

# CBCS SCHEME

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18RA56

## Fifth Semester B.Tech. Degree Examination, Jan./Feb. 2023 Mechatronics

Time: 3 hrs.

Max. Marks: 100

*Note: Answer any FIVE full questions, choosing ONE full question from each module.*

### Module-1

- 1 a. Define Mechatronics. List the advantages and disadvantages of Mechatronics. (04 Marks)
- b. With neat sketch explain closed loop control system with example. (08 Marks)
- c. Explain with a neat block diagram the working of Engine Management System. (08 Marks)

OR

- 2 a. With neat sketch explain Pneumatic sensors. (08 Marks)
- b. Write a short note on:  
i) Proximity switch      ii) Tactile sensor (12 Marks)

### Module-2

- 3 a. Sketch and explain the working principle of Hydraulic system. (10 Marks)
- b. Sketch and explain Hydraulic Rotary Actuators. (10 Marks)

OR

- 4 a. Sketch and explain Gear Trains. (10 Marks)
- b. Sketch and explain Open and Cross belt drive. (10 Marks)

### Module-3

- 5 a. Sketch and explain A.C Motors i.e., Single Phase Squirrel cage induction motor. (10 Marks)
- b. With neat sketch explain Stepper motor. (10 Marks)

OR

- 6 a. With block diagram explain Watch dog timer. (10 Marks)
- b. Explain Fault finding techniques. (10 Marks)

### Module-4

- 7 a. With block diagram explain interfacing relays. (10 Marks)
- b. Explain methodology for stepper motor control design. (10 Marks)

OR

- 8 a. Sketch and explain life curve. (10 Marks)
- b. Explain the steps involved in Response Surface Modelling. (10 Marks)

### Module-5

- 9 a. Write a short note on :  
(i) Validation methodology      (ii) Validation scheme (10 Marks)
- b. With neat sketch explain Fusion technique. (10 Marks)

OR

- 10 a. With neat sketch explain Autonomous guided vehicle. (10 Marks)
- b. Explain different parts of robot controller. (10 Marks)

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Important Note : 1. On completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages.  
2. Any revealing of identification, appeal to evaluator and /or equations written eg, 42+8 = 50, will be treated as malpractice.