# APPLIED PHYSICS HANDBOOK <br> <br> Physical Constants and Formulae 

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Basic Sciences and Humanities (Physics) Composite Board
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## Part I

## PHYSICAL CONSTANTS and STANDARD VALUES

## Chapter 1

## Physical constants and Standard Values for all Streams

### 1.1 Physical Constants

Acceleration due to Gravity $g=9.8 \mathrm{~ms}^{-2}$
Avogadro Number $6.023 \times 10^{26} \mathrm{Jkmole}^{-1} \mathrm{~K}^{-1}$
Boltzmann Constant $k=1.38 \times 10^{-23} \mathrm{JK}^{-1}$
Charge on the electron $e=-1.6 \times 10^{-19} \mathrm{C}$
Charge on the Proton $e=1.6 \times 10^{-19} \mathrm{C}$
Magnetic Peameability of Free Space $\mu_{0}=4 \pi \times 10^{-7} \mathrm{Hm}^{-1}$
Permittivity of Free Space $\epsilon_{0}=8.854 \times 10^{-23} \mathrm{Fm}^{-1}$
Planck's Constant $h=6.625 \times 10^{-34} J S$
Rest Mass of the Electron $m_{e}=9.1 \times 10^{-31} \mathrm{Kg}$
Rest Mass of the Proton $m_{p}=1.6726 \times 10^{-27} \mathrm{Kg}$
Rest Mass of the Neutron $m_{n}=1.6749 \times 10^{-27} \mathrm{Kg}$
Speed of Light $c=3 \times 10^{8} \mathrm{~ms}^{-1}$
Universal Gas constant $R=8.314 \mathrm{Jmole}^{-1} \mathrm{~K}^{-1}$

### 1.2 Stadard Values

Youngs Modulus of Steel $E=200 G P a$
Rigidity Modulus of Steel $K=80 G P a$

Bulk Modulus of Steel $K=160 G P a$
Fermi Energy of Copper $E_{F}=7 \mathrm{eV}$
Horizontal Component of Earth's Magnetic Field $B_{H}=0.3 \times 10^{-4} T$

## Part II

## FORMULAE

## Chapter 2

## Applied Physics for CSE Stream

### 2.1 Module-1 : LASER and Optical Fibers

### 2.1.1 LASER

1. Expression for the number of photons emitted per $t$ seconds $N=\frac{P t \lambda}{h c}$ Photons.
$P$ is LASER Power Output in watt, $t$ is the time in second,
$\lambda$ is the wavelength of LASER in m,
$h$ is Planck's Constant and
$c$ is the speed of light.
2. The Boltzmann relation $N_{2}=N_{1} e^{-\frac{h c}{k k T}}$
$N_{2}$ is the Number of Atoms in the higher energy state.
$N_{1}$ is the Number of Atoms in the Lower Energy State,
$\lambda$ is the wavelength of LASER,
kis Boltzmann Constant,
$T$ is Absolute Temperature.

### 2.1.2 Optical Fibers

1. Expression for Numerical Aperture of an Optical Fiber $N A=\sqrt{\frac{n_{1}^{2}-n_{2}^{2}}{n_{0}^{2}}}$ $n_{0}$ is the RI of the surrounding medium,
$n_{1}$ is the RI of the Core,
$n_{2}$ is the RI of Cladding.
2. The Acceptance Angle $\theta=\operatorname{Sin}^{-1}(N A)$
3. Attenuation Co-efficient $\alpha=\frac{-10}{L} \log _{10}\left(\frac{P_{o}}{P_{i}}\right) d B / \mathrm{km}$
$L$ is the length of the fiber in km.
$P_{o}$ is the Power Output of the fiber in $W$.
$P_{i}$ is the Power input of the fiber in $W$.
$d B$ is the unit in decibel.

### 2.2 Module -2 : Quantum Mechanics

1. The relation between Kinetic Energy and Momentum $E=\frac{p^{2}}{2 m}$, $m$ is the mass of the particle in $k g$, $p$ is the momentum of the particle in $N s$.
2. Energy of the photon $E=h v=\frac{h c}{\lambda}$,
$h$ is Planck's Constant, $v$ is the frequency of the radiation in Hz , $\lambda$ is the wavelength of the radiation in $m, c$ is the speed of light.
3. de Broglie Wavelength $\lambda=\frac{h}{p}=\frac{h}{m v}$ in meter
$h$ is Planck's Constant, $m$ is mass of the particle in kg , $v$ is the velocity of the particle $m s^{-1}$.
4. de Broglie Wavelength $\lambda=\frac{h}{\sqrt{2 m E}}$
$h$ is Planck's Constant,
$m$ is mass of the particle in kg ,
$E$ is the Kinetic Energy of the particle in $J$.
5. de Broglie Wavelength $\lambda=\frac{h}{\sqrt{2 m q V}}$
$h$ is Planck's Constant,
$m$ is the mass of the particle in kg ,
$q$ is the charge on the particle in $C$,
$V$ is the accelerating potential in $V$.
6. de Broglie Wavelength $\lambda=\frac{h}{\sqrt{2 m_{e} e V}}=\frac{12.27 \times 10^{-10}}{\sqrt{V}} \mathrm{~m}$
$h$ is Planck's Constant,
$m_{e}$ is the mass of the electron in kg ,
$e$ is the charge on the electron in $C$,
$V$ is the electron accelerating potential in $V$.
7. Heisenberg's Uncertainty Principle
$\Delta x \Delta p_{x} \geq \frac{h}{4 \pi}$
$\Delta E \Delta T \geq \frac{h}{4 \pi}$
$\Delta x$ is the uncertainty in the measurement of Position,
$\Delta P$ is the uncertainty in the measurement of Momentum,
$\Delta E$ is the uncertainty in the measurement of Energy,
$\Delta T$ is the uncertainty inn the measurement of transistion time.
8. The uncertainty in the measurment of momentum $\Delta P=m \Delta v$.
$\Delta v$ is the uncertainty in the measurment of velocity.
9. Eigen Energy Values for a Particle in a one dimensional potential well of infinite depth $E_{n}=\frac{n^{2} h^{2}}{8 m a^{2}}$,
$n=1,2,3 \ldots$ for the Ground, First and Second energy states etc.,
$h$ is Planck's Constant,
$m$ is the mass of the particle in $k g$,
$a$ is the width of the potential well in $m$.

### 2.3 Module -3 : Quantum Computing

1. The wave function in Ket notation $|\psi\rangle$ (Ket Vector), $\psi$ is the wave function.
$|\psi\rangle=\binom{\alpha_{1}}{\alpha_{2}}$
2. The matrix for of the states $|0\rangle$ and $|1\rangle$.
$|0\rangle=\binom{1}{0}$ and $|1\rangle=\binom{0}{1}$
3. Identity Operator $I=\left(\begin{array}{ll}1 & 0 \\ 0 & 1\end{array}\right)$
4. Pauli Matrices

- $\sigma_{0}=I=\left(\begin{array}{ll}1 & 0 \\ 0 & 1\end{array}\right)$.
- $\sigma_{1}=\sigma_{x}=X=\left(\begin{array}{ll}0 & 1 \\ 1 & 0\end{array}\right)$.
- $\sigma_{2}=\sigma_{y}=Y=\left(\begin{array}{cc}0 & -i \\ i & 0\end{array}\right)$.
- $\sigma_{3}=\sigma_{z}=Z=\left(\begin{array}{cc}1 & 0 \\ 0 & -1\end{array}\right)$.

5. A Matrix is said to be Unitary Matrix is $U^{\dagger} U=I$,

Here $U^{\dagger}$ is the conjugate-transpose of a matrix $U$.
6. A matrix $A$ is Hermitian if $A^{\dagger}=A$
7. The wave function in Bra notation $\langle\psi|$ (bra Vector), $\psi$ is the wave function. $\langle\psi|=\left(\begin{array}{ll}\alpha_{1}^{*} & \alpha_{2}^{*}\end{array}\right)$
8. Inner Product $\langle\psi \mid \phi\rangle=\langle\psi| *|\phi\rangle$. Here $\langle\psi|$ is a Row Vector and $|\phi\rangle$ is a Column Vector. The result is always a scalar product.
9. The product $\langle\psi \mid \psi\rangle=|\psi|^{2}$, the probability density.
10. Orthogonality $\langle\psi \mid \phi\rangle=0$

### 2.4 Module -4 : Electrical Properties of Materials and Applications

### 2.4.1 Electrical conductivity in Solids

1. The Fermi Factor $f(E)=\frac{1}{e^{\left(\frac{E-E_{F}}{k T}\right)_{+1}}}$
$E$ is the energy of the level above or below fermi level in, $E_{F}$ is the Fermi Energy, $k$ is Boltzmann Constant, $T$ is Absolute Temperature.

### 2.4.2 Superconductivity

1. The variation of Critical Field with Temperature $H_{c}=H_{0}\left[1-\frac{T^{2}}{T_{c}^{2}}\right]$ tesla, $H_{c}$ is the critical field at a temperature $T$ less than the critical temperature $T_{c}$, $H_{0}$ is the critical field at 0 K .

### 2.5 Module -5 : Application of Physics in Computing

### 2.5.1 Physics of Animation

1. The Odd Rule :When acceleration is constant, one can use the Odd Rule to time the frames. With this method, one calculate the distance the object moves between frames using a simple pattern of odd numbers. Between consecutive frames, the distance the object moves is a multiple of an odd number. For acceleration, the distance between frames increases by multiples of $1,3,5,7, \ldots$
2. The Odd number multiplier for consecutive frames= $(($ frame\# -1$) * 2)-1$
3. Multiplier for distance from first frame to current frame $=($ current frame\# -1$) 2$
4. Base distance $=\frac{\text { Total distance }}{(\text { Last frame number }-1)^{2}}$
5. Jump Magnification $J M=\frac{\text { Jump time }}{\text { Push time }}=\frac{\text { Jump Height }}{\text { Push Height }}=\frac{\text { Push Acceleration }}{\text { Jump Acceleration }}$
6. $J H=\frac{\text { Push Acceleration }}{\text { Gravitational Acceleration }}$

### 2.5.2 Statistical Physics for Computing

1. Poisson Distribution Probability Mass Function $=f(k ; \lambda)=P(X=k)=\frac{\lambda^{k} e^{-\lambda}}{k!}$
2. The Decay Equation $N=N_{0} e^{-\lambda t}$
$\lambda$ is decay constant, $t$ is the time, $N_{0}$ is Initial Number of Events, $N$ is number of events after time $t$.

## Chapter 3

## Applied Physics for EEE Stream

### 3.1 Module -1 : Quantum Mechanics

1. The relation between Kinetic Energy and Momentum $E=\frac{p^{2}}{2 m}$, $m$ is the mass of the particle in kg , $p$ is the momentum of the particle in $N s$.
2. Energy of the photon $E=h v=\frac{h c}{\lambda}$,
$h$ is Planck's Constant,
$v$ is the frequency of the radiation in Hz ,
$\lambda$ is the wavelength of the radiation in $m, c$ is the speed of light.
3. de Broglie Wavelength $\lambda=\frac{h}{p}=\frac{h}{m v}$ in meter
$h$ is Planck's Constant,
$m$ is mass of the particle in kg ,
$v$ is the velocity of the particle $m s^{-1}$.
4. de Broglie Wavelength $\lambda=\frac{h}{\sqrt{2 m E}}$
$h$ is Planck's Constant,
$m$ is mass of the particle in kg ,
$E$ is the Kinetic Energy of the particle in $J$.
5. de Broglie Wavelength $\lambda=\frac{h}{\sqrt{2 m q V}}$
$h$ is Planck's Constant,
$m$ is the mass of the particle in kg ,
$q$ is the charge on the particle in $C$,
$V$ is the accelerating potential in $V$.
6. de Broglie Wavelength $\lambda=\frac{h}{\sqrt{2 m_{e} e V}}=\frac{12.27 \times 10^{-10}}{\sqrt{\bar{V}}} \mathrm{~m}$
$h$ is Planck's Constant,
$m_{e}$ is the mass of the electron in kg ,
$e$ is the charge on the electron in $C$,
$V$ is the electron accelerating potential in $V$.
7. Heisenberg's Uncertainty Principle
$\Delta x \Delta p_{x} \geq \frac{h}{4 \pi}$
$\Delta E \Delta T \geq \frac{h}{4 \pi}$
$\Delta x$ is the uncertainty in the measurement of Position,
$\Delta P$ is the uncertainty in the measurement of Momentum,
$\Delta E$ is the uncertainty in the measurement of Energy,
$\Delta T$ is the uncertainty inn the measurement of transistion time.
8. The uncertainty in the measurment of momentum $\Delta P=m \Delta v$.
$\Delta v$ is the uncertainty in the measurment of velocity.
9. Eigen Energy Values for a Particle in a one dimensional potential well of infinite depth $E_{n}=\frac{n^{2} h^{2}}{8 m a^{2}}$,
$n=1,2,3 \ldots$ for the Ground, First and Second energy states etc.,
$h$ is Planck's Constant,
$m$ is the mass of the particle in kg ,
$a$ is the width of the potential well in $m$.

### 3.2 Module-2 : Electrical Properties of Materials

### 3.2.1 Electrical conductivity in Solids

1. The free electron mobility $\mu=\frac{v_{d}}{E}=\frac{\sigma}{n e} m^{2} V^{-1} s^{-1}$, $v_{d}$ is the drift velocity of the free elctrons, $E$ the applied electric field strength.
2. The Fermi Factor $f(E)=\frac{1}{e^{\left(\frac{E-E_{F}}{k T}\right)_{+1}}}$
$E$ is the energy of the level above or below fermi level, $E_{F}$ is the Fermi Energy, $k$ is Boltzmann Constant, $T$ is Absolute Temperature.
3. The electrical conductivity of metals as per Quantum Free Electron Theory $\sigma=\frac{1}{\rho}=\frac{n e^{2} \lambda_{F}}{m v_{F}}$ $n$ is number density of free electron (free electron concentration) in $m^{-3}$
$e$ is electronic charge in $C$, $\lambda_{F}$ is fermi level mean free path in $m$, $m$ is the rest mass of the electron in $k g$, $v_{F}$ is the fermi velocity in $\mathrm{ms}^{-1}$
4. Free electron concentration is given by $n=\frac{N N_{A} D}{A} m^{-3}$
$N$ is the number of free electrons per atom.
$N_{A}$ Avogadro number per kilo mole,
$D$ is the density of material in $k g$,
$A$ is the atomic mass.

### 3.2.2 Dielectrics

1. The Dipole Moment $\mu=q d x$, $q$ is either of the charge, $d x$ is the separation between the charges.
2. The Electronic Polarizability $\alpha_{e}=\frac{\mu_{e}}{E}$.
$E$ is the applied electric field strength.
3. The polarization $P=N \mu=\frac{q^{\prime}}{A}$,
$N$ is number of dipoles per unit volume,
$q^{\dagger}$ is surface image charge,
$A$ is the surface area.
4. The polarization $\vec{P}=\epsilon_{0}\left(\epsilon_{r}-1\right) \vec{E}$,
$\epsilon_{0}$ is Permittivity of Free Space,
$\epsilon_{r}$ is Dielectric Constant,
$E$ is the magnitude of Applied Field strength.
5. The internal field $E_{i}=E+\frac{1.2 \mu}{\pi \epsilon_{0} a^{3}}$ in one dimension. $a$ is the interdipole distance in $m$.
6. The internal field in Three Dimension is $E_{i}=E+\frac{\gamma N \alpha_{e} E}{3 \epsilon_{0}}$ in one dimension. $\gamma$ is internal field constant.
7. The internal field for elemental solid dielectric is called Lorentz Field $E_{L}=E+\frac{P}{3 \epsilon_{0}}$
8. Clausius-Mossotti relation $\frac{N \alpha_{e}}{3 \epsilon_{0}}=\frac{\epsilon_{r}-1}{\epsilon_{r}+2}$, Applicable only for Elemental Solid Dielectrics.

### 3.2.3 Superconductivity

1. The variation of Critical Field with Temperature $H_{c}=H_{0}\left[1-\frac{T^{2}}{T_{c}^{2}}\right]$ tesla, $H_{c}$ is the critical field at a temperature $T$ less than the critical temperature $T_{c}$, $H_{0}$ is the critical field at 0 K .

### 3.3 Module - 3 : LASER and Optical Fibers

### 3.3.1 LASER

1. Expression for the number of photons emitted per $t$ seconds $N=\frac{P t \lambda}{h c}$ Photons.
$P$ is LASER Power Output in watt, $t$ is the time in second,
$\lambda$ is the wavelength of LASER in m,
$h$ is Planck's Constant and
$c$ is the speed of light.
2. The Boltzmann relation $N_{2}=N_{1} e^{-\frac{h c}{\lambda k T}}$
$N_{2}$ is the Number of Atoms in the higher energy state.
$N_{1}$ is the Number of Atoms in the Lower Energy State,
$\lambda$ is the wavelength of LASER,
' $k$ 'is Boltzmann Constant,
T’ is Absolute Temperature.

### 3.3.2 Optical Fibers

1. Expression for Numerical Aperture of an Optical Fiber $N A=\sqrt{\frac{n_{1}^{2}-n_{2}^{2}}{n_{0}^{2}}}$
$n_{0}$ is the RI of the surrounding medium,
$n_{1}$ is the RI of the Core,
$n_{2}$ is the RI of Cladding.
2. The Acceptance Angle $\theta=\operatorname{Sin}^{-1}(N A)$
3. The fractional RI change $\Delta=\frac{n_{1}-n_{2}}{n_{1}}$
4. V-Number $V=\frac{2 \pi d}{\lambda} \sqrt{\left(n_{1}^{2}-n_{2}^{2}\right)}$ $d$ is the diameter of the fiber in $m$, $\lambda$ is the wavelength of light in $m$
5. The number of modes $N=\frac{V^{2}}{2}$
6. Attenuation Co-efficient $\alpha=\frac{-10}{L} \log _{10}\left(\frac{P_{o}}{P_{i}}\right) d B / \mathrm{km}$
$L$ is the length of the fiber in km .
$P_{o}$ is the Power Output of the fiber in $W$
$P_{i}$ is the Power input of the fiber in $W$.
$d B$ is the unit in decibel.

### 3.4 Module - 4 : Maxwell's Equations and EM Waves

### 3.4.1 Vector Calculus

1. The $\nabla$ operator is given by $\left(\frac{\partial}{\partial x} \hat{x}+\frac{\partial}{\partial y} \hat{y}+\frac{\partial}{\partial} \hat{z}\right)$ and a vector field $\vec{E}$ is given by $\left(E_{x} \hat{x}+E_{y} \hat{y}+\right.$ $E_{z} \hat{z}$ )
Then the Divergence of a vector field $\vec{E}$ is given by
$\nabla \cdot \vec{E}=\left(\frac{\partial}{\partial x} \hat{x}+\frac{\partial}{\partial} \hat{y}+\frac{\partial}{\partial} \hat{z}\right) \cdot\left(E_{x} \hat{x}+E_{y} \hat{y}+E_{z} \hat{z}\right)=\frac{\partial E_{x}}{\partial x}+\frac{\partial E_{y}}{\partial y}+\frac{\partial E_{z}}{\partial z}$
Divergence of a vector field signifies whether the point in a vector field is a source or a sink. If the divergence is zero then the vector field is Solenoidal.
2. $\nabla$ operator is given by $\left(\frac{\partial}{\partial x} \hat{x}+\frac{\partial}{\partial y} \hat{y}+\frac{\partial}{\partial} \hat{z}\right)$ and a vector field $\vec{E}$ is given by $\left(E_{x} \hat{x}+E_{y} \hat{y}+E_{z} \hat{z}\right)$ Then the curl of a vector field $\vec{E}$ is given by $\nabla \times \vec{E}=\left(\frac{\partial}{\partial x} \hat{x}+\frac{\partial}{\partial} \hat{y}+\frac{\partial}{\partial} \hat{z}\right) \times\left(E_{x} \hat{x}+E_{y} \hat{y}+E_{z} \hat{z}\right)=\left|\begin{array}{ccc}\hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ E_{x} & E_{y} & E_{z}\end{array}\right|$ The Curl of a vector field signifies how much the vector field rotates at a given point. If the Curl of a vector field is zero then the vector field is called Irrotational.

### 3.5 Module - 5 : Semiconductors and Devices

### 3.5.1 Electrical Conductivity in Semiconductors

1. The electrical conductivity of a semiconductor is $\sigma_{i}=\frac{1}{\rho_{i}}=n_{i} e\left(\mu_{e}+\mu_{h}\right)$ $n i$ is the intrinsic carrier concentration in $m^{-3}$,
$e$ is electronic charge in $C$,
$\mu_{e}$ and $\mu_{h}$ are electron and hole mobilities in $m^{2} V^{-1} s^{-1}$.
2. Relation between fermi energy $E_{F}$ and energy gap $E_{g}$ is given by $E_{f}=\frac{E_{g}}{2}$
3. Law of mass action $n_{i}^{2}=N_{e} N_{h}$
$N_{e}$ and $N_{h}$ are electron and hole concentrations respectively.

### 3.5.2 Hall Effect

1. The Hall Coefficient $R_{H}=\frac{1}{\rho n_{e}}$
$n_{e}$ is the free electron concentration.
$R_{H}$ is positive for holes and negative for electrons.
2. Hall field $E_{H}=R_{H} B J$
$B$ is the applied magnetic flux density,
$J$ is the current density.
3. Hall Voltage $V_{H}=R_{H} B J d$
$B$ is the applied magnetic flux density,
$J$ is the current density,
$d$ is the thickness of the material.

## Chapter 4

## Applied Physics for CV Stream

### 4.1 Module-1 : Oscillations and Shock waves

### 4.1.1 Oscillations

1. The angular velocity or angular frequency $\omega=2 \pi \nu=\frac{2 \pi}{T}=\sqrt{\frac{k}{m}}$ $v$ is the frequency of Oscillations in Hz ,
$T$ is the Time Period of oscillations in $s$,
$k$ is the force constant/stiffness factor in $N s^{-1}$,
$m$ is the mass of the body in $k g$.
2. Effective spring constant $k_{s}$ for $n$ springs in series $\frac{1}{k_{S}}=\frac{1}{k_{1}}+\frac{1}{k_{2}}+\frac{1}{k_{3}}+\ldots \frac{1}{k_{3}}$ $k_{1}, k_{2}, k_{3} \ldots$ are the spring constants of individual springs in $\mathrm{Nm}^{-1}$. for $n$ identical springs $k_{s}=\frac{k}{n}$
$k$ is the stiffness factor of each spring in $\mathrm{Nm}^{-1}$..
3. Effective spring constant $k_{p}$ for $n$ springs in parallel $k_{p}=k_{1}+k_{2}+k_{3}+\ldots k_{n}$
$k_{1}, k_{2}, k_{3} \ldots$ are the spring constants of individual springs in $\mathrm{Nm}^{-1}$.
for $n$ identical springs $k_{p}=n k$
$k$ is the stiffness factor of each spring in $\mathrm{Nm}^{-1}$..
4. The amplitude of damped oscillations $A_{d}=A e^{\frac{-b}{2 m} t}$ in $m$.
$b$ is damping constant,
$t$ is the time.
5. Amplitude in forced oscillations (As per the book Vibrations and Waves by A P French)
$A=\frac{\frac{f_{0}}{m}}{\sqrt{\left(\omega_{0}^{2}-\omega^{2}\right)^{2}+(\gamma \omega)^{2}}}$
$\frac{f_{0}}{m}$ is the amplitude of the applied periodic force per unit mass.
$\gamma$ is damping ration.
$\omega_{0}$ is the natural angular frequency of the system.
$\omega$ is the angular frequency of the applied periodic force.
or $A=\frac{\frac{f_{0}}{m}}{\sqrt{\left(\omega^{2}-p^{2}\right)^{2}+4 b^{2} p^{2}}}$
$b=\frac{r}{2 m}, p$ is the frequency of the applied periodic force.

### 4.1.2 Shock Waves

1. Mach Number $M=\frac{v_{0}}{v_{s}}$
$v_{0}$ is the velocity of the object or flow in a medium.
$v_{s}$ is the velocity of sound in the same medium.
2. Mach Angle $\theta_{M}=\operatorname{Sin}^{-1}\left(\frac{1}{M}\right)$

### 4.2 Module-2 : Elasticity

1. The Young's Modulus of the material of a wire of circular cross section loaded at one and fixed at the other $Y=\frac{F L}{\pi r^{2} l} \quad \mathrm{Nm}^{-2}$ orPa
$F$ is the applied force in $N$,
$L$ is the original length of the wire in $m$, $r$ is the radius of the wire in $m$,
$l$ is the extension in the wire in $m$.
2. The bulk modulus of the material is given by $K=\frac{P V}{\Delta V} \mathrm{Nm}^{-2} \operatorname{orPa}$
$P$ is the univorm pressure in $P a$, $V$ is the original volum in $m^{-3}$, $\Delta V$ is he change in volume in $m^{-3}$
3. The Rigidity Modulus of the material of a wire of circular cross section loaded at one and fixed at the other $\eta=\frac{F L}{A x} \quad \mathrm{Nm}^{-2}$ or Pa $F$ is the applied force tagnentially to the top surface $N$, $L$ length of the edege of the cube $m$, $A$ is the surface area of te top surface $m^{2}$, $x$ is the shearing distance $m$.
4. The Bending moment of a beam is given by $M=\frac{Y}{R} I_{g} \quad N m$ $Y$ is the Young's Modulus of the material of the beam in $P a$, $R$ is the radius of curvature of the beam in $m^{2}$, $I_{g}$ is the geometrical moment inertia of the beam in $\mathrm{kgm}^{2}$.

### 4.3 Module-3 : Acoustics, Radiometry \& Photometry

### 4.3.1 Acoustics

1. The absorption coefficient of a material surface $\alpha=\frac{\text { Sound Energy Absorbed }}{\text { Total Sound Energy Incident }}$
2. The total absorption co-efficient of all the materials in a hall is $A=\sum_{1}^{n} \alpha_{n} S_{n}$. $\alpha_{1}, \alpha_{2} \ldots$ are the absorption coefficients of the surfaces with areas $S_{1}, S_{2} \ldots$
3. Sabine's Formula for Reverberation time is $T=\frac{0.161 V}{A}$ $V$ is the volume of the Hall.

### 4.4 Module -2 : LASER and Optical Fibers

### 4.4.1 LASER

1. Expression for the number of photons emitted per $t$ seconds $N=\frac{P t \lambda}{h c}$ Photons.
$P$ is LASER Power Output in watt, $t$ is the time in second,
$\lambda$ is the wavelength of LASER in m,
$h$ is Planck's Constant and $c$ is the speed of light.
2. The Boltzmann relation $N_{2}=N_{1} e^{-\frac{h c}{\lambda k T}}$
$N_{2}$ is the Number of Atoms in the higher energy state.
$N_{1}$ is the Number of Atoms in the Lower Energy State,
$\lambda$ is the wavelength of LASER,
' $k$ 'is Boltzmann Constant,
T' is Absolute Temperature.

### 4.4.2 Optical Fibers

1. Expression for Numerical Aperture of an Optical Fiber $N A=\sqrt{\frac{n_{1}^{2}-n_{2}^{2}}{n_{0}^{2}}}$ $n_{0}$ is the RI of the surrounding medium,
$n_{1}$ is the RI of the Core,
$n_{2}$ is the RI of Cladding.
2. The Acceptance Angle $\theta=\operatorname{Sin}^{-1}(N A)$
3. Attenuation Co-efficient $\alpha=\frac{-10}{L} \log _{10}\left(\frac{P_{o}}{P_{i}}\right) d B$
$L$ is the length of the fiber in km.
$P_{o}$ is the Power Output of the fiber.
$P_{i}$ is the Power input of the fiber.
$d B$ is the unit in decibel.

### 4.5 Module-5 : Natural Hazards and Safety

1. Energy released during earthquake $\log E=5.24+1.44 M_{w}$, $M_{w}$ is the magnitude of the earthquake.
2. Magnitude of the earthquake $M_{w}=\frac{2}{3} \log M_{0}-10.7$ $M_{0}$ is the Seismic moment of the earthquake.
3. Magnitude of the earthquake interms of intensities $M=\log \left(\frac{I}{I_{0}}\right), I$ is the intensity of earthquake and $I_{0}$ is the base intesity.
4. Ratio of intensities of two earthquakes $\log \left(\frac{I_{1}}{I_{2}}\right)=10^{M_{1}-M_{2}}$ $I_{1}$ and $I_{2}$ are the intensities of two different earthquakes, $M_{1}$ and $M_{2}$ are the respective magnitudes.

In all the above equations $\log$ is $\log _{10}$

## Chapter 5

## Applied Physics for ME Stream

### 5.1 Module-1 : Oscillations and Shock waves

### 5.1.1 Oscillations

1. The angular velocity or angular frequency $\omega=2 \pi v=\frac{2 \pi}{T}=\sqrt{\frac{k}{m}}$ $v$ is the frequency of Oscillations in Hz ,
$T$ is the Time Period of oscillations in $s$,
$k$ is the force constant/stiffness factor in $N s^{-1}$,
$m$ is the mass of the body in $k g$.
2. Effective spring constant $k_{s}$ for $n$ springs in series $\frac{1}{k_{S}}=\frac{1}{k_{1}}+\frac{1}{k_{2}}+\frac{1}{k_{3}}+\ldots \frac{1}{k_{3}}$ $k_{1}, k_{2}, k_{3} \ldots$ are the spring constants of individual springs in $\mathrm{Nm}^{-1}$. for $n$ identical springs $k_{s}=\frac{k}{n}$
$k$ is the stiffness factor of each spring in $\mathrm{Nm}^{-1}$..
3. Effective spring constant $k_{p}$ for $n$ springs in parallel $k_{p}=k_{1}+k_{2}+k_{3}+\ldots k_{n}$
$k_{1}, k_{2}, k_{3} \ldots$ are the spring constants of individual springs in $\mathrm{Nm}^{-1}$.
for $n$ identical springs $k_{p}=n k$
$k$ is the stiffness factor of each spring in $\mathrm{Nm}^{-1}$..
4. The amplitude of damped oscillations $A_{d}=A e^{\frac{-b}{2 m} t}$ in $m$.
$b$ is damping constant,
$t$ is the time.
5. Amplitude in forced oscillations (As per the book Vibrations and Waves by A P French)
$A=\frac{\frac{f_{0}}{m}}{\sqrt{\left(\omega_{0}^{2}-\omega^{2}\right)^{2}+(\gamma \omega)^{2}}}$
$\frac{f_{0}}{m}$ is the amplitude of the applied periodic force per unit mass.
$\gamma$ is damping ratio given by $\frac{b}{m}$.
$\omega_{0}$ is the natural angular frequency of the system.
$\omega$ is the angular frequency of the applied periodic force.
or $A=\frac{\frac{f_{0}}{m}}{\sqrt{\left(\omega^{2}-p^{2}\right)^{2}+4 b^{2} p^{2}}}$
$b=\frac{r}{2 m}, p$ is the frequency of the applied periodic force.

### 5.1.2 Shock Waves

1. Mach Number $M=\frac{v_{0}}{v_{s}}$
$v_{0}$ is the velocity of the object or flow in a medium.
$v_{s}$ is the velocity of sound in the same medium.
2. Mach Angle $\theta_{M}=\operatorname{Sin}^{-1}\left(\frac{1}{M}\right)$

### 5.2 Module-2 : Elasticity

1. The Young's Modulus of the material of a wire of circular cross section loaded at one and fixed at the other $Y=\frac{F L}{\pi r^{2} l} \quad \mathrm{Nm}^{-2} \operatorname{orPa}$
$F$ is the applied force in $N$,
$L$ is the original length of the wire in $m$, $r$ is the radius of the wire in $m$,
$l$ is the extension in the wire in $m$.
2. The bulk modulus of the material is given by $K=\frac{P V}{\Delta V} \mathrm{Nm}^{-2} \operatorname{orPa}$
$P$ is the univorm pressure in $P a$, $V$ is the original volum in $m^{-3}$, $\Delta V$ is he change in volume in $m^{-3}$
3. The Rigidity Modulus of the material of a wire of circular cross section loaded at one and fixed at the other $\eta=\frac{F L}{A x} \quad \mathrm{Nm}^{-2}$ or Pa $F$ is the applied force tagnentially to the top surface $N$, $L$ length of the edege of the cube $m$, $A$ is the surface area of te top surface $m^{2}$, $x$ is the shearing distance $m$.
4. The Bending moment of a beam is given by $M=\frac{Y}{R} I_{g} \quad N m$ $Y$ is the Young's Modulus of the material of the beam in $P a$, $R$ is the radius of curvature of the beam in $m^{2}$, $I_{g}$ is the geometrical moment inertia of the beam in $\mathrm{kgm}^{2}$.

### 5.3 Module-3 : Thermoelectric Materials

### 5.3.1 Thermoelectricity

1. Seebeck effect, The voltage generated at the junction is $V=\alpha\left(T_{2}-T_{1}\right)$
$\alpha=\alpha_{A}+\alpha_{B}$ are the seebeck coefficients of metals A annd B.
$T_{1}$ and $T_{2}$ are the temperatures at the two junctions.
2. The $\alpha=\frac{\Delta V}{\Delta T}=\frac{E}{\Delta T}$
$E$ is the electric field in $\mathrm{Vm}^{-1}$
$\Delta T$ is the temperature gradient.
3. the peltiere coefficient $\pi_{a b}=\frac{H}{I t}$,
$I$ is the junction current,
$H$ is the heat absorbed in $t$ seconds.
4. The variation of thermo emf with temperature is $e=a t+\frac{1}{2} b t^{2}$.
$a$ and $b$ are Seebeck constants and $t=T_{2}-T_{1}$,
$T_{2}$ is the hot end emperature in $K$ and $T_{1}$ is the cold end temperature in $K$.
5. Figure of Merit $Z=\frac{\alpha^{2} \sigma}{K}$.
$\alpha$ is the seebeck coefficient of the material in microvolt/K,
$\sigma$ is electricla conductivity,
$K$ is Total thermal conductivity.
6. The Theromo EMF $e$ in terms of temperatures $T_{1}$ and $T_{2}$ is given by $e=\frac{\pi_{1}}{T_{1}}\left(T_{2}-T_{1}\right)$. $\pi_{1}$ is peltier coefficient.

### 5.4 Module-4 : Cryogenics

1. Joule Thomson Effect $\left(\frac{\delta T}{\delta P}\right)_{H}=\frac{1}{C_{p}}\left(\frac{2 a}{R T}-b\right)$
$a$ and $b$ are Van der wall's constant,
$R$ is universal gas constant $=8.314$ Joule $/ \mathrm{mole} / \mathrm{K}$.
2. Inversion Temperature $T_{i}=\frac{2 a}{b R}$
$a$ and $b$ are Van der wall's constant,
$R$ is universl gas constant $=8.314$ Joule $/ \mathrm{mole} / \mathrm{K}$

### 5.5 Module-5 : Materials and Characterization Techniques

1. Braggs' Lawnd $=2 d \sin (\theta)$
$n$ is the order of diffraction and can take values $1,2,3 \ldots$,
$\lambda$ is the wavelength of X-rays,
$d$ is the interplanar spacing, and
$\theta$ is the glancing angle corrsponding to the order of diffraction $n$.
2. Schrrer's Equation $B(2 \theta)=\frac{k \lambda}{L \cos \theta}$
$B(2 \theta)$ is the full width at half maximum,
$\lambda$ is the wavelength of X-rays, $L$ is the crystallite size,
$k$ is scherrer constant with the most common value 0.94 , $\theta$ is the glancing angle.
