.

		Teachi Hours
second degree equa method (first order	s: Solution of algebraic and transcendental equations- iterative methods based on ation – Muller method(no derivation), Chebyshev method. Fixed point iteration by, acceleration of convergence- Δ² - Aitken's method. System of non-linear large-Raphson method. Complex roots by Bairstow's method. ■  L₂ – Understanding, L₃ – Applying	10
Faxonomy Level Module-2	E <sub>2</sub> Chaotsunding, E <sub>3</sub> Tapping	
parabolic equations method. Hyperbolic	of Partial Differential Equations: Classification of second order equations, solution of one dimensional heat equation, explicit method, Crank-Nicolson equations- solution of one dimensional wave equation and two-dimensional explicit method.	10
Revised Bloom's Taxonomy Level	$L_3$ – Applying	
Module-3		,
properties, example <b>Linear Transform</b> linear transformatio transformations by	ations: Definition, properties, range and null space, rank and nullity, algebra of ns-invertible, singular and non-singular transformations, representation of	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding	
Module-4		
	<b>gebraic equations and Eigen value problems:</b> Iterative methods - Gauss-Seidal od, Eigen value problems – Gerschgorian circle theorem, Eigen values and Eigen netric matrices -Jacobi method.	10
vectors of real symr	mite interpolation, spline interpolation, numerical solution of differential	
vectors of real symmetric vectors of real symmetric vectors. Here	mite interpolation, spline interpolation, numerical solution of differential	
vectors of real symmather symmetric vectors of real symmetric vectors	mite interpolation, spline interpolation, numerical solution of differential ov method. ■	
rectors of real symmater polation: Here equations – Numeron Revised Bloom's Taxonomy Level Module-5  Optimization: Lin problem, simplex many Graph Theory: Bagraphs-walks, paths	mite interpolation, spline interpolation, numerical solution of differential ov method. ■	10

# M.TECH POWER ELECTRONICS (EPE) 16EEE11 APPLIED MATHAMATICS (Core Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

#### **Course outcomes:**

At the end of the course the student will be able to:

- 1. Employ numerical techniques in order to achieve more accurate values in the computation of roots of algebraic and non-linear equations.
- Utilize analytical and numerical schemes to solve partial differential equations applicable to engineering problems.
- 3. Understand vector spaces, basis, linear transformations and the process of obtaining matrix of linear transformations arising in magnification and rotation of images.
- 4. Apply standard iterative methods to compute Eigen values and solve ordinary differential equations.
- 5. Employ linear and non-linear programming techniques in simulation of network systems and optimization of electrical circuits. ■

#### **Graduate Attributes (As per NBA):**

Critical Thinking, Problem Solving, Research Skill, Usage of Modern Tools.

#### **Question paper pattern:**

- The question paper will have ten full questions carrying equal marks.
- Each full question is for 16 marks.
- There will be two full questions (with a maximum of four sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer five full questions, selecting one full question from each module.

1	Linear Algebra and its Applications	David C.Lay et al	Pearson	5th Edition,2015					
2	Numerical methods in Engineering and Science (with C, C++ & MATLAB)	B.S.Grewal	Khanna Publishers	2014					
3	Graph Theory with Applications to Engineering and Computer Science	Narsingh Deo	PHI	2012					
4	Numerical Methods for Scientific and Engineering Computation	M. K. Jain et al	New Age International	9 <sup>th</sup> Edition, 2014					
5	Higher Engineering Mathematics	B.S. Grewal	Khanna Publishers	43 <sup>rd</sup> Edition,2015					
6	Linear Algebra	K.Hoffman et al	PHI	2011					
I -	1								

- Web links:1. <a href="http://nptel.ac.in/courses.php?disciplineId=111">http://nptel.ac.in/courses.php?disciplineId=111</a>
  - 2. http://www.class-central.com/Course/math(MOOCs)
  - 3.www.wolfram.com

#### M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)

#### SEMESTER - I

POWER SEMICONDUCTOR DEVICES AND COMPONETS (Core Course)			
Course Code	16EPE12	IA Marks	20
Number of Lecture Hours/Week	04	Exam Hours	03
Total Number of Lecture Hours	50	Exam Marks	80

#### Credits - 04

- To enhance the knowledge of fundamentals of semiconductor physics, power electronics and power computation in circuits
- To enhance the knowledge of fundamentals of various semiconductor devices, their operation and characteristics.
- To explain the design and operation of drive circuits and snubber circuits.
- To explain the controlling of temperature rise of the semiconductor devices and designing of magnetic components used for the power electronic circuits

•	ts used for the power electronic circuits. ■			
Module-1		Teachin Hours		
Power Electronics	: Introduction, Converter Classification, Power Electronics Concepts, Electronic	10		
Switches, Switch Selection, Spice, PSpice and Capture, Representation of switches in Pspice -The				
	Switch, Transistors, Diodes and Thyristors (SCRs).			
	ons: Introduction, Power and Energy, Inductors and Capacitors, Energy Recovery,			
	pparent Power and Power Factor, Power Computations for Sinusoidal AC Circuits,			
	ns for Nonsinusoidal Periodic Waveforms, Power Computations Using Pspice.			
	tor Physics: Introduction, Conduction Processes in Semiconductors			
pn Junctions, Charg	ge Control Description of pn-Junction Operation, Avalanche Breakdown.			
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.			
Module-2				
	roduction, Basic Structure and I – V characteristics, Breakdown Voltage	10		
	-State Losses, Switching Characteristics, Schottky Diodes.			
<b>Bipolar Junction</b>	Fransistors: Introduction, Vertical Power Transistor Structures, Z-V			
<b>Bipolar Junction</b> The Characteristics, Physical Characteristics, Phys	<b>Fransistors:</b> Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second			
<b>Bipolar Junction</b> The Characteristics, Phys Breakdown, On-Sta	<b>Transistors:</b> Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.			
<b>Bipolar Junction</b> The Characteristics, Phy Breakdown, On-State Power MOSFETs	<b>Transistors:</b> Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation,			
<b>Bipolar Junction</b> The Characteristics, Phy Breakdown, On-State Power MOSFETs	<b>Transistors:</b> Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.			
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Character Revised Bloom's	<b>Transistors:</b> Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation,			
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Character	Transistors: Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Operating Limitations and Safe Operating Areas. ■			
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Character Revised Bloom's Taxonomy Level Module-3	Transistors: Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.			
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Character Revised Bloom's Taxonomy Level Module-3 Thyristors: Introdu	Transistors: Introduction, Vertical Power Transistor Structures, Z-V visics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.	10		
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Character Revised Bloom's Taxonomy Level Module-3 Thyristors: Introdus Switching Character Switching Ch	Transistors: Introduction, Vertical Power Transistor Structures, Z-V visics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second atte Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.	10		
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Character Revised Bloom's Taxonomy Level Module-3 Thyristors: Introdus Switching Character Gate Turn-Off Th	Transistors: Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.  Liction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Methods of Improving di/dt and dv/dt Ratings.  yristors: Introduction, Basic Structure and Z-V Characteristics,	10		
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Character Revised Bloom's Taxonomy Level Module-3 Thyristors: Introduced Switching Character Gate Turn-Off The Physics of Turn-Off Turn-	Transistors: Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, eristics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.  Ltion, Basic Structure, I-V Characteristics, Physics of Device Operation, eristics, Methods of Improving di/dt and dv/dt Ratings.  yristors: Introduction, Basic Structure and Z-V Characteristics, foperation, GTO Switching Characteristics, Overcurrent Protection of GTOs.	10		
Bipolar Junction T Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Characte Revised Bloom's Taxonomy Level Module-3 Thyristors: Introde Switching Characte Gate Turn-Off Th Physics of Turn-Of Insulated Gate Bip	Transistors: Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, eristics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.  Liction, Basic Structure, I-V Characteristics, Physics of Device Operation, eristics, Methods of Improving di/dt and dv/dt Ratings.  yristors: Introduction, Basic Structure and Z-V Characteristics, foperation, GTO Switching Characteristics, Overcurrent Protection of GTOs.  polar Transistors: Introduction, Basic Structure, I-V Characteristics, Physics of	10		
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Character Revised Bloom's Taxonomy Level Module-3 Thyristors: Introdus Switching Character Gate Turn-Off The Physics of Turn-Off Insulated Gate Bip Device Operation, Market Specific Control of the Character Character Control of the Character C	Transistors: Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, eristics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.  □  □  □  □  □  □  □  □  □  □  □  □  □	10		
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Characteristics Switching Characteristics Taxonomy Level Module-3 Thyristors: Introdustriction Switching Characteristic Gate Turn-Off The Physics of Turn-Off Insulated Gate Bip Device Operation, Emerging Devices	Transistors: Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.  L₁ − Remembering, L₂ − Understanding.  Laction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Methods of Improving di/dt and dv/dt Ratings.  yristors: Introduction, Basic Structure and Z-V Characteristics, operation, GTO Switching Characteristics, Overcurrent Protection of GTOs.  polar Transistors: Introduction, Basic Structure, I-V Characteristics, Physics of Latchup in IGBTs, Switching Characteristics, Device Limits and SOAs.  and Circuits: Introduction, Power Junction Field Effect Transistors, Field-	10		
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Characteristics and Characteristics and Characteristics and Characteristics and Characteristics are supported by the Characteristics and Ch	Transistors: Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.  L₁ − Remembering, L₂ − Understanding.  Liction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Methods of Improving di/dt and dv/dt Ratings.  yristors: Introduction, Basic Structure and Z-V Characteristics, for Operation, GTO Switching Characteristics, Overcurrent Protection of GTOs.  polar Transistors: Introduction, Basic Structure, I-V Characteristics, Physics of Latchup in IGBTs, Switching Characteristics, Device Limits and SOAs.  and Circuits: Introduction, Power Junction Field Effect Transistors, Field-or, JFET-Based Devices versus Other Power Devices, MOS-Controlled Thyristors,	10		
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Characteristics and Characteristics and Characteristics and Characteristics and Characteristics are supported by the Characteristics and Ch	Transistors: Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.  L₁ − Remembering, L₂ − Understanding.  Laction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Methods of Improving di/dt and dv/dt Ratings.  yristors: Introduction, Basic Structure and Z-V Characteristics, operation, GTO Switching Characteristics, Overcurrent Protection of GTOs.  polar Transistors: Introduction, Basic Structure, I-V Characteristics, Physics of Latchup in IGBTs, Switching Characteristics, Device Limits and SOAs.  and Circuits: Introduction, Power Junction Field Effect Transistors, Field-	10		
Bipolar Junction To Characteristics, Phy Breakdown, On-Sta Power MOSFETs Switching Characteristics and Characteristics and Characteristics and Characteristics and Characteristics are supported by the Characteristics and Ch	Transistors: Introduction, Vertical Power Transistor Structures, Z-V ysics of BJT Operation, Switching Characteristics, Breakdown Voltages, Second ate Losses, Safe Operating areas.  : Introduction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Operating Limitations and Safe Operating Areas.  L₁ − Remembering, L₂ − Understanding.  L₁ − Remembering, L₂ − Understanding.  Liction, Basic Structure, I-V Characteristics, Physics of Device Operation, existics, Methods of Improving di/dt and dv/dt Ratings.  yristors: Introduction, Basic Structure and Z-V Characteristics, for Operation, GTO Switching Characteristics, Overcurrent Protection of GTOs.  polar Transistors: Introduction, Basic Structure, I-V Characteristics, Physics of Latchup in IGBTs, Switching Characteristics, Device Limits and SOAs.  and Circuits: Introduction, Power Junction Field Effect Transistors, Field-or, JFET-Based Devices versus Other Power Devices, MOS-Controlled Thyristors,	10		

# M.TECH POWER ELECTRONICS (EPE) 16EPE12 POWER SEMICONDUCTOR DEVICES AND COMPONETS (Core Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

#### **Course outcomes:**

At the end of the course the student will be able to:

- Discuss power electronic concepts, electronic switches and semiconductor physics.
- Explain representation of switches in P-spice and power computations.
- Explain the internal structure, the principle of operation, characteristics and base drive circuits of power semiconductor devices; power diodes, power BJT, power MOSFET.
- Explain the internal structure, the principle of operation, characteristics and base drive circuits of power semiconductor devices; thyristors, power IGBT, power FET.
- Design Snubber circuits for the protection of power semiconductor devices.
- Design gate and base drive circuits for power semiconductor devices
- Design a heat sink to control the temperature rise of semiconductor devices
- Design magnetic components inductors and transformers used in the power electronic circuits. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge Problem, Analysis, Design / development of solutions, Ethics.

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

1	Power Electronics	Daniel W Hart	McGraw Hill	
2	Power Electronics Converters, Applications, and Design	Ned Mohan et al	Wiley	3 <sup>rd</sup> Edition,2014
3	Semiconductor Device Modeling with Spice	G. Massobrio, P. Antognetti	McGraw-Hill	2 <sup>nd</sup> Edition, 2010
4	Power Semiconductor Devices	B. Jayant Baliga	Springer	2008
		<u> </u>		

M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)				
	SEMESTER	- I		
POWER ELECTRONIC CONVERTERS (Core Course)				
Course Code 16EPE13 IA Marks 20				
Number of Lecture Hours/Week 04 Exam Hours 03				
Total Number of Lecture Hours 50 Exam Marks 80				
Credits - 04				

- To impart knowledge of PWM techniques in controlling the converter operation.
- To impart knowledge of designing and analyzing DC DC PWM converters and control modules.
- To impart knowledge of designing and analyzing DC AC and AC DC converters.
- To impart knowledge of analyzing different types of resonant converters and their control.
- To impart knowledge of AC –AC converters and multilevel controllers. ■

Module-1		Teaching
Galvanically Isolate of the Output Volta Discontinuous Mod Discontinuous Mod Pull (Symmetric) C Characteristics, Sel-	averters: Forward Converters - Analysis of the Basic Circuit, ed Forward Converter, Boost Converter - Analysis of the Basic Scheme, Variation ge, Boundary Between the Continuous and the Discontinuous Mode, le Power Losses, Indirect Converter - Boundary Between the Continuous and the le, Discontinuous Mode, Indirect Converter with Galvanic Separation, Push − onverters - Analysis of Idealized Circuit in Continuous Mode, Output ection of Components, DC Premagnetization of the Core, Half-Bridge Converter, Hamilton Circuit, Ćuk Converters - Elimination of the Current Ripple, Ćuk Ivanic Isolation. ■	Hours 10
Revised Bloom's Taxonomy Level	$L_1-Remembering,L_2-Understanding,L_3-Applying,L_4-Analysing.$	
Module-2		
Simple PWM, Volt Modules - Control DC/AC Converter Pulse-Width Modul Asynchronous PWI Application of Space Influence.	Basic Principles and Characteristics of PWM Control Modules - Circuit Analysis, age-Controlled PWM, Current-Controlled PWM- Compensated PWM, IC Control Module TL494, Control Module SG1524/2524/3524, Control Module TDA 1060. <b>s – Inverters:</b> Single-Phase Voltage Inverters - Pulse-Controlled Output Voltage, lated Inverters - Unipolar PWM, Three-Phase Inverters-Overmodulation (m <sub>a</sub> > 1), M, Space Vector Modulation - Space Vector Modulation: Basic Principles, see Vector Modulation Technique, Direct and Inverse Sequencing, Real Drive	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
Module-3		
Commutation of Cu Rectifiers, Phase Co Bridge Rectifiers, T Active Rectifier - A Control Techniques	s – Rectifiers: Half-Wave Single-Phase Rectifiers, Full-Wave Rectifiers - nrrent, Output Filters - Capacitive Filter, L Filter, Voltage Doublers, Three-Phase ontrolled Rectifiers - Full-Wave Thyristor Rectifiers, Three-Phase Thyristor Twelve-Pulse Rectifiers, Rectifiers with Circuit for Power Factor Correction, active Rectifier with Hysteresis Current Controller, PWM Rectifiers - Advanced to of PWM Rectifiers, PWM Rectifier with Current Output, PWM Rectifiers in the Topologies of PWM Rectifiers, Applications of PWM Rectifiers.■	10

M.TECH POWER ELECTRONICS (EPE)
16EPE13 POWER ELECTRONIC CONVERTERS (Core Course) (continued)
CHOICE BASED CREDIT SYSTEM (CBCS)

16EPE13 POWER ELECTRONIC CONVERTERS (Core Course) (continued)	
CHOICE BASED CREDIT SYSTEM (CBCS)	
Module-4	Teaching
Decement Conventours Decement Cinquits Decement Conventours of Class D. Sonies Decement	Hours
Resonant Converters: Resonant Circuits - Resonant Converters of Class D, Series Resonant Converters, Parallel Resonant Converters, Series - Parallel Resonant Converter, Series Resonant Converters Based on GTO Thyristors, Class E Resonant Converters, DC/DC Converters Based on Resonant Switches - ZCS Quasi-resonant Converters, ZVS Quasi-resonant Converters, Multiresonant Converters, ZVS Resonant DC/AC Converters, Soft Switching PWM DC/DC Converters -Phase Shift Bridge Converters, Resonant Transitions PWM Converters, Control Circuits of Resonant Converters - Integrated Circuit Family UCx861-8, Integrated Circuits for Control of Soft, Switching PWM Converters. ■	10
Module-5	
AC/AC Converters: Single-Phase AC/AC Voltage Converters - Time Proportional Control Three-Phase Converters, Frequency Converters, Direct Frequency Converters, Introduction to AC/AC Matrix Converters - Basic Characteristics, Bidirectional Switches, Realization of Input Filter, Current Commutation, Protection of Matrix Converter, Application of Matrix Converter.  Introduction to Multilevel Converters: Basic Characteristics -Multilevel DC/DC Converters, Time Interval: nT < t < nT + DT, n = 0, 1, 2, Time Interval: nT + DT < t < (n + 1)T, Multilevel Inverters - Cascaded H-Bridge Inverters, Diode-Clamped Multilevel Inverters, Flying Capacitor Multilevel Inverter, Other Multilevel Inverter Topologies, Control of Multilevel Inverters - Multilevel SPWM, Space Vector Modulation, Space Vector Control, Selective Harmonic Elimination. ■	10
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#### **Course outcomes:**

At the end of the course the student will be able to:

- Use the knowledge of PWM techniques in controlling different power electronic converters.
- Apply the knowledge of power electronics in design and analysis of DC –DC PWM converters.
- Design and analyze DC -AC and AC DC converters and control their operation using PWM techniques.
- Design and analyze different resonant converters and their control circuits.
- Analyze AC AC converters and multilevel converters. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem analysis.

#### Question paper pattern:

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

1	Power Electronics Converters and Regulators	Branko L. Doki ć Branko Blanu š a	Springer (International Publishing, Switzerland)	3 <sup>rd</sup> Edition, 2015
2	Power Electronics Converters, Applications, and Design	Ned Mohan at el	Wiley	3 <sup>rd</sup> Edition,2014

M.TECH POWER ELECTRONICS (EPE)
CHOICE BASED CREDIT SYSTEM (CBCS)
SEMESTED _ I

MODELLING AND DESIGN OF CONTROLLERS (Core Course)

MODELLE (GIR DE DESIGN OF CONTROLLER (CONTROL			
Course Code	16EPE14	IA Marks	20
Number of Lecture Hours/Week	04	Exam Hours	03
Total Number of Lecture Hours	50	Exam Marks	80
G 71. A4			

#### Credits - 04

- To impart knowledge required for modeling and computer simulation of power electronic converters and systems.
- To explain control system essentials in representing system in digital domain.
- To explain the designing of digital controllers by different methods.
- To explain the design and analysis of optimal and robust controllers by different methods.
- To impart knowledge of discrete computation essentials. ■

Module-1		Teaching
		Hours
Computer Simulation Domain Analysis, V Modelling of Syste Representation, Tra	tion of Power Electronic Converters and Systems: Introduction, Challenges in on, Simulation Process, Mechanics of Simulation, Solution Techniques for Time-Widely Used, Circuit-Oriented Simulators, Equation Solvers.  ems: Input-Output relations, Differential Equations and Linearization, State Space insfer Function Representation, Block Diagrams, Lagrange method, Circuit raphs, Space Vector Modelling.	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying.	
Module-2		
Filter, Mapping bet	sentials: Representation of system in digital Domain, The Z – Transform, Digital ween s – plane and z – plane, Effect of Sampling, Continuous to Discrete Domain Il System Basics, Control Principles, State - Space Method. ■	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
Module-3		
Root Locus Method	<b>Design:</b> Controller Design Techniques, Bode Diagram Method, PID Controller, I, State Space Method, Full State Feedback, Regulator Design by Pole Placement, Tracker: Controller Design. ■	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
Module-4		
Induction motor, Or Optimal and Rob Energy Principle, L	Design (continued): Controlling Voltage, Controlling Current, Control of utput Feedback, Induction motor Control with Output Feedback.  Design: Least Squares Principle, Quadratic Forms, Minimum Least Square Solution, Weighted Least Squares, Recursive Least Squares, Optimal adratic, Induction motor example, Robust Controller Design.  L₁ − Remembering, L₂ − Understanding, L₃ − Applying, L₄ − Analysing.	10
Taxonomy Level		

# M.TECH POWER ELECTRONICS (EPE) 16EPE14 MODELLING AND DESIGN OF CONTROLLERS (Core Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

	CHOICE BASED CREDIT SYSTEM (CBCS)	
Module-5		Teaching
		Hours
Discrete Computa	tion Essentials: Numeric Formats, Tracking the Base Point in the Fixed Point	10
System, Normalizat	ion And Scaling, Arithmetic Algorithms.	
Revised Bloom's	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
Taxonomy Level		
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#### **Course outcomes:**

At the end of the course the student will be able to:

- Describe the role of computer simulations in the analysis and design of power electronics systems.
- Understand the functional modeling of static systems.
- Use sampling technique to determine a digital equivalent to a continuous time system.
- Understand the control basics of digital systems.
- Design digital controllers in discrete time and frequency domain.
- Design optimal and robust controllers by different methods.
- Explain essentials of discrete computation. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Ethics.

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

1	Power Electronics Converters, Applications, and Design	Ned Mohan, Tore M. Undeland, William P. Robbins	Wiley	3 <sup>rd</sup> Edition,2014
2	Power Electronics Essentials and Applications	L.Umanand	Wiley	1 <sup>st</sup> Edition,2014

M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)					
SEMESTER - I					
EMBEDDED SYSTEMS (Elective Course)					
Course Code 16EPE151 IA Marks 20					
Number of Lecture Hours/Week 03 Exam Hours 03					
Total Number of Lecture Hours 40 Exam Marks 80					
	Credits - 0	3			

- To impart knowledge of embedded systems with suitable examples, explanation of process, classification of embedded systems.
- To explain the processor architecture, memory organization, communication with processor and interrupt services.
- To explain the program modeling concepts, inter-process communication and synchronization of processes.

Module-1		Teachin Hours
Embedded Hardwar Embedded Systems Technology, Compl Formulation of Syst	mbedded Systems: Embedded Systems, Processor Embedded into a System, re Units and Devices in a System, Embedded Software in a System, Examples of , Embedded Systems − on −chip (Soc) and Use of VLSI Circuit Design lex Systems Design and Processors, Design of Process in Embedded System, tem Design, Design Process and Design Examples, Classification of Embedded ired for an Embedded System Designer. ■	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-2		
Introduction to Adv Parallelism, Perforr Selection, Memory		08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-3		
Communication De Wireless Devices, Tembedded Systems PCI –X and Advance Device Drivers and	d Interrupts Service Mechanisms: Programmed – I/O Busy – wait Approach ervice Mechanism, ISR Concept, Interrupt Sources, Interrupt Servicing	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Madula 4		1
Module-4		

# M.TECH POWER ELECTRONICS (EPE)

Module-5		Teaching Hours
Functions, Memory in RTOS Environm Design Using an R	ating Systems: OS Services, Process Management, Timer Functions, Event management, Device, File and IO Subsystems Management, Interrupt Routines ent and Handling of Interrupt Source Calls, Real − time Operating Systems, Basic TOS, Rtos Task Scheduling Models, Interrupt Latency and Response of the task trics, OS Security Issues. ■	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain design process in embedded system and formulation of system design.
- Describe processor architecture and memory organization.
- Describe the devices; serial port, parallel port devices, timing devices, devices for synchronous isosynchronous and asynchronous communication.
- Describe device drivers and interrupt mechanisms.
- Explain the programming concepts and source code engineering tools for embedded programming.
- Explain real time programming and program modeling concepts during single and multi-processor system software development process.
- Describe real time operating systems concepts. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem analysis.

#### Question paper pattern:

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

#### Text Book

Programming and Design	Embedded Systems: Architecture, Programming and Design	Raj Kamal	Mc Graw Hill	2 <sup>nd</sup> Edition,2014
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		TECH POWER ELEC	, ,		
	СНО	ICE BASED CREDIT SEMESTER			
	POWER	R SYSTEM HARMON			
Course Code		16EPE152	IA Marks	20	0
Number of Lecture	Hours/Week	03	Exam Hours	0.	3
Total Number of Le	ecture Hours	40	Exam Marks	80	0
		Credits - 0	3		
Course objective					
_		es of harmonics in powe			
_		and mitigation of harmo			
_		ystem components for h	armonic studies.		
<ul> <li>Introducing d</li> </ul>	ifferent methods of	f harmonic studies.			
Module-1					Teachi
Edoo-tolo of l	Townson to a Tutur d				Hours
		uction, Examples of har ment of harmonic distor			08
		ance, capacitor banks ar			
		s voltage rise and resona			
		action, sources of harmo			
fluorescent lights, s	tatic var compensa	tors, cycloconverters. S	ingle phase controlled r	rectifiers, three	
phase converters.	ı				
Revised Bloom's	L <sub>1</sub> – Rememberir	ng, $L_2$ – Understanding.			
Taxonomy Level					
Module-2					
					1
		Power System: Introduc			08
environment, harmo	onic effects on pow	ver system equipment, c	apacitor banks, transfor		08
environment, harmo machines, protection	onic effects on pow on, communication	ver system equipment, c and electronic equipment	apacitor banks, transfor nt.	mers, rotating	08
environment, harmomachines, protection Mitigation of Pow	onic effects on pow on, communication a er system Harmon	ver system equipment, c and electronic equipmentics: Introduction, harm	apacitor banks, transfor nt. onic filters, power conv	rmers, rotating verters,	08
environment, harmonachines, protection Mitigation of Powtransformers, rotati	onic effects on pow on, communication a er system Harmon ng machines, capac	ver system equipment, c and electronic equipment nics: Introduction, harm citor banks, harmonic fil	apacitor banks, transfor nt. onic filters, power conv lter design, active filters	mers, rotating verters,	08
environment, harmomachines, protection Mitigation of Powtransformers, rotati Revised Bloom's	onic effects on pow on, communication a er system Harmon ng machines, capac	ver system equipment, c and electronic equipmentics: Introduction, harm	apacitor banks, transfor nt. onic filters, power conv lter design, active filters	mers, rotating verters,	08
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environment, harmonachines, protection Mitigation of Pow transformers, rotation Revised Bloom's Taxonomy Level Module-3 Limits of Harmonachines, harmonachines, protection Mitigation of Power P	onic effects on power, communication a er system Harmon and machines, capace $L_1$ – Remembering	ver system equipment, c and electronic equipment nics: Introduction, harm citor banks, harmonic fil	apacitor banks, transfornt. onic filters, power conv lter design, active filters L <sub>3</sub> – Applying, L <sub>4</sub> – An	mers, rotating verters, s. ■ nalysing.	08
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environment, harmomachines, protection Mitigation of Pow transformers, rotating Revised Bloom's Taxonomy Level Module-3  Limits of Harmon distortion limits. Harmonic studies of harmonics, sking shunt capacitor ban Transformer Mod admittance matrice transmission matric transformers.  Revised Bloom's Taxonomy Level Module-4  Modelling of Transeries impedance, recapacitance, surge capacitance – single conversion between	conic effects on powers, communication of the system Harmon of machines, capacity and the system Harmon of the system Harmon of the system Harmon of the system of the sys	ver system equipment, c and electronic equipment nics: Introduction, harm citor banks, harmonic fil- ing, L <sub>2</sub> – Understanding, oduction, voltage harmonic system Components: Interpretation of the high voltage grid, in the banks, load models, into modelling of two winderstance matrix, modelling of the high voltage grid, into the high voltage and current across tance matrix, modelling mg, L <sub>2</sub> – Understanding, bles: Introduction, skin tween conductors, mutual city of propagation, lines, the transmission (ABC and admittance matrices	apacitor banks, transformt.  nonic filters, power convoluter design, active filters  L <sub>3</sub> – Applying, L <sub>4</sub> – And the convolution of the convolutio	rrent harmonic n the presence odelling of g. se sequence mers, ding nalysing.  wer lines, Line's s shunt nce matrix, – single phase	08
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# M.TECH POWER ELECTRONICS (EPE) 16EPE152 POWER SYSTEM HARMONICS (Elective Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

	CHOICE BASED CREDIT SYSTEM (CBCS)	Γ
Module-5		Teaching Hours
harmonic analysis u	<b>Emonic Studies:</b> Introduction, harmonic analysis using a computer program, using spread sheet, harmonic distortion limits, harmonic filter rating, and practical monic study of simple system, 300 -22 kV power system and low voltage system.	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain the fundamentals that facilitate the understanding of the issues of harmonics.
- Explain the causes for generation of harmonics.
- Explain the effects of harmonics distortion on power system equipment and loads and suppression of harmonics in power systems.
- Discuss standard limits of harmonic distortion and modeling of power system components for harmonic analysis study.
- Model transmission lines and cables for harmonic analysis.
- Discuss implementation of harmonic studies. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Modern Tool Usage, Ethics.

#### Question paper pattern:

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module. ■

1	Power System Harmonics	George J Wakileh	Springer	Reprint, 2014
2	Power System Harmonic Analysis	Jos Arrillaga et al	Wiley	Reprint, 2014
3	Power System Harmonic	J. Arrillaga, N.R. Watson	Wiley	2 <sup>nd</sup> Edition, 2003
4	Harmonics and Power Systems	Francisco C. DE LA Rosa	CRC Press	1st Edition, 2006

80

	ECH POWER ELECTRO CE BASED CREDIT SY SEMESTER - I	STEM (CBCS)	
ADVANCI	ED CONTROL SYSTEM		
Course Code	16EPE153	IA Marks	20
Number of Lecture Hours/Week	03	Exam Hours	03

Credits - 03

Exam Marks

#### **Course objectives:**

Total Number of Lecture Hours

• To impart basic knowledge about digital control through signal conversion, their representation, z – transform, stability analysis in the z – plane, signal reconstruction .etc.

40

- Development of models of systems in the digital domain, and their implementation.
- To perform state variable method of analysis of digital control systems.
- To impart knowledge of optimal control system analysis in continuous and discrete time domains.
- To impart knowledge about the analysis of nonlinear control systems.

• 10 impart kno	owledge about the analysis of nonlinear control systems.	
Module-1		Teaching Hours
Digital Control Sch Domain Models for Frequency Respons Systems, Sampled S	Control System Terminology, Need of Digital control, Configurations of the Basic eme, Principle of Signal Conversion, Basic Discrete − Time Signals, Time Discrete − Time Systems, The z − Transform, Transfer Function Models, we, Stability on the z − Plane and Jury Stability Criterion, Sample and Hold Spectra and Aliasing, Reconstruction of Analog Signals, Practical Aspects of the Rate, Principle of Discretization. ■	08
Revised Bloom's Taxonomy Level	$L_1-Remembering, L_2-Understanding, L_3-Applying, L_4-Analysing. \\$	
Module-2		
Continuous – time l		08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
Module-3		
Processors, State D with Dead Time, So Multivariable Syste Pole Placement De Feedback, Necessar Design, Design of S Introduction of the Digital Control Sys Observers. ■	esign and State Observers: Introduction, Stability Improvement by State ry and sufficient Conditions for Arbitrary Pole – Placement, State Regulator State Observers, Compensator Design by the Separation Principle, Servo Design – reference Input by Feedforward Control, State Feedback with Integral Control, tems with State Feedback, Deadbeat control by State Feedback and Deadbeat	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
<b>Module-4</b>		
Functions for Linea Performance Index,	ll Control: Introduction, The Concept of Lyapunov Stability, Lyapunov ar Systems, Parameter Optimization and Optimal Control Problems, Quadratic Control Configurations, Optimal State Regulator, Optimal Digital Control ed State Feedback Control. ■	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	

# M.TECH POWER ELECTRONICS (EPE) 16EPE153 ADVANCED CONTROL SYSTEMS (Elective Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

Module-5		Teaching Hours
nonlinearities in Co Common nonlinear Plane Analysis, Co Variable Structure	Analysis: Introduction, Common nonlinear System Behaviours, Common ontrol Systems, Describing Function Fundamentals, Describing Function of ities, Stability Analysis by the Describing Function Method, Concept of Phase onstruction of Phase Portraits, System Analysis on the Phase Plane, Simple Systems, Lyapunov Stability Definitions, Lyapunov Stability Theorems, as for Nonlinear Systems.	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	

#### **Course outcomes:**

At the end of the course the student will be able to:

- Evaluate Z transform of a continuous time signal.
- Assess the stability of a system in Z domain.
- Explain the process of reconstructing the analog signal from a digital signal.
- Model the digital systems to analyze them in the digital domain.
- Use state variable representation to design control law and observers for a system in both continuous and discrete time domains.
- Solve optimal control problems.
- Construct Lyapunov functions to evaluate the stability of a system.
- Use describing function, phase plane methods and Lyapunov method to assess the stability of the nonlinear system.

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Modern Tool Usage, Ethics.

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

1	Digital Control and State Variable Methods (Conventional and Intelligent Control Systems)	M Gopal	Mc Graw Hill	3 <sup>rd</sup> Edition, 2008
2	Discrete – Time Control Systems	Katsuhiko Ogata	Pearson	2 <sup>nd</sup> Edition, 2015
3	Digital Control Systems	Benjamin C Kuo	Oxford University Press	2 <sup>nd</sup> Edition, 2007
4	Control System Engineering	I.J. Nagrath M.Gopal	New Age International	5 <sup>th</sup> Edition, 2007

	ECH POWER ELECT CE BASED CREDIT S SEMESTER	SYSTEM (CBCS)	
EMC IN I	POWER ELECTRON		
Course Code	16EPE154	IA Marks	20
Number of Lecture Hours/Week	03	Exam Hours	03
Total Number of Lecture Hours	40	Exam Marks	80
	Credits - 03		

- To explain different electromagnetic disturbances and their classification.
- To explain measurement of the high frequency characteristics of EMI filter elements, their selection and measurement.
- To explain suppression of noise in relay systems.
- To explain designing and analysis of EMI filters.
- To explain conduction of test as per IEC specifications and reducing internal EMI.

		Teaching Hours
by character and tree Conducted EMI Meconducted EMI refugeasurements for a EMI in Power Electrical Emission Emission Electrical Emission Electrical Emission Emission Electrical Emission English Emission English Emission English Emission	Disturbances: Introduction, Classification of disturbances by frequency content, ansmission mode.  Measurement: Introduction, EMI measuring instruments, Basic terms and erences, Measuring the interference voltage and current, Spectrum analysers, EMI consumer applications, Measuring impulse like EMI.  Deteronic Equipment: EMI from power semiconductors, controlled rectifier lation for semiconductor equipment.	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
Module-2		
	nts: Measuring High Frequency Characteristics OF EMI Filter Elements, Coils, Resistors. ■	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
Module-3		
Application of RC EMI Generation ar EMI Filter Circuit Circuits, Insertion	a: Noise Suppression in Relay Systems, Application of AC Switching Relays,  — Snubbers to Power Semiconductors, Shielded Transformers, Capacitor Filters, and Reduction at its Source, Influence of Layout and Control of Parasitics.  **t selection and measurement**: Definition of EMI Filter Parameters, ENI Filter  **Loss Test Methods. ■	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
Module-4		
	: EMI Filter Design for Insertion Loss, Calculation of Worst – case Insertion	
Loss, Design Meth Common – Mode ( of Noise Filter Circ	od for Mismatched Impedance Condition, Design Method for EMI Filters with Choke Coils, Damped EMI Filters and Lossy Filter Elements, HF Characteristics cuit Elements, EMI Filter Layout.	08
Loss, Design Meth Common – Mode O of Noise Filter Circ Revised Bloom's Taxonomy Level	od for Mismatched Impedance Condition, Design Method for EMI Filters with Choke Coils, Damped EMI Filters and Lossy Filter Elements, HF Characteristics	08
Loss, Design Meth Common – Mode O of Noise Filter Circ Revised Bloom's	od for Mismatched Impedance Condition, Design Method for EMI Filters with Choke Coils, Damped EMI Filters and Lossy Filter Elements, HF Characteristics cuit Elements, EMI Filter Layout.	08
Loss, Design Meth Common – Mode Coord Noise Filter Circle Revised Bloom's Taxonomy Level Module-5 Testing for Suscer Tests per IEC Spec Reduction Techni	od for Mismatched Impedance Condition, Design Method for EMI Filters with Choke Coils, Damped EMI Filters and Lossy Filter Elements, HF Characteristics cuit Elements, EMI Filter Layout. ■  L <sub>1</sub> − Remembering, L <sub>2</sub> − Understanding, L <sub>3</sub> − Applying, L <sub>4</sub> − Analysing.  otibility to Power Line Disturbances: Surge Voltages in AC Power Mains, EMC Effications, Other EMS Test Methods.  ques for internal EMI: Conductive Noise Coupling, Electromagnetic Coupling, oupling Reduction Methods, Wiring Layout Methods to Reduce EMI Coupling,	08

# M.TECH POWER ELECTRONICS (EPE) 16EPE154 EMC IN POWER ELECTRONICS (Elective Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

#### **Course outcomes:**

At the end of the course the student will be able to:

- Describe Electromagnetic interference and its classification and measurement of conducted high frequency disturbance.
- Survey electromagnetic interference specific to power electronic equipment.
- Explain the characteristics of circuit elements used for noise suppression.
- Explain EMI suppression methods used in semiconductor and electromechanical devices.
- Explain design of EMI filter circuits and filtering methods.
- Explain susceptibility and noise withstand capability test.
- Explain EMS reduction techniques for power electronic equipment.

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Modern Tool Usage, Ethics.

#### Question paper pattern:

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

#### Text Book

1 Electromagnetic Compatibility in Power Electronics Laszlo Tihanyi Newnes 1st Edition, 1995
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	I POWER ELEC' BASED CREDIT SEMESTER	SYSTEM (CBCS)	
POWER	<b>ELECTRONIS L</b>	ABORATORY-1	
Course Code	16EPEL16	IA Marks	20
Number of Practical Hours/Week	03	Exam Hours	03
Total Number of Practical Hours	40	Exam Marks	80

Credits - 02

#### **Course objectives:**

- To conduct experiment on various power electronic devices to analyze their static and dynamic characteristics.
- To conduct experiments and enhance understanding of different power electronic converters.

Sl. NO	Experiments
1	Analysis of static and dynamic characteristic of MOSFET and IGBT.
2	Performance of single phase fully controlled and semi-controlled converter for RL load for continuous current mode.
3	Performance of single phase fully controlled and semi-controlled converter for RL load for discontinuous current mode.
4	Study of effect of source inductance on the performance of single phase fully controlled converter.
5	Performance analysis of three phase fully controlled and semi-controlled converter for RL load for continuous current mode.
6	Performance analysis of three phase fully controlled and semi-controlled converter for RL load for discontinuous current mode.
7	Performance analysis of single phase bridge inverter for RL load and voltage control by single pulse width modulation.
8	Performance analysis of two quadrant chopper.
9	Diode clamped multilevel inverter.
10	ZVS operation of a Synchronous buck converter.
	ed Bloom's $L_3$ – Applying, $L_4$ – Analysing, $L_5$ – Evaluating, $L_6$ – Creating homy Level

#### **Course outcomes:**

At the end of the course the student will be able to:

- Analyze the static and dynamic characteristics of various semiconductor devices.
- Apply the knowledge of converters in assessing the performance of single phase and three phase fully controlled and semi controlled converters for RL load for continuous current modes.
- Apply the knowledge of converters in assessing the performance of single phase and three phase fully controlled and semi controlled converters for RL load for discontinuous current modes.
- Assess the performance of single phase bridge inverter for RL load and control the voltage by pulse width modulation.
- Apply the knowledge of power electronics in performance analysis of chopper and synchronous buck converter.

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Conduct investigations of complex Problems, Modern Tool Usage, Individual and Team work, Communication.

100

#### M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS) **SEMESTER - I SEMINAR** Course Code 16EPE17 IA Marks No. of Lecture Hours/Week

Credits - 01

Exam Hours

Exam Marks

Number of Tutorial Hours/week

The objective of the seminar is to inculcate self-learning, face audience confidently, enhance communication skill, involve in group discussion and present and exchange ideas.

03

Each student, under the guidance of a Faculty, is required to

- Choose, preferably, a recent topic of his/her interest relevant to the Course of Specialization.
- Carryout literature survey, organize the Course topics in a systematic order.
- Prepare the report with own sentences.
- Type the matter to acquaint with the use of Micro-soft equation and drawing tools or any such facilities.
- Present the seminar topic orally and/or through power point slides.
- Answer the queries and involve in debate/discussion.
- Submit two copies of the typed report with a list of references.

The participants shall take part in discussion to foster friendly and stimulating environment in which the students are motivated to reach high standards and become self-confident.

The Internal Assessment marks for the seminar shall be awarded (based on the relevance of the topic, presentation skill, participation in the question and answer session and quality of report) by the committee constituted for the purpose by the Head of the Department. The committee shall consist of three faculties from the department with the senior most acting as the Chairman.

#### Marks distribution for internal assessment of the course 16EPE17 seminar:

Seminar Report: 30 marks Presentation skill:50 marks Ouestion and Answer:20 marks

Number of contact Hours/week

Total No. of contact Hours

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Conduct investigations of complex Problems, Modern Tool Usage, Engineers and society, Environment and sustainability, Ethics, Individual and Team work, Communication.

SCHEME OF TEACHING AND EXAMINATION - 2016-17

#### M.Tech POWER EECRTONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)

(Total number of credits prescribed for the programme - 85)

#### II SEMESTER

			Teaching	Hours /Week		Exami	nation		
Sl. No	Course Code	Title	Theory	Practical/ Field work/ Assignment	Duration in hours	I.A. Marks	Theory/ Practical Marks	Total Marks	Credits
1	16EPE21	Electric Drives	04		03	20	80	100	4
2	16EPE22	Switched - Mode Power Supplies	04		03	20	80	100	4
3	16EPE23	Modelling and Analysis of Electrical Machines	04		03	20	80	100	4
4	16EPE24	FACTS Controllers	04		03	20	80	100	4
5	16EPE25X	Elective - 2	03		03	20	80	100	3
6	16EPEL26	Power Electronics Laboratory - 2	-	3	03	20	80	100	2
7	16EPE27	Seminar	-	3	-	100	-	100	1
	ТО	TAL	19	06	18	220	480	700	22

Number of credits completed at the end of II semester: 22+22=44

#### **Elective - 2**

Course Code under 16EPE25X	Title
16EPE251	Converters for Solar and Wind Power Systems
16EPE252	Uninterruptible Power Supply
16EPE253	Power Quality Problems and Mitigation
16EPE254	Hybrid Electric Vehicles

**Note: Project Phase-1:** 6-week duration shall be carried out between 2<sup>nd</sup> and 3<sup>rd</sup> Semester vacation. Candidates in consultation with the guide shall carry out literature survey/ visit industries to finalize the topic of Project.

	ECH POWER ELECT CE BASED CREDIT	` ,	
	SEMESTER	- II	
E	LECTRIC DRIVES (	Core Course)	
Course Code	16EPE21	IA Marks	20
Number of Lecture Hours/Week	04	Exam Hours	03
Total Number of Lecture Hours	50	Exam Marks	80
	Credits - 04	4	

- To give an introduction to drive, their characteristics and breaking.
- To explain the basic elements of drives, classification of drives, their dynamics and speed control
- To explain selection of drive for a specific application.
- To explain control of an electric drive using microprocessor.

Module-1		Teaching Hours
	ectric motors: Introduction, Characteristics of DC motors, Three phase Induction onous Motors, Braking of Electric Motors. ■	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-2		
Electric Drive, Dyr	ric Drives: Introduction, Classification of Electric Drives, Basic Elements of an namic Conditions of Drive System, Stability Considerations of Electric Drive. c Motors: Induction Motor Drives.	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-3		
Magnet Synchrono	c Motors (continued): Synchronous Motor Drives, DC Drives. Permanent us Motor, Classification of Permanent Magnet Synchronous Motor, d Synchronous Motor. ■	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-4		
Permanent Magnet <b>Applications:</b> Driv	c Motors (continued): Permanent Magnet Synchronous Motor, Classification of Synchronous Motor, Cycloconverters fed Synchronous Motor. The Considerations foe Textile Mills, Steel Rolling Mills, Cranes and Hoist Drives, ar Mills, Machine Tools, Paper Mills, Coal Mines, Centrifugal Pumps, Turbo -	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-5		
versus Microproce Technology, Cont	and Control of Electrical Drives: Introduction, Dedicated Hardware Systems essor Control, Applications Area and Functions of Microprocessors in Drive erol of Electric Drives using Microprocessors, Control System Design of essed Variable Speed Drives, Stepper motors. ■	10
Whereprocessors of		

# M.TECH POWER ELECTRONICS (EPE) 16EPE21 ELECTRIC DRIVES (Core Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain characteristics of DC motors, induction motors and synchronous motors.
- Explain braking of electric motors.
- Classify electric drives.
- Discuss dynamics conditions and stability considerations of Electric drive.
- Control the speed of electric motors.
- Suggest a drive for a specific application.
- Explain using microprocessor in the control of an electric drive.

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

# Text Book 1 Electric Drives Concepts and Applications Vedam Subrahmanyam Mc Graw Hill 2<sup>nd</sup> Edition, 2016

	ECH POWER ELECT CE BASED CREDIT ( SEMESTER )	SYSTEM (CBCS)	
SWITCHED		UPPLIES (Core Course)	
Course Code	16EPE22	IA Marks	20
Number of Lecture Hours/Week	04	Exam Hours	03
Total Number of Lecture Hours	50	Exam Marks	80
	Credits - 04	1	

- To give an overview on SMPS, its characteristics, new technologies, basic principles and control modes.
- To introduce the topology of DC/DC converter used and the method of selecting key peripheral components of SMPS.
- To explain the power factor correction circuit design of SMPS, the design of high-frequency transformer, the examples of SMPS optimization design, and the key design points of SMPS.
- To introduce the SMPS testing technology and the protection circuit design of SMPS. ■

Module-1		Teachin Hours
Supply, Characterist Control Mode Type Characteristics of S <b>Topologies of the I</b> Converter, Basic Pr (Single-ended prim Converter, Half/Ful	ower Supply (SMPS): Overview, Classification of Integrated Regulated Power stics of SMPS, New Development Trend of SMPS, Basic Principles of SMPS, of SMPS, Working Mode of SMPS, Feedback Type of SMPS, Load MPS.  OC/DC Converter: Topologies of the DC/DC Converter, Basic Principle of Buck inciple of - Boost Converter, Buck-Boost Converter, Charge Pump Converter, ary inductor converter)SEPIC, Flyback Converter, Forward Converter, Push-Pull I Bridge Converter, Soft Switching Converter, Half-Bridge LLC Resonant Forward Converter. ■	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-2		
	ing Key Peripheral Components of SMPS: Selection Method for - Fixed s, Inductor Characteristics and Selection Method for Magnetic Beads, Selection	10
Method for EMI Fi	Iter - Input Bridge Rectifier, Output Rectifier, Transient Voltage Suppressor ching Tube, Optical Coupler, Adjustable Precision Shunt Regulator, SMPS	
Method for EMI Fi (TVS), Power Swit	Iter - Input Bridge Rectifier, Output Rectifier, Transient Voltage Suppressor ching Tube, Optical Coupler, Adjustable Precision Shunt Regulator, SMPS	
Method for EMI Fi (TVS), Power Swit Protection Element Revised Bloom's	tter - Input Bridge Rectifier, Output Rectifier, Transient Voltage Suppressor ching Tube, Optical Coupler, Adjustable Precision Shunt Regulator, SMPS s. ■	
Method for EMI Fi (TVS), Power Swit Protection Element  Revised Bloom's Taxonomy Level  Module-3  Power Factor Cor (PFC), Basic Principle of Active of High-Power PFC Scheme.  Design of High-Fr Formula or Output Formula Derivation Design of Flyback	tter - Input Bridge Rectifier, Output Rectifier, Transient Voltage Suppressor ching Tube, Optical Coupler, Adjustable Precision Shunt Regulator, SMPS s. ■	10

M.TECH POWER ELECTRONICS (EPE)  16EPE22 SWITCHED - MODE POWER SUPPLIES (Core Course) (continued)	
CHOICE BASED CREDIT SYSTEM (CBCS)  Module-4	Teaching Hours
Key Design Points of SMPS: SMPS Design Requirements, Design of High-Efficiency SMPS, Methods of Reducing No-Load and Standby Power Consumption of SMPS, Stability Design of Optocoupler Feedback Control Loop SMPS Layout and Wiring, Design of Constant Voltage/Current SMPS, Design of Precision Constant Voltage/Current SMPS, Design of Remote Turn-Off Circuit for SMPS, Typical Application and Printed Circuit Design of New Single-Chip SMPS, Electromagnetic Interference Waveform Analysis and Safety Code Design of SMPS, Radiator Design of Single-Chip SMPS, Radiator Design of Power Switching Tube (MOSFET), Common Troubleshooting Methods of SMPS. ■	10
Module-5	I
SMPS Testing Technology: Parameter Testing of SMPS, Performance Testing of SMPS, SMPS Measurement Skills, Accurate Measurement Method of Duty Ratio, Method to Detect the Magnetic Saturation of High-Frequency Transformer with Oscilloscope, Digital Online Current/Resistance Meter, Electromagnetic Compatibility Measurement of SMPS, Waveform Test and Analysis of SMPS.  Protection and Monitoring Circuit Design of SMPS: Design of Drain Clamp Protection Circuit, Overvoltage Protection Circuit Constituted by Discrete Components, Application of Integrated Overvoltage Protector, Design of Undervoltage Protection Circuit, Design of Overcurrent and Overpower Protection Circuit, Design of Soft-Start Circuit, Mains Voltage Monitor, Transient Interference and Audio Noise Suppression Technology of SMPS, Design of Overheating Protection Component and Cooling Control System. ■	10

#### **Course outcomes:**

**Revised Bloom's** 

**Taxonomy Level** 

At the end of the course the student will be able to:

• Explain a SMPS, its characteristics, new technologies, basic principles and control modes.

 $L_1$  – Remembering,  $L_2$  – Understanding,  $L_3$  – Applying,  $L_4$  – Analysing.

- Suggest a suitable DC/DC converter for an SMPS.
- Explain the method of selecting key peripheral components of SMPS.
- Design the power factor correction circuit of SMPS.
- Explain selection of magnetic core and designing of high-frequency transformer.
- Explain designing of different SMPS.
- Explain testing technology of SMPS.
- Design protection and monitoring circuit for SMPS. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Ethics, Communication.

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module. ■

#### **Text Book**

1	Optimal Design of Switching Power Supply	Zhanyou Sha et al	Wiley	2015

#### M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)

#### **SEMESTER - II**

MODELLING AND AN	ALYSIS OF ELECTRIC	CAL MACHINES (Co	re Course)
Subject Code	16EPE23	IA Marks	20
Number of Lecture Hours/Week	04	Exam Hours	03
Total Number of Lecture Hours	50	Exam Marks	80

#### Credits - 04

- To provide basic concepts of modelling of dc and ac machines.
- To provide knowledge of theory of transformation of three phase variable to two phase variable.
- To analyze the steady state and dynamic state operation of three-phase induction machines using transformation theory based mathematical modelling.
- To provide modeling concepts of single phase and three phase transformers.
- To analyze the steady state and dynamic state operation of three-phase synchronous machines using transformation theory based mathematical modelling. ■

Module-1		Teaching Hours
phase synchronous primitive machine- DC Machine Moo transient state analy	Modelling: Basic two pole machine representation of commutator machines, 3-machine with and without damper bar and 3-phase induction machine, Kron's voltage, current and torque equations.  delling: Mathematical model of separately excited DC motor-steady state and ysis, sudden application of inertia load, transfer function of separately excited DC all model of dc series motor, shunt motor, linearization techniques for small	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
Module-2		
obtain constant mat  Dynamic Modellin  electromagnetic tor model, rotor referen	Theory: Real time model of a two phase induction machine, transformation to rices, three phase to two phase transformation, power equivalence.  ng of Three Phase Induction Machine: Generalized model in arbitrary frame, que, deviation of commonly used induction motor models-stator reference frames are frames model, synchronously rotating reference frames model, equations in flux model, dynamic simulation. ■	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	
Module-3		
machine, space pha motor. <b>Transformer Moc</b> connections, per ph change of base, per	tions of the Induction Machine: Derivation of small signal equations of induction as model, DQ flux linkages model derivation, control principle of the induction delling: Introduction, single phase transformer model, three phase transformer as analysis, normal systems, per unit normalization, per unit three phase quantities, unit analysis of normal system, regulating transformers for voltage and phase angle primers, transmission line and transformers. ■	10
Revised Bloom's Taxonomy Level	$L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing, $L_5$ – Evaluating.	
Module-4		
machine variables, equations, torque e	chronous Machines: Introduction, voltage equations and torque equation in stator voltage equations in arbitrary and rotor reference frame variables, Park's equations in substitute variables, rotor angle and angle between rotors, per unit steady state operation.	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	

# M.TECH POWER ELECTRONICS (EPE) 16EPE23 MODELLING AND ANALYSIS OF ELECTRICAL MACHINES (Core Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

	CHOICE BRISED CREDIT STSTEM (CDCS)	
Module-5		Teaching Hours
input torque and dur rotor angle characte characteristics durin comparison of actua	of Synchronous Machines: Dynamic performance during sudden change in ring a 3-phase fault at the machine terminals, approximate transient torque versus ristics, comparison of actual and approximate transient torque-angle as a sudden change in input torque; first swing transient stability limit, al and approximate transient torque-angle characteristics during a 3-phase fault at alls, critical clearing time, equal area criterion, computer simulation.	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.	

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain the basic concepts of modeling.
- Develop mathematical models for DC motors for transient state analysis.
- Use reference frame theory to transform three phase to two phase.
- Develop dynamic model for three phase induction motor in stator ad rotor reference frames.
- Develop mathematical model of single phase transformers.
- Model synchronous machine using Park's transformation for the analysis of steady state operation.
- Model synchronous machine to perform dynamic analysis under different conditions.

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Conduct investigations of complex Problems, Modern Tool Usage, Ethics,

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module. ■

1	Generalized Theory of Electrical Machines	P.S.Bimbra	Khanna Publications	5th Edition,1995
2	Electric Motor Drives - Modelling, Analysis & Control	R. Krishnan	PHI Learning Private Ltd	Indian Edition, 2009
3	Analysis of Electrical Machinery and Drive Systems	P.C.Krause, et al	Wiley	2nd Edition,2010
4	Power System Analysis	Arthur R Bergen and Vijay Vittal	Pearson	2 <sup>nd</sup> Edition,2009
5	Power System Stability and Control	Prabha Kundur	Mc Graw Hill	1st Edition,1994
6	Dynamic Simulation of Electric Machinery using Matlab / Simulink	Chee-Mun Ong	Prentice Hall	1998

	CH POWER ELECT E BASED CREDIT SEMESTER	SYSTEM (CBCS)	
FACT	TS CONTROLLERS	S (Core Course)	
Course Code	16EPE24	IA Marks	20
Number of Lecture Hours/Week	04	Exam Hours	03
Total Number of Lecture Hours	50	Exam Marks	80
	Credits - 0	4	

- To discuss the growth of complex electrical power networks and to introduce the lack of controllability of the active- and reactive-power flows in energized networks.
- To describe the conventional controlled systems and introduce the basic operating principles of new FACTS devices
- To describe the various components of a general SVC, its control system, an overview of the voltage-control characteristics of SVC and the principles of design of the SVC voltage regulator.
- To explain the concepts of SVC control in such applications as stability enhancement, damping subsynchronous oscillations, improvement of HVDC link performance and the basic issues relating to the design of SVC controllers in different applications.
- To explain the concepts of series compensation, TCSC controller and its operation, characteristics, modeling and applications.
- To introduce voltage source converter based facts devices.

Module-1		Teaching Hours
Conventional Contr Transmission Netw Reactive-Power Co Uncompensated Tra Principles of Conv	ontrol in Electrical Power Transmission Systems: Reactive Power, ansmission Lines, Passive Compensation. entional Reactive-Power Compensators: Introduction, Synchronous atturated Reactor (SR), The Thyristor-Controlled Reactor (TCR), The Thyristor-	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-2		
Thyristor-Controlle Controlled Reactor Capacitor-Thyristor SVC Voltage Cont	wentional Reactive-Power Compensators (continued): The Fixed Capacitor—d Reactor (FC–TCR), The Mechanically Switched Capacitor—Thyristor—(MSC–TCR), The Thyristor-Switched Capacitor (TSC), The Thyristor-Switched r-Controlled Reactor (TSC–TCR), A Comparison of Different SVCs.	10
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-3		
2nd Harmonic Inter	rol (continued): Effect of Network Resonances on the Controller Response, The action between the SVC and ac Network, Application of the SVC to Seriesstems, 3rd Harmonic Distortion, Voltage-Controller Design Studies. ■  L₁ − Remembering, L₂ − Understanding.	10
Taxonomy Level		
Module-4		
Transient Stability,	Introduction, Increase in Steady-State Power-Transfer Capacity, Enhancement of Augmentation of Power-System Damping - Principle of the SVC, Auxiliary ntributions of SVC Controllers, Effect of the Power System, Effect of the SVC, Subsynchronous Resonance (SSR) - Principle of SVC Control, Configuration and	10

### M.TECH POWER ELECTRONICS (EPE) 16EPE24 FACTS CONTROLLERS (Core Course) (continued)

	16EPE24 FACTS CONTROLLERS (Core Course) (continued)	
	CHOICE BASED CREDIT SYSTEM (CBCS)	
Module-4 (contin	nued)	Teaching
		Hours
The Thyristor-Co	ntrolled Series Capacitor (TCSC): Series Compensation, The TCSC Controller,	
Operation of the TO	CSC, The TSSC, Analysis of the TCSC, Capability Characteristics, Harmonic	
Performance, Losse	es, Response of the TCSC, Modelling of the TCSC.	
·		
Revised Bloom's	$L_1$ – Remembering, $L_2$ – Understanding.	
Taxonomy Level		
Module-5		
TCSC Application	s: Introduction, Open-Loop Control, Closed-Loop Control, Improvement of the	10
System-Stability Li	mit, Enhancement of System Damping, Subsynchronous Resonance (SSR)	
Mitigation, Voltage	-Collapse Prevention.	
VSC based FACTS	S Controllers: Introduction, The STATCOM, The SSSC, The UPFC,	
Comparative Evalu	ation of Different FACTS Controllers. ■	
Revised Bloom's		-
	$L_1$ – Remembering, $L_2$ – Understanding.	
Taxonomy Level		

#### **Course outcomes:**

At the end of the course the student will be able to:

- Discuss the growth of complex electrical power networks, the lack of controllability of the active- and reactive-power flows in energized networks.
- Describe the conventional controlled systems and the basic operating principles of FACTS.
- Describe the various components of a general SVC, its control system, control characteristics and the design of the SVC voltage regulator.
- Explain the use of SVC in stability enhancement, damping subsynchronous oscillations, improvement of HVDC link performance.
- Explain the concepts of series compensation, TCSC controller and its operation, characteristics, modeling and applications.
- Explain the operation of voltage source converter based FACTS. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Lifelong Learning.

#### Question paper pattern:

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

1	Thyristor-Based FACTs Controllers for Electrical	R. Mohan Mathur	Wiley	2002
	Transmission Systems	Rajiv K. Varma		
2	Understanding FACTS : concepts and technology of flexible AC Transmission systems	Narain G. Hingorani Laszlo Gyugyi.	Wiley	2000
3	Facts Controllers in Power Transmission and Distribution	K. R. Padiyar	New Age International	2007

### M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)

**SEMESTER - II** 

CONVERTERS FOR SO	OLAR AND WIND POW	ER SYSTEMS (Elect	ive Course)
Course Code	16EPE251	IA Marks	20
Number of Lecture Hours/Week	03	Exam Hours	03
Total Number of Lecture Hours	40	Exam Marks	80
	Credits - 03		

- To give an overview of the latest developments in the PV and WT penetrations in the worldwide power systems.
- To discusses the various high-efficiency topologies for PV inverters as well as some generic control structures.
- To describe the grid requirements for PV installations, to give a deep analysis of the basic PLL and to discuss different quadrature signal generator methods,
- To discuss islanding detection methods and to describe the most typical WT grid converter topologies together with generic control structures, the most recent grid requirements for WT grid connection and the grid codes.
- To extrapolate the knowledge of single-phase PLL structure for three-phase systems, new robust synchronization structures to cope with the unbalance grid or frequency adaptation.
- To explain the most used grid converter control structures for WT and to extrapolate the control issue for the case of grid faults.
- To explain designing of grid interface filters, methods actively used to damp the resonance for LCL filters and methods for controlling the grid current. ■

filters and		
Module-1		Teachi
T . T YYY		Hours
	d Power Development, Photovoltaic Power Development, The Grid Converter –	08
	n Grid Integration of WT and PV Systems.	
	rter Structures: Introduction, Inverter Structures Derived from H-Bridge	
	Structures Derived from NPC Topology, Typical PV Inverter Structures, Three-	
	, Control Structures, Conclusions and Future Trends.	
	s for PV: Introduction, International Regulations, Response to Abnormal Grid	
Conditions, Power	Quality, Anti-islanding Requirements. ■	
Revised Bloom's	$L_1$ – Remembering, $L_2$ – Understanding.	1
Taxonomy Level		
Module-2		
Grid Synchronizat	tion in Single-Phase Power Converters: Introduction, Grid Synchronization	08
Techniques for Sing	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs	
	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI	
Based on In-Quadra Frequency-Locked Revised Bloom's	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI	
Based on In-Quadra Frequency-Locked	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop.	
Based on In-Quadra Frequency-Locked Revised Bloom's	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop.	
Based on In-Quadra Frequency-Locked Revised Bloom's Taxonomy Level Module-3	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop.	08
Based on In-Quadra Frequency-Locked  Revised Bloom's Taxonomy Level  Module-3 Islanding Detectio	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop. $ \blacksquare $ $ L_1 - \text{Remembering, } L_2 - \text{Understanding.} $	
Based on In-Quadra Frequency-Locked  Revised Bloom's Taxonomy Level  Module-3  Islanding Detectio Passive Islanding D	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop.  Loop.  L <sub>1</sub> - Remembering, L <sub>2</sub> - Understanding.  n: Introduction, Non-detection Zone, Overview of Islanding Detection Methods,	
Based on In-Quadra Frequency-Locked Revised Bloom's Taxonomy Level Module-3 Islanding Detectio Passive Islanding D Grid Converter St	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop. ■  L₁ − Remembering, L₂ − Understanding.  n: Introduction, Non-detection Zone, Overview of Islanding Detection Methods, Detection Methods, Active Islanding Detection Methods.	
Based on In-Quadra Frequency-Locked  Revised Bloom's Taxonomy Level  Module-3  Islanding Detectio Passive Islanding D  Grid Converter St  Grid Power Convert	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop. ■  L₁ − Remembering, L₂ − Understanding.  n: Introduction, Non-detection Zone, Overview of Islanding Detection Methods, Detection Methods, Active Islanding Detection Methods.  ructures for Wind Turbine Systems: Introduction, WTS Power Configurations,	
Based on In-Quadra Frequency-Locked  Revised Bloom's Taxonomy Level  Module-3  Islanding Detectio Passive Islanding D Grid Converter St Grid Power Converter Grid Requirement	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop. ■  L₁ − Remembering, L₂ − Understanding.  n: Introduction, Non-detection Zone, Overview of Islanding Detection Methods, Detection Methods, Active Islanding Detection Methods.  ructures for Wind Turbine Systems: Introduction, WTS Power Configurations, ter Topologies, WTS Control.	
Based on In-Quadra Frequency-Locked Revised Bloom's Taxonomy Level Module-3 Islanding Detectio Passive Islanding D Grid Converter St Grid Power Conver Grid Requirement and Voltage Deviat	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop. ■  L₁ − Remembering, L₂ − Understanding.  n: Introduction, Non-detection Zone, Overview of Islanding Detection Methods, Detection Methods, Active Islanding Detection Methods.  ructures for Wind Turbine Systems: Introduction, WTS Power Configurations, ther Topologies, WTS Control.  ts for WT Systems: Introduction, Grid Code Evolution (Germany), Frequency	
Based on In-Quadra Frequency-Locked  Revised Bloom's Taxonomy Level  Module-3 Islanding Detectio Passive Islanding D Grid Converter St Grid Power Conver Grid Requirement and Voltage Deviat Reactive Power Co	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop. ■  L₁ − Remembering, L₂ − Understanding.  n: Introduction, Non-detection Zone, Overview of Islanding Detection Methods, Detection Methods, Active Islanding Detection Methods.  ructures for Wind Turbine Systems: Introduction, WTS Power Configurations, ter Topologies, WTS Control.  Is for WT Systems: Introduction, Grid Code Evolution (Germany), Frequency ion under Normal Operation,	
Based on In-Quadra Frequency-Locked  Revised Bloom's Taxonomy Level  Module-3 Islanding Detectio Passive Islanding D Grid Converter St Grid Power Conver Grid Requirement and Voltage Deviat Reactive Power Co	gle-Phase Systems, Phase Detection Based on In-Quadrature Signals, Some PLLs ature Signal Generation, Some PLLs Based on Adaptive Filtering, The SOGI Loop. ■  L₁ − Remembering, L₂ − Understanding.  n: Introduction, Non-detection Zone, Overview of Islanding Detection Methods, Detection Methods, Active Islanding Detection Methods.  ructures for Wind Turbine Systems: Introduction, WTS Power Configurations, ter Topologies, WTS Control.  Is for WT Systems: Introduction, Grid Code Evolution (Germany), Frequency ion under Normal Operation, Active Power Control in Normal Operation, Introl in Normal Operation (Germany), Behaviour under Grid Disturbances	

## M.TECH POWER ELECTRONICS (EPE) 16EPE251 CONVERTERS FOR SOLAR AND WIND POWER SYSTEMS (Elective Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

CHOICE BASED CREDIT SYSTEM (CBCS)			
Module-4		Teaching Hours	
Vector under Grid I Grid Conditions, Th Double Second-Ord <b>Grid Converter Co</b> Voltage Control, Vo Droop Control and		08	
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.		
Module-5			
Control of Grid Converters under Grid Faults: Introduction, Overview of Control Techniques for Grid-Connected Converters under Unbalanced Grid Voltage Conditions, Control Structures for Unbalanced Current Injection, Power Control under Unbalanced Grid Conditions, Flexible Power Control with Current Limitation.  Grid Filter Design: Introduction, Filter Topologies, Design Considerations, Practical Examples of LCL Filters and Grid Interactions, Resonance Problem and Damping Solutions, Nonlinear Behaviour of the Filter. ■		08	
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying.		

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain developments in the PV and WT penetrations in the worldwide power systems.
- Discuss the various high-efficiency topologies for PV inverters and generic control structures.
- Describe the grid requirements for PV installations, and different quadrature signal generator methods,
- Explain grid synchronization techniques for single phase power converters.
- Explain islanding detection methods and typical WT grid converter topologies, control structures, the grid requirements for WT grid connection and the grid codes.
- Explain grid synchronization of three phase power converters and new robust synchronization structures to cope with the unbalance and distorted grid conditions.
- Explain the grid converter control structures for WT and the control issue for the case of grid faults.
- Design grid interface filters used to damp the resonance for LCL filters and methods for controlling the grid current.

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions.

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

# Text Book 1 Grid Converters for Photovoltaic and Wiley Wind Power Systems Remus Teodorescu at al Wiley 2011

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M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS) SEMESTER - II							
UNINTERRUPTIBLE POWER SUPPLY (Elective Course)							
Course Code	16EPE252	IA Marks	20				
Number of Lecture Hours/Week	03	Exam Hours	03				

Credits - 03

40

#### **Course objectives:**

Total Number of Lecture Hours

• To explain the classification of UPS, batteries for UPS, parallel operation and performance evaluation and control of UPS systems.

Exam Marks

- To describe sources of harmonics, effects of harmonics in UPS, and their mitigation using active filters.
- To describe different topologies of active filters, their applications, configurations, control methods, modelling and analysis, and stability issues.
- To explain the analysis, control, and steady-state operation of unified power quality conditioners.
- To give the concept of reduced parts converters, their operation, modelling, simulation and analysis.
- To explain reduced part active filters and power quality conditioners, modelling, analysis and design of digital control.

digital cont	trol. ■	
Module-1		Teaching Hours
Uninterruptible Power Supplies: Classification, Batteries for UPS Applications, Flywheels for UPS Applications, Comparative Analysis of Flywheels and Electrochemical Batteries, Applications of UPS Systems, Parallel Operation, Performance Evaluation of UPS Systems, Power Factor Correction in UPS Systems, Control of UPS Systems, Converters for UPS Systems, Battery Charger/Discharger. ■		
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-2		
Active Filters: Harmonic Definition, Harmonic Sources in Electrical Systems, Effects of Harmonics, Harmonic Mitigation Methods, Classification of Active Filters, Active Filters for DC/DC Converters, Modelling and Analysis, Control Strategies, Stability Assessment. ■		08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-3		
Unified Power Quality Conditioners: Series—Parallel Configuration, Current Control, Voltage Control, Power Flow and Characteristic Power.  Reduced-Parts Uninterruptible Power Supplies: Concept of Reduced-Parts Converters Applied to Single-Phase On-Line UPS Systems, New On-Line UPS Systems Based on Half-Bridge Converters.		08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-4		
New On-Line UPS Systems Based on a Novel AC/DC Rectifier: New Three-Phase On-Line UPS System with Reduced Number of Switches, New Single-Phase to Three-Phase Hybrid Line-Interactive/On-Line UPS System. ■		08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-5		
Reduced-Parts Active Filters: Reduced-Parts Single-Phase and Three-Phase Active Filters, Reduced-Parts Single-Phase Unified Power Quality Conditioners, Reduced-Parts Single-Phase Series-Parallel Configurations, Reduced-Parts Three-Phase Series-Parallel Configurations.  Modelling, Analysis, and Digital Control: Systems Modelling Using the Generalized State Space Averaging Method, Digital Control. ■  Revised Bloom's L₁ − Remembering, L₂ − Understanding, L₃ − Applying.		08
Taxonomy Level		

# M.TECH POWER ELECTRONICS (EPE) 16EPE252 UNINTERRUPTIBLE POWER SUPPLY (Elective Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain classification of UPS, batteries for UPS, parallel operation and performance evaluation and control of UPS systems.
- Describe sources of harmonics and their mitigation using active filters.
- Describe topologies of active filters, their applications, control methods, modeling analysis, and stability issues.
- Explain steady-state operation and control of unified power quality conditioners.
- Explain an on-line ups system based on novel AC/DC rectifier.
- Explain the concept of reduced parts active filters, their modeling and control. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Modern Tool Usage.

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

1	Uninterruptible Power Supplies and Active Filters	Ali Emadi et al	CRC Press	2005
2	Uninterruptible Power Supplies and Standby Power Systems	Alexander C King, William Knight	McGraw-Hill	2003

	M.TECH POWER ELECTRONICS (EPE)
	CHOICE BASED CREDIT SYSTEM (CBCS)
	SEMESTER - II
POV	WER OUALITY PROBLEMS AND MITIGATION (Elect

POWER QUALITY PROBLEMS AND MITIGATION (Elective Course)							
Course Code 16EPE253 IA Marks 20							
Number of Lecture Hours/Week	03	Exam Hours	03				
Total Number of Lecture Hours	40	Exam Marks	80				
	O 711 00						

#### Credits - 03

- To give an introduction on power quality (PQ), causes and effects of PQ problems, requirement of PQ improvements, and mitigation aspects of PQ problems.
- To give PQ definitions, terminologies, standards, benchmarks, monitoring requirements through numerical problems.
- To explain passive shunt and series compensation using lossless passive LC components, active shunt compensation using DSTATCOM (distribution static compensators), active series compensation using DVR (dynamic voltage restorer), and combined compensation using UPQC (unified power quality compensator) for mitigation of current-based PQ problems.
- To explain classification, modeling and analysis of various nonlinear loads which cause the power quality problems.

quanty pro	olems. =	1			
Module-1		Teaching Hours			
Problems, Causes of Classification of Mit Power Quality State Standards and Mont Standards, Power Q Passive Shunt and Compensators, Claster Passive Shunt and Standards Shunt and Standards Shunt and Standards Standard	roduction, State of the Art on Power Quality, Classification of Power Quality from Quality Problems, Effects of Power Quality Problems on Users, itigation Techniques for Power Quality Problems.  Introduction, State of the Art on Power Quality itoring, Power Quality Terminologies, Power Quality Definitions, Power Quality Monitoring, Numerical Examples.  Series Compensation: Introduction, State of the Art on Passive Shunt and Series sification of Passive Shunt and Series Compensators, Principle of Operation of Series Compensators, Analysis and Design of Passive Shunt Compensators, ion, and Performance of Passive Shunt and Series Compensators, Numerical	08			
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.				
Module-2					
Active Shunt Compensation: Introduction, State of the Art on DSTATCOMs, Classification of DSTATCOMs, Principle of Operation and Control of DSTATCOMs, Analysis and Design of DSTATCOMs, Modelling, Simulation, and Performance of DSTATCOMs, Numerical Examples.Revised Bloom's Taxonomy LevelL₁ – Remembering, L₂ – Understanding, L₃ – Applying, L₄ – Analysing.					
Module-3					
Active Series Com Classification of Ac Compensators, Ana	pensation: Introduction, State of the Art on Active Series Compensators, etive Series Compensators, Principle of Operation and Control of Active Series lysis and Design of Active Series Compensators, Modelling, Simulation, and ive Series Compensators, Numerical Examples. ■	08			
Revised Bloom's $L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.					
Module-4					
Unified Power Quality Compensators: Introduction, State of the Art on Unified Power Quality Compensators, Classification of Unified Power Quality Compensators, Principle of Operation and Control of Unified Power Quality Compensators, Analysis and Design of Unified Power Quality Compensators, Modelling, Simulation, and Performance of UPQCs, Numerical Examples (from 6.01 to 6.10). ■					
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.				

## M.TECH POWER ELECTRONICS (EPE) 16EPE253 POWER QUALITY PROBLEMS AND MITIGATION (Elective Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

CHOICE BASED CREDIT SYSTEM (CBCS)	
Module-5	Teaching Hours
Unified Power Quality Compensators (continued): Numerical Examples (from 6.11to 20).  Loads That Cause Power Quality Problems: Introduction, State of the Art on Nonlinear Loads, Classification of Nonlinear Loads, Power Quality Problems Caused by Nonlinear Loads, Analysis of Nonlinear Loads, Modelling, Simulation, and Performance of Nonlinear Loads, Numerical Examples. ■	08

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain causes, effects of PQ problems and classification of mitigation techniques for PQ problems.
- Explain PQ standards, terminology and monitoring requirements through numerical problems.
- Explain passive shunt and series compensation using lossless passive components.
- Explain the design, operation and modeling of active shunt compensation equipment.
- Explain the design, operation and modeling of active series compensation equipment.
- Explain the design operation and modeling of unified power quality compensators.
- Discuss mitigation of power quality problems due to nonlinear loads.

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Modern Tool Usage, Engineers and society, Ethics, Individual and Team work, Communication, Lifelong Learning.

#### **Ouestion paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

#### 

M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS) SEMESTER - II						
HYBRID ELECTRIC VEHICLES (Elective Course)						
Course Code 16EPE254 IA Marks 20						
Number of Lecture Hours/Week	03	Exam Hours	03			
Total Number of Lecture Hours	Exam Marks	80				
	Credits - 03					

- To explain the basics of electric and hybrid electric vehicles, their architecture, technologies and fundamentals.
- To explain plug in hybrid electric vehicle architecture, design and component sizing and the power electronics devices used in hybrid electric vehicles.
- To discuss various electric drives suitable for hybrid electric vehicles
- To discuss different energy storage technologies used for hybrid electric vehicles and their control.
- To explain modeling and simulation of electric hybrid vehicles by different techniques, sizing of components and design optimization and energy management. ■

componen	ts and design optimization and energy management. ■				
Module-1		Teaching Hours			
Architectures of HE Key Technology of <b>Hybridization of the</b> Plug-In Hybrid Electory <b>HEV Fundamenta</b> Component Sizing, <b>Revised Bloom's</b>	ainable Transportation, A Brief History of HEVs, Why EVs Emerged and Failed, EVs, Interdisciplinary Nature of HEVs, State of the Art of HEVs, Challenges and HEVs.  the Automobile: Vehicle Basics, Basics of the EV, Basics of the HEV, Basics of etric Vehicle (PHEV), Basics of Fuel Cell Vehicles (FCVs).  Is: Introduction, Vehicle Model, Vehicle Performance, EV Powertrain Series Hybrid Vehicle, Parallel Hybrid Vehicle, Wheel Slip Dynamics.  L₁ − Remembering, L₂ − Understanding.	08			
Taxonomy Level Module-2					
Range of Blended F and Component Siz to PHEV Conversion Power Electronics Buck Converter Use Inverter, Current So EV and PHEV Batt	PHEVs, Fuel Economy of PHEVs, Power Management of PHEVs, PHEV Design ing, Component Sizing of EREVs, Component Sizing of Blended PHEVs, HEV ons, Other Topics on PHEVs, Vehicle-to-Grid Technology.  in HEVs: Introduction, Principle of Power Electronics, Rectifiers Used in HEVs, ed in HEVs, Non-isolated Bidirectional DC–DC Converter, Voltage Source ource Inverter, Isolated Bidirectional DC–DC Converter, PWM Rectifier in HEVs, ery Chargers, Modelling and Simulation of HEV Power Electronics, Emerging Devices, Circuit Packaging, Thermal Management of HEV Power Electronics.	08			
Revised Bloom's $L_1$ – Remembering, $L_2$ – Understanding.					
Module-3					
Motor Drives, Swite	and Drives in HEVs: Introduction, Induction Motor Drives, Permanent Magnet ched Reluctance Motors, Doubly Salient Permanent Magnet Machines, Design on Motors, Thermal Analysis and Modelling of Traction Motors. ■  L₁ − Remembering, L₂ − Understanding.	08			
Taxonomy Level					
Module-4		08			
Batteries, Ultracapacitors, Fuel Cells, and Controls: Introduction, Battery Characterization, Comparison of Different Energy Storage Technologies for HEVs, Modelling Based on Equivalent Electric Circuits, Battery Charging Control, Charge Management of Storage Devices, Flywheel Energy Storage System, Hydraulic Energy Storage System, Fuel Cells and Hybrid Fuel Cell Energy Storage System. ■					
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.				

## M.TECH POWER ELECTRONICS (EPE)

16EPE254 HYBRID ELECTRIC VEHICLES (Elective Course) (continued)			
CHOICE BASED CREDIT SYSTEM (CBCS)			
Module-5	Teaching		
Modelling and Simulation of Electric and Hybrid Vehicles: Introduction, Fundamentals of	Hours 08		
Vehicle System Modelling, HEV Modelling Using ADVISOR, HEV Modelling Using PSAT,	00		
Physics-Based Modelling, Bond Graph and Other Modelling Techniques, Consideration of			
Numerical Integration Methods, Conclusion.			
HEV Component Sizing and Design Optimization: Introduction, Global Optimization Algorithms	<b>;</b>		
for HEV Design, Model-in-the-Loop Design Optimization Process, Parallel HEV Design			
Optimization Example, Series HEV Design Optimization Example, Conclusion.			
Vehicular Power Control Strategy and Energy Management: A Generic Framework, Definition,			
and Needs, Methodology to Implement, Benefits of Energy Management. ■			
<b>Revised Bloom's</b> $L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying, $L_4$ – Analysing.			
Taxonomy Level			

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain the basics of electric and hybrid electric vehicles, their architecture, technologies and fundamentals.
- Explain plug in hybrid electric vehicle architecture, design and component sizing.
- Explain the use of different power electronics devices in hybrid electric vehicles.
- Suggest a suitable electric drive for a specific type of hybrid electric vehicle.
- Explain the use of different energy storage devices used for hybrid electric vehicles, their technologies and control.
- Simulate electric hybrid vehicles by different techniques for the performance analysis.

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Modern Tool Usage, Individual and Team work, Communication.

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

#### **Text Book**

_	1	Hybrid Electric Vehicles principles and Applications with Practical Perspectives	Chris Mi,M. Abul Masrur,David Wenzhong Gao	Wiley	2011
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M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS) SEMESTER - II							
POWER ELECTRONIS LABORATORY-2							
Course Code	16EPEL26	IA Marks	20				
Number of Practical Hours/Week	03	Exam Hours	03				
Total Number of Practical Hours	40	Exam Marks	80				
	Credits - (	)2					

- To conduct experiments to assess the performance of separately excited DC motor fed by single phase and three phase fully controlled converter in continuous and discontinuous current modes.
- To conduct experiments to assess the performance of Chopper fed DC drives for class A and class C commutation in continuous current mode.
- To simulate different converters and analyze the waveform in continuous and discontinuous current modes.
- To simulate forward converter, fly back converter and resonant converter to study their performance. ■

Sl. NO	Experiments
1	Study and performance analysis of single phase fully controlled converter fed separately excited DC Motor for continuous current mode.
2	Study and performance analysis of single phase fully controlled converter fed separately excited DC Motor for discontinuous current mode.
3	Study and performance analysis of three phase fully controlled converter fed separately excited DC Motor for continuous current mode.
4	Study and performance analysis of three phase fully controlled converter fed separately excited DC Motor for discontinuous current mode.
5	Performance analysis of a practical chopper fed DC Drives system for class-A and class-C commutation and analysis of wave forms in continuous mode.
6	Simulation study of buck, boost and buck- boost converter (basic topologies) and analysis of wave forms for continuous current mode (CCM).
7	Simulation study of buck, boost and buck-boost converter (basic topologies) and analysis of wave forms for discontinuous current mode (DCM).
8	Simulation study of forward converter and fly back converter and performance analysis of various wave forms.
9	Resonant converter simulation study and analysis.
10	Closed loop operation of a buck and boost converter.
	ded Bloom's L <sub>1</sub> - Remembering, L <sub>2</sub> – Understanding L <sub>3</sub> – Applying, L <sub>4</sub> – Analysing, L <sub>5</sub> – Evaluating.

#### **Course outcomes:**

At the end of the course the student will be able to:

- Conduct experiments on single phase / three phase fully controlled converter fed separately excited DC motor to assess the performance in continuous and discontinuous current modes.
- Conduct experiments to assess the performance of Chopper fed DC drives for class A and class C commutation in continuous current mode.
- Simulate different converters for analyzing the waveform in continuous and discontinuous current modes.
- Simulate forward converter, fly back converter and resonant converter to study their performance.

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Conduct investigations of complex Problems, Modern Tool Usage, Individual and Team work, Communication.

#### M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS) SEMESTER - II

## SEMINARCourse Code16EPE27IA Marks100No. of Lecture Hours/Week--Exam Hours--Number of contact Hours/week03Number of Tutorial Hours/week--Total No. of contact Hours--Exam Marks--

#### Credits - 01

The objective of the seminar is to inculcate self-learning, face audience confidently, enhance communication skill, involve in group discussion and present and exchange ideas.

Each student, under the guidance of a Faculty, is required to

- Choose, preferably, a recent topic of his/her interest relevant to the Course of Specialization.
- Carryout literature survey, organize the Course topics in a systematic order.
- Prepare the report with own sentences.
- Type the matter to acquaint with the use of Micro-soft equation and drawing tools or any such facilities.
- Present the seminar topic orally and/or through power point slides.
- Answer the queries and involve in debate/discussion.
- Submit two copies of the typed report with a list of references.

The participants shall take part in discussion to foster friendly and stimulating environment in which the students are motivated to reach high standards and become self-confident.

The Internal Assessment marks for the seminar shall be awarded (based on the relevance of the topic, presentation skill, participation in the question and answer session and quality of report) by the committee constituted for the purpose by the Head of the Department. The committee shall consist of three faculties from the department with the senior most acting as the Chairman.

#### Marks distribution for internal assessment of the course 16EPE27 seminar:

Seminar Report: 30 marks Presentation skill:50 marks Question and Answer:20 marks

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Conduct investigations of complex Problems, Modern Tool Usage, Engineers and society, Environment and sustainability, Ethics, Individual and Team work, Communication.

#### VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI

SCHEME OF TEACHING AND EXAMINATION - 2016-17

#### M.Tech POWER EECRTONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)

 $(Total\ number\ of\ credits\ prescribed\ for\ the\ programme\ -\ 85)$ 

#### III SEMESTER

			Teaching	Hours /Week		Exami	nation		
Sl. No	Course Code	Title	Theory	Practical/ Field work/ Assignment	Duration in hours	I.A. Marks	Theory/ Practical Marks	Total Marks	Credits
		Seminar / Presentation on							
1	16EPE31	Internship.				25		25	
1   TOLLI	TOEL EST	(After 8 weeks from the date				25		25	
		of commencement)							20
2	16EPE32	Report on Internship				25		25	
2	1.CEDE22	Evaluation and Viva-Voce of					50	50	
3	16EPE33	Internship					50	50	
4	16EPE34	Evaluation of Project phase -1				50		50	1
	•	TOTAL				100	50	150	21

Number of credits completed at the end of III semester: 22+22+21=65

#### Note

Internship of 16 weeks shall be carried out during III semester.

Major part of the Project work shall also be carried out during the III semester in consultation with the Guide/s.

#### VISVESVARAYA TECHNOLOGICAL UNIVERSITY, BELAGAVI

SCHEME OF TEACHING AND EXAMINATION - 2016-17

### M.Tech POWER EECRTONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS)

(Total number of credits prescribed for the programme - 85)

#### **IV SEMESTER**

		ing Hours Week Examination				S			
Sl. No	Course Code		Theory	Practical/ Field work/ Assignment	Duration in hours	I.A. Marks	Theory/ Practical Marks	Total Marks	Credits
1	16EPE41	HVDC power Transmission	04		03	20	80	100	4
2	16EPE42X	Elective - 3	03		03	20	80	100	3
3	16EPE43	Evaluation of Project phase - 2				50	-	50	3
4	16EPE44	Evaluation of Project and Viva-Voce				-	100 + 100	200	10
		TOTAL	07		06	90	360	450	20

Number of credits completed at the end of IV semester: 22+22+21+20=85

#### Elective - 3

Course Code under 16EPE42X	Title
16EPE421	Digital Power Electronics
16EPE422	MPPT in Solar Systems
16EPE423	Multi-Terminal DC Grids
16EPE424	Multilevel Converters for Industrial Applications

**Note: 1. Project Phase-1:** 6-week duration shall be carried out between 2<sup>nd</sup> and 3<sup>rd</sup> Semester vacation. Candidates in consultation with the guide shall carry out literature survey/ visit industries to finalize the topic of Project.

- **2. Project Phase-2:** 16-week duration during 4<sup>th</sup> semester. Evaluation shall be done by the committee comprising of HoD as Chairman, Guide and Senior faculty of the department.
- **3. Project Evaluation**: Evaluation shall be taken up at the end of 4<sup>th</sup> semester. Project work evaluation and Viva-Voce examination shall conducted
- 4. Project evaluation:
  - a. Internal Examiner shall carry out the evaluation for 100 marks.
  - b. External Examiner shall carry out the evaluation for 100 marks.
  - c .The average of marks allotted by the internal and external examiner shall be the final marks of the project evaluation.
  - d. Viva-Voce examination of Project work shall be conducted jointly by Internal and External examiner for 100 marks.

M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS) SEMESTER - IV			
HVDC POWER TRANSMISSION (Core Course)			
Course Code	16EPE41	IA Marks	20
Number of Lecture Hours/Week	04	Exam Hours	03
Total Number of Lecture Hours 50 Exam Marks 80		80	
	Credits - M	•	

- To give an introduction to DC power transmission and describe the basic components of a converter, and describe the methods for compensating the reactive power demanded by the converter and the methods for simulation of HVDC systems
- To describe the types of filters for removing harmonics and the characteristics of the system impedance resulting from AC filter designs and different methods of control of HVDC converter and system.
- To explain the design techniques for the main components of an HVDC system.
- To explain the protection of HVDC system and other converter configurations used for the HVDC transmission and the recent trends for HVDC applications. ■

transmissi	on and the recent trends for HVDC applications. ■		
Module-1		Teaching Hours	
and Organization o Characteristics and	Anology: Introduction, Advantages of HVDC Systems, HVDC System Costs, Overview ation of HVDC Systems, Review of the HVDC System Reliability, HVDC cs and Economic Aspects.  Version: Thyristor, 3-Phase Converter, 3-Phase Full Bridge Converter, 12-Pulse		
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.		
Module-2			
Impedance, Active Control of HVDC Failure, HVDC Con	<b>Converter and System:</b> Converter Control for an HVDC System, Commutation ntrol and Design. ■	10	
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.		
Module-3		10	
Control of HVDC Converter and System (continued): HVDC Control Functions, Reactive Power and Voltage Stability.  Interactions between AC and DC Systems: Definition of Short Circuit Ratio and Effective Short Circuit Ratio, Interaction between HVDC and AC Power System. ■			
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.		
Module-4			
HVDC Overhead L	gn: Converter Circuit and Components, Converter Transformer, Cooling System, ine, HVDC Earth Electrodes, HVDC Cable, HVDC Telecommunications Current bise and Vibration. ■  L₁ – Remembering, L₂ – Understanding.	10	
Module-5		_	
of an HVDC Syster Other Converter ( Converter (VSC), ( Trends for HVDC	nd Protection of HVDC System: Valve Protection Functions, Protective Action m, Protection by Control Actions, Fault Analysis.  Configurations for HVDC Transmission: Introduction, Voltage Source CCC and CSCC HVDC System, 10.4 Multi-Terminal DC Transmission.  Applications: Wind Farm Technology, Modern Voltage Source Converter ems, 800 kV HVDC System. ■	10	
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.		

## M.TECH POWER ELECTRONICS (EPE) 16EPE41 HVDC POWER TRANSMISSION (Core Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain importance of DC power transmission.
- Describe the basic components of a converter, the methods for compensating the reactive power demanded by the converter
- Explain the methods for simulation of HVDC systems and its control.
- Describe filters for eliminating harmonics and the characteristics of the system impedance resulting from AC filter designs
- Explain the design techniques for the main components of an HVDC system.
- Explain the protection of HVDC system and other converter configurations used for the HVDC transmission.
- Explain the recent trends for HVDC applications. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Lifelong Learning.

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

#### Text/Reference Books

1	HVDC Transmission: Power Conversion Applications in Power Systems	Chan-Ki Kim et al	Wiley	2009
2	Direct Current Transmission	E.W. Kimbark	Wiley	1971
3	High Voltage Direct Current Transmission	Arrilaga	IET	2 <sup>nd</sup> Edition, 1998
4	HVDC Transmission	S. Kamakshaiah et al	Mc Graw Hill	2011
5	HVDC and FACTs Controllers; Applications of Static Converters in Power Systems	Vijay K Sood	BSP Books	2013
6	HVDC Power Transmission Systems	K. R. Padiyar	New Age International	2012

M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS) SEMESTER - IV			
DIGITAL POWER ELECTRONICS (Elective Course)			
Course Code	16EPE421	IA Marks	20
Number of Lecture Hours/Week	03	Exam Hours	03
Total Number of Lecture Hours 40 Exam Marks 80		80	
	Credits - 0	3	

- To give introduction to multi quadrant operation and choppers, digital power electronic circuits, power semiconductor devices applied in power electronics and the important factors involved in digital power electronics.
- To explain basic mathematics of digital control systems and mathematical modeling of digitally controlled power electronic devices such as rectifiers, inverters and converters
- To explain open loop and closed loop control of power electronic devices and energy factor application

Module-1		Teaching Hours	
Digital power electrolics and convelectronics.  Energy Factor (EF energy (SE), Energy	orical review, Traditional parameters, Multiple-quadrant operations and choppers, ronics: pump circuits and conversion Technology, Shortage of analog power version technology, Power semiconductor devices applied in digital power  (F) and Sub-sequential Parameters: Introduction, Pumping energy (PE), Stored y factor (EF), Variation energy factor (EFV), Time constant, τ, and damping time bles of applications, Small signal analysis. ■	08	
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying.		
Module-2			
Shannon's sampling analog conversion, conversion: the zero (the s-domain), The <b>Mathematical Moo</b> AC/DC controlled r Inverters, A second AC/AC (AC/DC/AC		08	
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying.		
Module-3		II.	
inverters, Single-ph PWM VSI, Three-p <b>Digitally Controlle</b> converters, Fundam	ed DC/AC Inverters: Introduction, Mathematical modelling for DC/AC PWM ase half-wave VSI, Single-phase full-bridge PWM VSI, Three-phase full-bridge phase full-bridge PWM CSI, Multistage PWM inverter, Multilevel PWM inverter. ed DC/DC Converters: Introduction, Mathematical Modelling for power DC/DC tental DC/DC converter, Developed DC/DC converters, Soft-switching tement resonant power converters.	08	
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying.		
Module-4			
(AC/DC/AC) converses SISO cycloconverter Matrix converters.  Open-loop Control	ed AC/AC Converters: Introduction, Traditional modelling for AC/AC enters, Single-phase AC/AC converter, Three-phase AC/AC voltage controllers, ers, TISO cycloconverters, TITO cycloconverters, AC/DC/AC PWM converters, If for Digital Power Electronics: Introduction, Stability analysis, Unit-step Impulse responses.	08	
Tunction responses.	i i	1	

## M.TECH POWER ELECTRONICS (EPE)

16EPE421 DIGITAL POWER ELECTRONICS (Elective Course) (continued	)
CHOICE BASED CREDIT SYSTEM (CBCS)	
Module-5	Teaching
	Hours
Closed-Loop Control for Digital Power Electronics: Introduction, PI control for AC/DC rectified	ers, <b>08</b>
PI control for DC/AC inverters and AC/AC (AC/DC/AC) converters, PID control for DC/DC	
converters.	
Energy Factor Application in AC and DC Motor Drives: Introduction, Energy storage in motor	rs,
A DC/AC voltage source, An AC/DC current source, AC motor drives, DC motor drives. ■	
<b>Revised Bloom's</b> $L_1$ – Remembering, $L_2$ – Understanding, $L_3$ – Applying.	
Taxonomy Level	

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain traditional parameters computation, multiple quadrant operation and choppers.
- Explain the disadvantages of analog power electronics and conversion technology, energy factor and sub-sequential parameters.
- Explain basic mathematics of digital control systems and mathematical modeling of digitally controlled power electronic devices such as rectifiers, inverters and converters.
- Describe mathematical modeling of AC/DC rectifiers, DC/AC inverters, DC/DC converters and AC/AC (AC/DC/AC) converters are working in the discrete-time state.
- Discuss DC/AC pulse-width-modulation (PWM) inverters and AC /AC converters modeled as a firstorder-hold (FOH) element in digital control systems.
- Discuss DC/DC converter modeled as a second order-hold (SOH) element in digital control systems.
- To explain open loop and closed loop control of power electronic devices and energy factor application of AC and DC motor drives. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

#### Text Book Digital Power Electronics and Fang Lin Luo, Hong Ye, 2005 1 Elsevier Muhammad Rashid Applications

	ECH POWER ELECT CE BASED CREDIT SEMESTER :	SYSTEM (CBCS)	
MPPT IN SOLAR SYSTEMS (Elective Course)			
Course Code	16EPE422	IA Marks	20
Number of Lecture Hours/Week	03	Exam Hours	03
Total Number of Lecture Hours 40 Exam Marks 80		80	
	Credits - 0.	3	

- To explain the PV cell, its characteristics and its models, equivalent circuits and circuit parameter calculations.
- To explain different methods of tracking maximum power point and effect of noise on MPPT and reduction of noise.
- To explain distributed Maximum Power Point Tracking of PV arrays and its analysis.
- To explain the design of high energy efficiency power converters for PV MPPT. ■

Module-1		Teaching Hours
Module, The Doubl Parameters, Examp Function for Model Maximum Power I Voltage and Short-O Revised Bloom's Taxonomy Level	bom the Photovoltaic Cell to the Field, The Electrical Characteristic of a PV le-Diode and Single-Diode Models, From Data Sheet Values to Model le: PV Module Equivalent Circuit Parameters Calculation, The Lambert W ling a PV Field, Example.  Point Tracking: The Dynamic Optimization Problem, Fractional Open-Circuit Circuit Current, Soft Computing Methods, The Perturb and Observe Approach.  L <sub>1</sub> – Remembering, L <sub>2</sub> – Understanding.	08
Module-2		
Evolution of the Per MPPT Efficiency: Disturbances in Sin	Point Tracking (continued): Improvements of the P&O Algorithm, rturbative Method, PV MPPT via Output Parameters, MPPT Efficiency.  Noise Sources and Methods for Reducing their Effects: Low-Frequency gle-Phase Applications, Instability of the Current-Based MPPT Algorithms, System, Analysis of the MPPT Performances in a Noisy Environment, e. ■	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-3		
MPPT, A New App	num Power Point Tracking of Photovoltaic Arrays: Limitations of Standard broach: Distributed MPPT, DC Analysis of a PV Array with DMPPT, Optimal of the DC Inverter Input Voltage. $\blacksquare$ $L_1 - \text{Remembering}, L_2 - \text{Understanding}.$	08
Taxonomy Level		
Module-4		
<b>Distributed Maxin</b> of a PV Array with	num Power Point Tracking of Photovoltaic Arrays (continued): AC Analysis DMPPT. ■	08
Revised Bloom's Taxonomy Level	$L_1$ – Remembering, $L_2$ – Understanding.	
Module-5		
Power, Energy, Effi in Power Converter Switching Losses.		08
Revised Bloom's Taxonomy Level	$L_1$ - Remembering, $L_2$ - Understanding, $L_3$ - Applying	

## M.TECH POWER ELECTRONICS (EPE) 16EPE422 MPPT IN SOLAR SYSTEMS (Elective Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain the PV cell, its characteristics and its models, equivalent circuits and circuit parameter calculations.
- Explain different methods of tracking maximum power point.
- Explain the sources of noise, effect of noise on MPPT and reduction of noise.
- Explain Distributed Maximum Power Point Tracking of PV arrays.
- Conduct DC analysis of PV array with DMPPT.
- Conduct AC analysis of PV array with DMPPT.
- Explain the use of high energy efficiency power converters for PV MPPT application. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Design / development of solutions, Lifelong Learning.

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

# Text Book 1 Power electronics and Control Techniques for Maximum energy harvesting in Photovoltaic systems Nicola Femia et al CRC Press 2013

M.TECH POWER ELECTRONICS (EPE) CHOICE BASED CREDIT SYSTEM (CBCS) SEMESTER - IV			
MULTI-TERMINAL DC GRIDS (Elective Course)			
Course Code	16EPE423	IA Marks	20
Number of Lecture Hours/Week	03	Exam Hours	03
Total Number of Lecture Hours 40 Exam Marks 80		80	
	Credits - 0.	3	

- To provide the fundamentals of MTDC grids, their network architectures, components and control modes and basics of voltage sourced converters.
- To explain modeling, simulation and analysis of AC- MTDC grids
- To explain the concept of power sharing in MTDC grid, load flow solution and post contingency operation
- To explain protection issues of MTDC grids, including the DC circuit breakers and fault blocking VSC systems and protection strategies.

Module-1		Teaching Hours
Grids, Enabling Tec Challenges for MTI MTDC Grids.	roduction, Rationale behind MTDC Grids, Network Architectures of MTDC chnologies and Components of MTDC Grids, Control Modes in MTDC Grid, DC Grids, Configurations of MTDC Converter Stations, Research Initiatives on Converter (VSC): Introduction, Ideal Voltage-Sourced Converter, Practical converter.	08
Revised Bloom's Taxonomy Level	$L_1$ - Remembering, $L_2$ - Understanding, $L_3$ - Applying.	
Module-2		
	Converter (continued): Control, Simulation.  is, and Simulation of AC–MTDC Grids: Introduction, MTDC Grid Model. ■  L₁ - Remembering, L₂ - Understanding, L₃ - Applying, L₄ – Analysing.	08
Taxonomy Level	$E_1$ remaindering, $E_2$ onderstanding, $E_3$ rippiying, $E_4$ rimarysing.	
Module-3		
MTDC Load flow	is, and Simulation of AC–MTDC Grids (continued): AC Grid Model, AC–Analysis, AC–MTDC Grid Model for Nonlinear Dynamic Simulation, Small-lysis of AC–MTDC Grid, Transient Stability Analysis of AC–MTDC Grid. ■  L₁ - Remembering, L₂ - Understanding, L₃ - Applying, L₄ – Analysing.	08
Taxonomy Level	$L_1$ - Keinembering, $L_2$ - Onderstanding, $L_3$ - Apprying, $L_4$ - Analysing.	
Module-4		
Sea Benchmark Sys Study 3: MTDC Gr Autonomous Powe Power Sharing, Pow	is, and Simulation of AC–MTDC Grids (continued): Case Study 1: The North stem, Case Study 2: MTDC Grid Connected to Equivalent AC Systems, Case id Connected to Multi-machine AC System.  er Sharing: Introduction, Steady-state Operating Characteristics, Concept of wer Sharing in MTDC Grid, AC–MTDC Grid Load flow Solution, Postion, Linear Model, Case Study.	08
Revised Bloom's Taxonomy Level	$L_1$ - Remembering, $L_2$ - Understanding, $L_3$ - Applying, $L_4$ - Analysing.	
Module-5		ı
Frequency Support Frequency Support Modified Droop Co Operation, Case Stu Protection of MTI	rt: Introduction, Fundamentals of Frequency Control, Inertial and Primary from Wind Farms, Wind Farms in Secondary Frequency Control (AGC), ontrol for Frequency Support, AC–MTDC Load Flow Solution, Post-Contingency ady.  OC Grids: Introduction, Converter Station Protection, DC Cable Fault Response, verters, DC Circuit Breakers, Protection Strategies.	08
raun-blocking Con	$\sim$	1

## M.TECH POWER ELECTRONICS (EPE) 16EPE423 MULTI-TERMINAL DC GRIDS (Elective Course) (continued) CHOICE BASED CREDIT SYSTEM (CBCS)

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain the fundamentals of MTDC grids, their network architectures, components and control modes
- Differentiate ideal and practical voltage sourced converters.
- Simulate AC- MTDC grids for the analysis.
- Explain the concept of power sharing in MTDC grid, load flow solution and post contingency operation.
- Explain frequency support from wind farms.
- Explain protection issues of MTDC grids, including the DC circuit breakers and fault blocking VSC systems and protection strategies. ■

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis, Modern Tool Usage, Lifelong Learning.

#### **Question paper pattern:**

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module.

# Text Book 1 Multi-Terminal Direct-Current Grids Modelling, Analysis, and Control et al 2014

M.TECH POWER ELECTRONICS (EPE)
CHOICE BASED CREDIT SYSTEM (CBCS)
CEMECTED IV

#### SEMESTER - IV

SENIEDIER - IV							
MULTILEVEL CONVERTERS FOR INDUSTRIAL APPLICATIONS (Elective Course)							
Course Code	16EPE424	IA Marks	20				
Number of Lecture Hours/Week	03	Exam Hours	03				
Total Number of Lecture Hours	40	Exam Marks	80				
Credits - 03							

- To provide an overview of medium-voltage power converters and their applications.
- To describe the generalized multilevel converter topology and to derive the classic converters with a common DC bus and to analyze the common characteristics of the symmetric topologies.
- Explain the analysis of the operation of the diode-clamped multilevel converter, and a multilevel space vector modulation and to characterize the balancing boundary of the passive front-end converter
- To describe the operation and analysis of the flying capacitor multilevel converter.
- To explain asymmetric topology with hybrid modulation and a common DC source called a cascade asymmetric multilevel converter (CAMC) with five voltage levels and its advantages.
- To analysee the behaviour of the CAMC as a distribution static compensator (DSTATCOM) and shunt active power filter in improving the power quality in medium-voltage distribution systems as custom power devices.
- To analyse the behaviour of the diode-clamped topology configured as a back-to-back converter for several working conditions.

	orking conditions. ■		
Module-1		Teaching Hours	
Converters: Introduction, Medium-Voltage Power Converters, Multilevel Converters, Applications.  Multilevel Topologies: Introduction, Generalized Topology with a Common DC Bus, Converters  Derived from the Generalized Topology, Symmetric Topologies without a Common DC Link,  Summary of Symmetric Topologies, Asymmetric Topologies. ■			
Revised Bloom's Taxonomy Level	$L_1$ - Remembering, $L_2$ - Understanding, $L_3$ - Applying, $L_4$ - Analyzing, $L_5$ - Evaluating, $L_6$ - Creating		
Module-2			
Diode-Clamped Multilevel Converter: Introduction, Converter Structure and Functional Description, Modulation of Multilevel Converters, Voltage Balance Control, Effectiveness Boundary of Voltage Balancing in DCMC Converters, Performance Results. ■			
Revised Bloom's Taxonomy Level	$L_1$ - Remembering, $L_2$ - Understanding, $L_3$ - Applying, $L_4$ - Analyzing, $L_5$ - Evaluating, $L_6$ - Creating		
Module-3			
Flying Capacitor Multilevel Converter: Introduction, Flying Capacitor Topology, Modulation Scheme for the FCMC, Dynamic Voltage Balance of the FCMC.  Cascade Asymmetric Multilevel Converter (CAMC): Introduction, General Characteristics of the CAMC, CAMC Three-Phase Inverter, Comparison of the Five-Level Topologies. ■			
Revised Bloom's Taxonomy Level	$L_1$ - Remembering, $L_2$ - Understanding, $L_3$ - Applying, $L_4$ - Analyzing, $L_5$ - Evaluating, $L_6$ - Creating		
Module-4			
Case Study 1: DSTATCOM Built with a Cascade Asymmetric Multilevel Converter: Introduction, Compensation Principles, CAMC Model, Reactive Power and Harmonics Compensation.			
Revised Bloom's Taxonomy Level	$L_1$ - Remembering, $L_2$ - Understanding, $L_3$ - Applying, $L_4$ - Analyzing, $L_5$ - Evaluating, $L_6$ - Creating		
Module-5			
Case Study 2: Medium-Voltage Motor Drive Built with DCMC: Introduction, Back-to-Back DCMC Converter, Unified Predictive Controller of the Back-to-Back DCMC in an IM Drive Application, Performance Evaluation. ■			
Revised Bloom's Taxonomy Level	$L_1$ - Remembering, $L_2$ - Understanding, $L_3$ - Applying, $L_4$ - Analyzing, $L_5$ - Evaluating, $L_6$ - Creating		

## M.TECH POWER ELECTRONICS (EPE) 16EPE424 MULTILEVEL CONVERTERS FOR INDUSTRIAL APPLICATIONS (Elective Course) (continued)

#### **CHOICE BASED CREDIT SYSTEM (CBCS)**

#### **Course outcomes:**

At the end of the course the student will be able to:

- Explain the working of medium-voltage power converters and their applications.
- Explain multilevel, symmetric and asymmetric topologies.
- Explain the structure and operation of the diode-clamped multilevel converter, and a multilevel space vector modulation.
- Characterize the balancing boundary of the passive front-end converter.
- Describe the operation and analysis of the flying capacitor multilevel converter.
- Discuss the characteristics topologies of the Cascade Asymmetric Multilevel Controller.
- Explain the working of a distribution static compensator (DSTATCOM) built with CAMC for reactive power and harmonic compensation.
- Evaluate the performance of back-to-back converter in an induction motor drive for several working conditions.

#### **Graduate Attributes (As per NBA):**

Engineering Knowledge, Problem Analysis.

#### Question paper pattern:

- The question paper will have ten questions.
- Each full question is for 16 marks.
- There will be 2 full questions (with a maximum of four sub questions in one full question) from each module.
- Each full question with sub questions will cover the contents under a module.
- Students will have to answer 5 full questions, selecting one full question from each module. ■

Text	Book			
1	Multilevel Converters for Industrial Applications	Sergio Alberto González, Santiago Andrés Verne, María Inés Valla	CRC Press	2014