B.E. Mechatronics Engineering

III SEMESTER

			Tea	ching Hours	/Week	4	Exam	ination		Credits
Sl.	Subject	Title	Theory	Tutorial	Practical/	Duration	Theory/	I.A.	Total Marks	
No	Code	Titte			Drawing		Practical	Marks		
							Marks			
1	15MAT31	Engineering Mathematics – III	04			03	80	20	100	4
2	15MT32	Material Science& Technology	04			03	80	20	100	4
3	15MT33	Mechanics of Materials	03	02		03	80	20	100	4
4	15MT34	Control System	03	02		03	80	20	100	4
5	15MT35	Analog and Digital Electronics	04			03	80	20	100	4
6	15MT36	Computer Organization	04			03	80	20	100	4
7	15MTL37	Mechanical Lab – I	1		2	03	80	20	100	2
8	15MTL38	Analog And Digital Electronics Lab	1		2	03	80	20	100	2
		TOTAL	24	04	4	24	640	160	800	28

B.E. Mechatronics Engineering

IV SEMESTER

			Teach	ing Hours /	Week			amination		Credits
Sl. No	Subject Code	Title	Theory	Tutorial	Practical/ Drawing	Duration	Theory/ Practica l Marks	I.A. Marks	Total Marks	
1	15MAT 41	Engineering Mathematics – IV	04			03	80	20	100	4
2	15MT 42	Fluid Mechanics and Machines	03	02		03	80	20	100	4
3	15MT43	Micro Controller	03	02		03	80	20	100	4
4	15MT 44	Manufacturing Technology	04			03	80	20	100	4
5	15MT45	Theory of Machines	03	02		03	80	20	100	4
6	15MT46	Instrumentation and Measurement	04			03	80	20	100	4
7	15MTL47	Mechanical Lab – II	01		02	03	80	20	100	2
8	15MTL48	Micro Controller Lab	01		02	03	80	20	100	2
		TOTAL	23	06	04	24	06	160	800	28

B.E. Mechatronics Engineering

V SEMESTER

			Tea	ching Hours	/Week		Examinat	tion		Credits
Sl. No	Subject Code	Title	Theory	Tutorial	Practical/ Drawing	Duration	Theory/ Practical Marks	I.A. Marks	Total Marks	
1	15MT51	Design Of Machine Elements	03	02		03	80	20	100	4
2	15MT52	Virtual Instrumentation	04		4	03	80	20	100	4
3	15MT53	Hydraulics and Pneumatics	04			03	80	20	100	4
4	15MT54	Micro and Smart Systems Technology	04			03	80	20	100	4
5	15MT55X	Professional Elective-I	03			03	80	20	100	3
6	15MT56X	Open Elective-I	03			03	80	20	100	3
7	15MTL57	Virtual Instrumentation Lab	01		02	03	80	20	100	2
8	15MTL58	Micro and Smart Systems Technology Lab	01		02	03	80	20	100	2
		TOTAL	22	04	04	24	09	160	800	26

Professional	Elective-I	Open Electi	ve-I
15MT551	Wireless Networks & Communication	15MT561	Mechatronics Engineering
15MT552	Operations Research	15MT562	Automation in Manufacturing
15MT553	Linear Integrated Circuits		
15MT554	Drives and Controls		
15MT555	Object Oriented Program with C ⁺⁺		

B.E. Mechatronics Engineering

VI SEMESTER

Branch: Mechatronics Engineering

			1	Teaching H	ours /Week		10080	nination		Credits
Sl. No	Subject Code	Title	Theory	Tutorial	Practical/Drawing	Dura- tion	Theory/ Practical Marks	I.A. Marks	Total Marks	
1	15MT61	PLC & SCADA	04	4		03	80	20	100	4
2	15MT62	Embedded Systems (ARM)	04			03	80	20	100	4
3	15MT63	Power Electronics	03	02		03	80	20	100	4
4	15MT64	Computer Aided Machine Drawing	02		04	03	80	20	100	4
5	15MT65X	Professional Elective-II	03			03	80	20	100	3
6	15MTL66	Open Elective-II	03			03	80	20	100	3
7	15MTL67	PLC & SCADA Lab	01		02	03	80	20	100	2
8	15MTL68	Power Electronics Lab	01		02	03	80	20	100	2
		TOTAL	21	02	08	24	640	160	800	26

Professional	Elective-II	Open Electi	ve-II
15MT651	Modeling And Simulation	15MT661	Robotics and Automation
15MT652	Rapid Prototyping	15MT662	Process Instrumentation
15MT653	Mechanical Vibration		
15MT654	Satellite Communication		
15MT655	Computer Integrated Manufacturing		

B.E. Mechatronics Engineering

VII SEMESTER

				Teaching Ho	ours /Week		Exami	nation		Credits
Sl. No	Subject Code	Title	Theory	Tutorial	Practical/Drawing	Duration	I.A. Marks	Theory/ Practical Marks	Total Marks	
1	15MT71	Industrial Robotics	04			03	20	80	100	4
2	15MT72	Thermal Engineering	04			03	20	80	100	4
3	15MT73	Signal Process	03	02		03	20	80	100	4
4	15MT74X	Professional Elective-III	03			03	20	80	100	3
5	15MT75X	Professional Elective-IV	03			03	20	80	100	3
6	15MTL76	Robotics Lab	01		02	03	20	80	100	2
7	15MTL77	Signal Process - Lab	01		02	03	20	80	100	2
8	15MTP78	Project Phase – I Seminar	-	-	-	-	50	-	50	1
		TOTAL	19	02	04	21	190	560	750	23

Professional	Elective-III	Professional	l Elective-IV
15MT741	Automation In Process Control	15MT751	Biomedical Signal Processing
15MT742	Nano Technology	15MT752	Machine Learning
15MT743	Real Time Systems	15MT753	Safety and Security of Automotive Systems
15MT744	OOPS using C++	15MT754	Digital Image Processing
15MT745	Analytical Instrumentation	15MT755	Artificial Neural Networks

B.E. Mechatronics Engineering

VIII SEMESTER

			Teach	ing Hours /Week		Exami	nation		Credit
Sl. No	Subject Code	Title	Theory	Practical/Drawing	Duration	I.A. Marks	Theory/ Practical Marks	Total Marks	
1	15MT81	Automotive Electronics & Hybrid Vehicles	4		3	20	80	100	4
2	15MT82	Communication System	4		3	20	80	100	4
4	15MT83X	Professional Elective-V	3	-	3	20	80	100	3
5	15MT84	Internship/Professional Practice	Inc	lustry Oriented	3	50	50	100	4
6	15MTP85	Project Work	-	6	3	100	100	200	9
7	15MTS86	Seminar	-	4	-	100	-	100	2
		TOTAL	11	10	15	310	390	700	26

Professional	l Elective-V
15MT831	Product Design and Development
15MT832	Artificial Intelligence
15MT833	Digital Control System
15MT834	Management Information Systems
15MT835	Radar Engineering

		G AND DIGITAL ELECTI		
	[As per Choice Bas	sed Credit System (CBCS) sch	emej SEMESTER – III	
Subject Code	15MTL38	IA Marks	20	
		Exam Marks	80	
Hours/Week	03			
		Exam Hours	03	
Total Number of				
Lecture Hours	-			
		CREDITS – 02		
Course objectives	s:			
1) Is to under	stand the characteris	stice and recording of analog or		
2) Is to design	n and develop analo	stics and working of analog ar og and digital applications		
	n and develop analo		Revised Bloom'sTa	axonomy
2) Is to design	n and develop analo		Revised Bloom'sTa	axonomy
2) Is to design Laboratory Expe	n and develop analoriments:		Revised Bloom'sTa	axonomy
2) Is to design Laboratory Experiments 1. Clipper circles	eriments:	og and digital applications	Revised Bloom'sTa (RBT)Level	axonomy
2) Is to design Laboratory Experiment 1. Clipper cir 2. Single stage	eriments: cuits and Clamper coge RC coupled ampli	og and digital applications	Revised Bloom'sTa (RBT)Level	axonomy
1. Clipper cir 2. Single stag 3. Invering A 4. Astable an	recuits and Clamper coge RC coupled amplifier, Non inverted Monostable multiv	og and digital applications fircuits using diodes. ifier using BJT and its frequenting Amplifier, voltage Follow vibrator using timer 555.	Revised Bloom'sTa (RBT)Level	axonomy
1. Clipper cir 2. Single stag 3. Invering A 4. Astable an	recuits and Clamper coge RC coupled amplifier, Non invert	og and digital applications fircuits using diodes. ifier using BJT and its frequenting Amplifier, voltage Follow vibrator using timer 555.	Revised Bloom'sTa (RBT)Level	axonomy
1. Clipper cir 2. Single stag 3. Invering A 4. Astable an 5. RC phase s	recuits and Clamper coge RC coupled amplifier, Non inverted Monostable multivashift Oscillator using	og and digital applications fircuits using diodes. ifier using BJT and its frequenting Amplifier, voltage Follow vibrator using timer 555.	Revised Bloom's Ta (RBT)Level cy respons.	axonomy
1. Clipper cir 2. Single stag 3. Invering A 4. Astable an 5. RC phase s 6. Simplifican	recuits and Clamper coge RC coupled amplifier, Non inverted Monostable multivashift Oscillator using	og and digital applications ircuits using diodes. ifier using BJT and its frequenting Amplifier, voltage Follow vibrator using timer 555. g BJT. of Boolean expression using leading to the second control of the second	Revised Bloom's Ta (RBT)Level cy respons.	axonomy
1. Clipper cir 2. Single stag 3. Invering A 4. Astable an 5. RC phase s 6. Simplificat 7. Half adder	recuits and Clamper coge RC coupled amplifier, Non inverted Monostable multivashift Oscillator using tion and realization of	og and digital applications ircuits using diodes. ifier using BJT and its frequenting Amplifier, voltage Follow vibrator using timer 555. g BJT. of Boolean expression using leading to the second control of the second	Revised Bloom's Ta (RBT)Level cy respons.	axonomy
1. Clipper cir 2. Single stag 3. Invering A 4. Astable an 5. RC phase s 6. Simplificat 7. Half adder 8. Decoder an	recuits and Clamper coge RC coupled amplifier, Non inverted Monostable multivishift Oscillator using tion and realization of and Full Adder using	circuits using diodes. ifier using BJT and its frequenting Amplifier, voltage Follow vibrator using timer 555. g BJT. of Boolean expression using logic gates.	Revised Bloom's Ta (RBT)Level cy respons.	axonomy

- 1. Analyze the Importance & Applications of Diode as Rectifiers, Filters, Zener Diode Regulators, Switching Circuits &Filters.
- 2. Design and Develop Analog and Digital Circuits.
- 3. Understand, Design and Develop counters, Registers for memory applications.

Graduate Attributes (as per NBA):

Scheme of Examination:

One Question: **70 marks**Viva- Voice: **10 Marks**Total: **80 Marks**

		ALOG & DIGITAL ELE ased Credit System (CBCS			R – III	
Subject Code	15MT35	IA Marks			20	
Number of		Exam Marks			80	
Lecture						
Hours/Week	04					
Total Number of Lecture Hours		03				
CREDITS – 04						
semiconductor proposed to-analog conversion power supplies and Modules Modules Module -1 Diode Application	perties, operational on techniques. Final logic devices. see: PN junction Dieswitch, Diode speci	make students understand a amplifiers, combinational a ally, students will gain expode, VI-Characteristics, June fications, Circuit applications, ge Regulators.	Hours Teaching	Revised (RBT)L	d analog-to-design of analog	igital digital- g amplifiers,
		s: Active filters, I & II orde	•		10 Hours	
and II order high particular oscillator, wein brid		nd pass and Band reject filte	er, phase shif	t 		
-	ers, monostable mu	compartors, zero crossing d altivibrator, astable multivib			10 Hours	

Module -4		
Logic families: Digital circuits, basic logic operations, the NOR & NAND logic gates, other IC logic gates, logic gates characteristics, the TTL logic, CMOS logic family, emitter coupled logic.	10 Hours	
Sequential circuits: RS latch, Flip flops, JK flip flop, digital registers, binary and decade counters, read and write memories.		
Module -5		
Combinational circuits: multiplexers, demultiplixers, encoders, decoders, adders Analog – Digital Converters: Quantization of analog signals, DAC, ADC, digital instrumentation System.	10 Hours	

By the end of the course the student will be able to:

- 1. Analyze the Importance & Applications of Diode as Rectifiers, Filters, Zener Diode Regulators & Switching Circuits.
- 2. With the Knowledge of Active Filters & Oscillators students can better understand the Real-time Communication Systems.
- 3. Students are prepared to Understand, Analyze & Design Various Analog Electronics circuits if recruited to Analog Electronics Industry.
- 4. Students are prepared to Understand, Analyze & Design Digital Circuits, if interested to work in VLSI Industry.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.

The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. "Electronic Circuits and systems- analog and digita l", Y.N Bapat 1992 edition, Tata Mc GrawHill.
- 2. "Opamp and Linear Integrated Circuits", Ramakant A Gayakwad $3^{\rm rd}$ edition, PHI.
- 3. "Digital Logic and Computer Design", M Morris Mano, 2001 ledition, PHI.

- "Digital Electronics: Principles and Integrated cir cuits", Anil K Maini, 2008, wiley India.
 "Linear Integrated Circuits", D. Roy Choudhury and Shail B Jain, 2nd edition, Reprint 2006, New Age International.
- 3. "Digital Principles and applications", Malvino & Leach, Tata Mc. Graw Hill.

[A	Computer Organization [As per Choice Based Credit System (CBCS) scheme] SEMESTER – III					
Subject Code	15MT36	IA Marks	20			
		Exam Marks	80			
Number of LectureHours/Week	04					
Total Number of Lecture Hours	50	Exam Hours	03			

CREDITS – 04

Course objectives:

This course enables students to:

- Describe basic structure of computers, machine instructions and programs.
- Describe different addressing modes, output operations, Stacks and Queues, Subroutines and Additional Instructions, IEEE standard for Floating point Numbers.
- Understand the accessing of I/O Devices, Interrupts, Direct Memory Access, Busses, Interface Circuits, and Standard I/O Devices.
- Know the concepts of Semiconductor RAM Memories, Read Only Memories, Cache Memories, Performance Considerations and Virtual Memories.
- Execute a Complete Instruction, Multiple Bus Organization, Microprogrammed Control and Hardwired Control.

Modules	Hours Teaching	Revised Bloom'sTaxonomy(RBT)Level
Module -1		

	<u> </u>
Basic Structure of Computers: Computer Types,	
Functional Units, Basic Operational Concepts, Bus	
Structures, Software, Performance – Processor Clock, Basic	10 Hours
Performance Equation.	
1 Chormance Equation.	
Machine Instructions and Programs: Numbers,	
Arithmetic Operations and Characters, Memory Location	
and Addresses, Memory Operations, Instructions and	
Instruction Sequencing.	
Instruction Sequencing.	
Module -2	<u> </u>
Machine Instructions and Programs (Continued): Addressing	10 Hours
Modes, Assembly Language, Basic Input and Output	10 110015
Operations, Stacks and Queues, Subroutines, Additional	
Instructions. IEEE standard for Floating point Numbers (6.7.1 of	
Chapter 6)	
Module -3	
Module -3	
Input/output Organization: Accessing I/O Devices, Interrupts,	10 Hours
Direct Memory Access, Busses, Interface Circuits, Standard I/O	10110010
Devices.	
Devices.	
Module -4	1
Memory System: Some Basic Concepts, Semiconductor RAM	10 Hours
Memories, Read Only Memories, Cache Memories, Performance	
Considerations, and Virtual Memories.	
0011014014014014014014014014014014014014	
Module -5	
Basic Processing Unit: Some Fundamental Concepts, Execution	
of a Complete Instruction, Multiple Bus Organization,	
Microprogrammed Control, Hardwired Control.	
Microprogrammed Control, Hardwired Control.	
Course outcomes:	<u> </u>
A Community and the community and a mill be able to	
After studying this course, students will be able to:	
1. Understand the basic structure of computer and machine in	astructions.
2. Understand the interfacing concepts.	
3. Understand the concepts of memory system.	
Graduate Attributes (as per NBA):	
Graduate Attirbutes (as per 115/1).	

Question paper pattern:

- The question paper will have TEN questions.
 Each full question consists of 16 marks.
 There will be 2 full questions (with maximum of FOUR sub questions) from each module.

• Each full question will have sub questions covering all the topics under a module. The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. Carl Hamacher, Zvonko Vranesic, Safwat Zaky, "Computer Organization", McGraw Hill, 5th Edition, 2015, ISBN:9781259005275.

- 1. David A. Patterson, John L. Hennessy, "Computer Organization and Design The Hardware / Software Interface ARM", Elsevier.
- 2. William Stallings, "Computer Organization & Architecture", Pearson.
- 3. Vincent P. Heuring & Harry F. Jordan, "Computer Systems Design and Architecture", Pearson.

	[As pe	CONTROL SYSTEMS r Choice Based Credit System (CBCS SEMESTER – III			
Subject Code	15MT34	IA Marks		20	
Number ofLecture		Exam Marks		80	
Hours/Week	50	Exam Hours		03	
Total Number of Lecture Hours					
CREDITS - 04					
		the fundamental concepts of Contro nd frequency response of the system			
	Modules	5	Hours Teaching		edBloom's nomy(RBT)
		Module -1			
Systems, with example Translational (Mec Analogous systems bas	es. Concept of mathem hanical acceleromete sed on force voltage an	ntroduction to Control Systems, Typatical modeling of physical systems, systems excluded), and Rotational nalogy and force current analogy. In merical problems on all topics.	Mechanical, systems,	10 Hours	
		Module -2		l	
Transfer functions for Introduction. Standard	the given SFG using test signals, respons	l Flow graph, Mason's gain formu Mason's gain formula. <u>Time respo</u> e of first order & second order sys nts. Numerical problems on all topic	nse analysis: tems for unit	10 Hours	
		Module -3		1	I
stability criterion. Routl The Root Locus Tech	h stability criterion. R I nique: Introduction.	ility. Necessary conditions for stab elative stability analysis using RH Cr Root locus concepts. Construction Numerical problems on all topics.	iterion.	10 Hours	
		Module -4			
between time & frequer	ncy response, Bode plo	on to frequency domain analysis ots. yquist plots, Nyquist stability crite		10 Hours	

analysis using Polar plot. Numerical problems on all		
Module -5		
	40.77	T
State space Analysis: Concept of state, state variables and state model. State diagrams and State models for Linear continuous-time systems (Electrical systems): State space	10 Hours	
representation using Physical and Phase variables. Derivation of transfer functions from the		
state model. Numerical problems on all topics.		
Solution of state equations: Solutions of homogeneous and Nonhomogeneous state		
equations. Properties of state transition matrix, computation of state transition matrix by		
matrix exponential and Laplace transform method. Numerical problems		

After studying this course, students will able to:

- Apply modeling knowledge in implementation physical systems.
- Understand the reduction of block diagram & analyze using Signal flow graph.
- Comment on performance of a system by evaluating various parameters.
- Model a system by applying the concept of State Space analysis
- Design and develop portable control systems

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. "Control Systems Engineering", I.J. Nagarath and M. Gopal ,New Age International (P) Limited, Publishers, Fifth edition
- 2. "Modern Control Engineering", K. Ogata, Pearson Education Asia/PHI, 4th Edition, 2002.

Reference Books

1. "Automatic Control Systems", Benjamin C. Kuo, John Wiley India Pvt. Ltd., 8th Edition, 2008. 2. "Feedback and Control System", Joseph J Distefano III et al., Schaum's Outlines, TMH, 2nd Edition 2007

		IAL SCIENCE AND TE d Credit System (CBCS) s		R – III	
Subject Code	15MT32	IA Marks		20	
Number of Lecture	04	Exam Marks		80	
Hours/Week Total Number of Lecture Hours	50	Exam Hours		03	
		CREDITS – 04			
of various engineer	anding of the relation	nships between the structur	es, properties, proc	_	
Modules				Hours Teaching	Revised Bloom's Taxonomy (RBT) Level
Module -1					
of materials, Liner Properties in plastic tensile strength, tou twinning. Atomic diffusion, f	and non-linear elastic range, Yield streng ighness plastic defor lick's laws of Diffus treep: Description of	liagram showing ductile are behavior and properties, the offset yield strength, duration of single crystal by ion, Factors attaching the late the phenomenon with example: types of fatigue lauding	mechanical ctility, ultimate slip and Diffusion mples, 3 stages of	10 Hours	
	_	es, Fatigue testing and S-N	-		
Module -2					
its types, Normalization hardenability, Surfa	ing, Hardening, Tem ace hardening metho	Continuous cooling curves pering, Martempering, Au ds like Carburizing, Cyaning, age hardening of alumin	stemparing, ding Nitriding,	10 Hours	

	<u> </u>
alloys.	
Ferrous and non ferrous materials: Properties composition and use of grey cush iron, malleable iron, SG iron and steel. Copper alloys- brasses and bronzes, aluminum alloys Al-Cu, Al-Si, Al-Zn alloys.	
Module -3	
Solidification and phase diagram: Mechanism of solidification, Homogenous and Heterogeneous nucleation. Cristal Growth, Cast metal strictures, Phase diagram. Solid solutions Substitution and Interstitial solid solution, Hume rothary rule, Intermediate phase, construction of equilibrium diagram involving complete and partial solubility, lever rule, Gibb's phase rule.	10 Hours
Module -4	
Composite materials: Definition, classification, type of matrix materials and reinforcements, advantages and application of composites. Processing of FRP Composites: Layup and curing, fabricating process, open and closed mould process, hand layup technique; structural laminate bag molding, production procedures for bag molding; filament winding, pultrusion, pulforming, thermo-forming, injection molding, blow molding. Metal Matrix Composites: Reinforcement materials, types, characteristics and selection, base metals selection. Need for MMC's and its application.	10 Hours
Module -5	
Smart Materials: Piezoelectric Materials, Electrostrictive Materials, Magnetostrictive Materials, Magnetoelectric Materials. Magnetorheological Fluids, Electrorheological Fluids, Shape Memory Materials, Fiber-Optic Sensors. Smart Sensor, Actuator and Transducer Technologies: Smart Sensors: Accelerometers; Force Sensors; Load Cells; Torque Sensors; Pressure Sensors; Microphones; Impact Hammers	10 Hours
Course outcomes: At the end of the course, the students will be able to:	<u> </u>

- Appreciate the necessity of engineering materials, Smart Sensors and its applications in various fields.
- Identify possible cause of failure due to fatigue and Creep.

- · Demonstrate the knowledge of nucleation, Crystal growth, Solid solution and Phase diagrams.
- . Appreciate the significance and applications of Various heat treatment processes.
- · Explain the definition and classification and fabrication processes of composite materials.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Materials Science and Engineering, William D. Callister Jr., John Wiley & Sons. Inc, 5th Edition, 2001.
- 2. Mechanics of Composite Materials, Second Edition, Autar K. Kaw, CRC Press, 2005.
- 3. Smart Materials and Structures M. V. Gandhi and B. So Thompson Chapman & Hall, London; New York 1992 (ISBN: 0412370107).
- 4. Materials Science and Engineering, William D. Callister Jr., John Wiley & Sons. Inc, 5th Edition, 2001
- 5. Materials Science, Shackleford., & M. K. Muralidhara, Pearson Publication 2007.
- 6. "Material Science & Metallurgy For Engineers", Dr. V.D. Kodgire& S. V. Kodgire, Everest Publication.
- 7. "Mechanical Behavior & Testing Of Materials", A. K. Bhargava, C.P. Sharma.P H I Learning Private Ltd.

- 1. An Introduction to Metallurgy; Alan Cottrell, Universities Press India Oriental Longman Pvt. Ltd., 1974.
- 2. Engineering Materials Science, W.C.Richards, PHI, 1965
- 3. Physical Metallurgy; Lakhtin, Mir Publications
- 4. Materials Science and Engineering, V.Raghavan, PHI, 2002
- 5. Elements of Materials Science and Engineering, H. VanVlack, Addison-Wesley Edn., 1998
- 6. Materials Science and Engineering, William D. Callister Jr., John Wiley & Sons. Inc, 5th Edition, 2001.

The Science Learning, 4th	and Engineering Ed., 2003.	of Materials, D	onald R. Askla	and and Pradee	p.P. Phule, Ce	ngage

Exam Marks 80 Hours/Week 03 Exam Hours 03			MECHANICAL LAB-02	1
Exam Marks 80		[As per Choice Bas	sed Credit System (CBCS) sch	neme] SEMESTER – III
Hours/Week 03 Total Number of Lecture Hours 03 CREDITS - 02 Course objectives: • Understand the characteristics and behavior of Engineering materials used for engineering applications. • To provide training to students to enrich their practical skills. Laboratory Experiments: Revised Bloom'sTaxonomy (RBT)Level Part-A 1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine. (Not for Examination) Course outcomes:	Subject Code	15MTL37	IA Marks	20
Total Number of Lecture Hours - CREDITS – 02 Course objectives: • Understand the characteristics and behavior of Engineering materials used for engineering applications. • To provide training to students to enrich their practical skills. Laboratory Experiments: Revised Bloom's Taxonomy (RBT) Level Part-A 1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:			Exam Marks	80
Total Number of Lecture Hours - CREDITS – 02 Course objectives: • Understand the characteristics and behavior of Engineering materials used for engineering applications. • To provide training to students to enrich their practical skills. Laboratory Experiments: Revised Bloom's Taxonomy (RBT) Level Part-A 1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:				
Total Number of Lecture Hours CREDITS – 02 Course objectives: • Understand the characteristics and behavior of Engineering materials used for engineering applications. • To provide training to students to enrich their practical skills. Laboratory Experiments: Revised Bloom's Taxonomy (RBT) Level Part-A 1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwell hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	Hours/Week	03		
CREDITS – 02 Course objectives: • Understand the characteristics and behavior of Engineering materials used for engineering applications. • To provide training to students to enrich their practical skills. Laboratory Experiments: Revised Bloom'sTaxonomy (RBT)Level Part-A 1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	Total Number of		Exam Hours	03
Understand the characteristics and behavior of Engineering materials used for engineering applications. To provide training to students to enrich their practical skills. Laboratory Experiments: Revised Bloom'sTaxonomy (RBT)Level Part-A 1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	Lecture Hours	-		
Understand the characteristics and behavior of Engineering materials used for engineering applications. To provide training to students to enrich their practical skills. Laboratory Experiments: Part-A 1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:		1	CREDITS – 02	
Understand the characteristics and behavior of Engineering materials used for engineering applications. To provide training to students to enrich their practical skills. Laboratory Experiments: Part-A 1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	Course objectives	S:		
Part-A 1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	applicationTo provide	s. training to students		S
1. Tensile, shear and compression tests of metallic specimens using Universal Testing machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	Laboratory Expe	i inients.		
machine. 2. Torsion Test. 3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:			Part-A	I
 Torsion Test. Bending Test on Non metallic specimens. Izod and Charpy tests on M.S Specimen. Brinell and rockwell hardness test. Part-B Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	1. Tensile, sh	near and compressi	on tests of metallic specime	ns using Universal Testing
3. Bending Test on Non metallic specimens. 4. Izod and Charpy tests on M.S Specimen. 5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	machine.			
 Izod and Charpy tests on M.S Specimen. Brinell and rockwelll hardness test. Part-B Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	2. Torsion Te	est.		
5. Brinell and rockwelll hardness test. Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	3. Bending To	est on Non metallic	specimens.	
Part-B 1. Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:			-	
 Preparation of two models on lathe involving Plain turning, Taper turning, Step turning, Thread cutting, Facing, Knurling. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:	5. Brinell and	l rockwelll hardness	test.	
Thread cutting, Facing, Knurling. 2. Demonstration on cutting the V Groove using a shaper and cutting a gear teeth using Milling Machine.(Not for Examination) Course outcomes:			Part-B	
	Thread cut 2. Demonstra	ting, Facing, Knurli tion on cutting the `	ng. V Groove using a shaper and c	
By the end of the course the student will be able to:	Course outcomes	:		
	By the end of the c	ourse the student wil	l be able to:	

- 1. Demonstrate the knowledge & skill to conduct and analysis the result with respect to Hardness testing, and different loads.
- 2. Demonstrate the various skills of Turning Facing, Knurling and Thread cutting using lathe.

Graduate Attributes (as per NBA):

Scheme of Examination:

One Question From Part -A: 30marks One Question From Part -B: 40 Marks Viva- Voice : 10 Marks

Total: 80 Marks

		CHANICS OF MATERIA			
[[As per Choice Base	ed Credit System (CBCS)	scheme] SEMESTER -	– III	
Subject Code	15MT33	IA Marks	2	20	
Number of		Exam Marks	:	80	
Lecture					
Hours/Week	04				
Total Number of		Exam Hours	(03	
Lecture Hours	50				
CREDITS – 04					
Course objectives:					
This course is design	ned to introduce basic	c principles of statics for de	eformable bodies. The n	nain objec	tive is to help
•	-	uilibrium, properly constra	•		
~	•	heory and design approach stems that will be encounter			le bodies will
neip prepare me stud	ients for complex sys	stems that will be encounter	ed ili advaliced desigli c	courses.	
Modules			Н	Iours	Revised
			Т	eaching	Bloom's
					Taxonomy
					(RBT)
					Level
Module -1					

10 Hours

Simple Stress and Strain: Introduction, Concept of Stress and Strain, Linear elasticity, Hooke's Law and Poisson's ratio. Extension / Shortening of a bar, bars with

varying cross sections (step and tapering circular and rectangular), Elongation due to

Simple shear stress and Shear strain. Volumetric strain: expression for volumetric strain, Elastic Constants and relations. Stresses in Composite Section and temperature

self weight, Principle of super position, St. Venant's Principle.

stresses (No numerical).

Module -2	
Compound Stresses: Introduction, Concept of Plane stress, Stress tensor for plane stress, stresses on inclined sections, principal stresses and maximum shear stresses, Mohr's circle for plane stress.	10 Hours
Thick and Thin Cylinder Stresses in thin cylinders, changes in dimensions of cylinder (diameter, length and volume). Thick cylinders Lame's equation (compound cylinders not included).	
Module -3	
Bending Moment and Shear Force in Beams: Introduction, Sign conventions, relationship between shear force and bending moments. Shear force and bending moment diagrams for Cantilever, simply supported and overhanging beams subjected to concentrated loads, uniformly distributed load (UDL), uniformly varying load (UVL) and couple, simple numerical.	10 Hours
Module -4	l
Bending and Shear Stresses in Beams : Introduction, Theory of simple bending, assumptions in simple bending. General equation for bending. Moment carrying capacity of a section. Shearing stresses in beams, shear stress across rectangular, symmetrical I and T sections. (Composite / notched beams not included).	10 Hours
Deflection of Beams : Introduction, Differential equation for deflection. Equations for deflection, slope and bending moment. Double integration method for cantilever and Macaulay's method for simply supported beams for point load, UDL and Couple. (Simple Numericals)	
Module -5	
Torsion of Circular Shafts : Introduction. Pure torsion, assumptions, derivation of torsional equations, polar modulus, torsional rigidity / stiffness of shafts. Power transmitted by solid and hollow circular shafts.	10 Hours
Elastic Stability of Columns: Euler's theory for axially loaded elastic long columns. Derivation of Euler's load for various end conditions, limitations of Euler's theory, Rankine's formula.	

At the end of the course, the student will be able to:

CO1: Analyze the normal stresses and strains for axially loaded members using Hooke's law

CO2: Enumerate principal stresses and shear stresses for simple two dimensional loadings

CO3: Elucidate the stresses and strains in thick and thin cylindrical pressure vessels.

CO4: Perform analysis of beams for static loading.

CO5: Design torsional shafts and structural columns

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. "Mechanics of Materials", by R.C.Hibbeler, Prentice Hall. Pearson Edu., 2011.
- 2. "Mechanics of materials", James.M.Gere, Thomson, Eighth edition 2013.
- 3. "Mechanics of materials", in SI Units, Ferdinand Beer & Russell Johston, 5th Ed., TATA McGraw Hill-2003.
- 4. "Mechanics of Materials", K.V. Rao, G.C. Raju, Subhash Publication, Fourth Edition, 2013

- 1. "Strength of Materials", S.S. Rattan, Tata McGraw Hill, 2009.
- 2. "Strength of Materials", S.S.Bhavikatti, Vikas publications House -1 Pvt. Ltd., 2nd Ed., 2006.
- 3. "Engineering Mechanics of Solids", Egor.P. Popov, Pearson Edu. India, 2nd, Edition, 1998.
- 4. "Strength of Materials", W.A. Nash, 5th Ed., Schaum's Outline Series, Fourth Edition-2007.

		MICRO CONTROLLER I	LAB
	[As per Choice Bas	sed Credit System (CBCS) scl	neme] SEMESTER – IV
Subject Code	15MTL48	IA Marks	20
		Exam Marks	80
Hours/Week	03		
Total Number of		Exam Hours	03
Lecture Hours	-		
	1	CREDITS – 02	
 To study 	assembly language p	s peripherals using 8051	
Laboratory Experiments:		Revised Bloom's Taxonomy (RBT) Level	

- Data Transfer Block move, Exchange, Sorting, Finding largest element in an array.
- 2. Arithmetic Instructions Addition/subtraction, multiplication and division, square, Cube (16 bits Arithmetic operations – bit addressable).
- 3. Counters.
- 4. Boolean & Logical Instructions (Bit manipulations).
- 5. Conditional CALL & RETURN.
- 6. Code conversion: BCD ASCII; ASCII BCD, ASCII Decimal; Decimal ASCII; HEX - Decimal and decimal - HEX.
- 7. Programs to generate delay, Programs using serial port and on-Chip timer / counter.

Part-B

- 1. Write C programs to interface 8051 chip to Interfacing modules to develop single chip solutions.
- 2. Simple Calculator using 6 digit seven segment display and Hex Keyboard interface to 8051.
- 3. Interfacing of 8051 to LCD.
- 4. External ADC and Temperature control interface to 8051.

- 5. Generate different waveforms Sine, Square, Triangular, Ramp etc. using DAC interface to 8051; change the frequency and amplitude.
- 6. Stepper and DC motor control interface to 8051.

By the end of the course the student will be able to:

- **1.** Build application on 8051 using assembly / C language.
- 2. Interface between external peripherals to 8051 using C programming.

Graduate Attributes (as per NBA):

Scheme of Examination:

One Question From Part – A: **35marks** One Question From Part – B: **35 Marks**

Viva- Voice: 10 Marks
Total: 80 Marks

	[As per Choice Bas	THEORY OF M sed Credit System (C		ne] SEM	ESTER – IV	
Subject Code	15MT45	IA Marks		20		
		Exam Marks		80		
Number of Lecture	04					
Hours/Week	04					
Total Number		Exam Hours			03	
of Lecture	50					
Hours						
	·	CREDITS	5 – 04			
Course objectives	:					
The course has bee	an decigned to intro	duce the basic conce	nte of Linam	atios and	l dynamica associ	isted with
	_	inderstand the constr	•		•	
machines.						
Modules			Hours		Bloom'sTaxonomy(RBT)	
Module -1			Teaching	Level		
Module -1						
Introduction: Def	finitions Link or ele	ment, Kinematic pair	rs, Degrees o	of		
-	,	derivation), Kinemat			10 Hours	
	•	echanisms (with prob				
	_	d four bar mechanisr nd Ratchet and Pawl		ent		
Wiotion - Geneva v	viicei ilicellaliisili ai	id Raichet and I awi	meenamsm.			
		of Mechanisms: Vel				
•		anism and slider crai		m by		
_	•	nd acceleration methus centres method (n	-	,)		
Module -2	ation to instantaneo	us centres method (n	o numericais	s).		
		ology, law of gearin	-		10 Hours	
		ears. Simple gear tra				
· ·	e speed. Reduction, ratio of epicyclic g	Epicyclic gear trains	s. Tabular m	etnods		
Module -3	ratio of cpicyclic g	om tiums.			1	
					T 4 0 ==	1
		wers. Displacement, les. Disc cam with re		l,	10 Hours	
		ower, Disc cam with re		oller		
_	•	SHM, Uniform acce	_			
retardation and Cy	cloidal motion.					

Module -4	
Balancing of Rotating Masses: Static and dynamic balancing. Balancing of single rotating mass by balancing masses in same plane and in different planes. Balancing of several rotating masses by balancing masses in same plane and in different planes.	10 Hours
Belt Drivers: Belt Drives: Flat Belt Drives, Ratio of Belt Tensions, Centrifugal Tension, power Transmitted.	
Module -5	
Gyroscope: Vectorial Representation of Angular Motion, Gyroscopic Couple. Effect of Gyroscopic Couple on Ship, Plane Disc, Aircraft, Stability of Two Wheelers.	
Governors: Types of governors; force analysis of Porter and Hartnell governors. Controlling force, stability, sensitiveness, isochronism, effort and power.	

At the end of the course, the student will be able to:

- 1. Explain the concepts of mechanism, machines, and types of motion, and calculate the mobility of a mechanism.
- 2. Determine the positions, velocities and accelerations of links of simple mechanisms by using graphical approach.
- 3. Explain basic cam terminology, analyze various types of CAMS, and draw CAM profile diagrams.
- 4. Demonstrate the knowledge of various transmission mechanisms like gears and belts, and apply them for simple problems.
- 5. Appreciate the principles of Balancing, Governors, and Gyroscope, and their applications

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Theory of Machines: Sadhu Singh, Pearson Education, 2nd edition, 2007.
- 2. Theory of Machines: Rattan S.S Tata McGraw Hill Publishing Company Ltd., New Delhi, 2nd Edition, 2006.
- 3. Theory of Machines, R. S. Khurmi, J. K. Gupta, Eurasia Publishing House, 2008 Revised Edition.

- 1. Theory of Machines and Mechanisms, John Joseph Uicker, G. R. Pennock, Joseph Edward Shigley, Oxford University Press, 2003.
- 2. Theory of Machines and Mechanisms, Amitabha Ghosh and Mallick, East West Press, 3rd Edition 2006.
- 3. Theory of Machines, Thomas Bevan, CBS Publication 1984.

		ID MECHANICS All sed Credit System (CF			ESTER – IV		
Subject Code	15MT42	IA Marks		20			
Number of Lecture Hours/Week	04	Exam Marks			80		
Total Number of Lecture Hours	50	Exam Hours		03			
		CREDITS -	- 04				
	udents to the funda	mentals of fluid mech		les of en			
Wiodules			Teaching	Level	cubioom staxor	iomy(KD1)	
Module -1						I	
fluids, viscosity, su Fluid pressure and	urface tension, vapo d its Measurement mospheric, gauge an	ection, Types of fluids r pressure and cavitati t: Intensity of pressure and vacuum pressures,	on. e, Pascal's la	w,	10 Hours		
	•	er of pressure on submed plane surfaces sub					
Module -2							
	nates only), velocity	v, continuity equation y and acceleration, vel s.			10 Hours		
	s and also from Eul	s equation of motion, er's equation, limitati		•			

Dimensional Analysis: Introduction, derived quantities, dimensions of physical quantities, dimensional homogeneity, Rayleigh's method, Buckingham's π-theorem, dimensionless numbers, similitude, types of similitudes. Fluid Flow Measurements: Venturimeter, orificemeter, pitot-tube, V-Notch and rectangular notches (Derivations Venturimeter and V-Notch only), Problems. Module -4	10 Hours
Turbomachines: Definition of a Turbomachine, parts of a Turbomachine, Comparison with positive displacement machine; Classification.	10 Hours
Energy transfer in turbo machine: Euler Turbine equation, alternate form of	
Euler turbine equation, components of energy transfer, Degree of reaction, general analysis of a Turbo machine – effect of blade discharge angle on energy transfer and degree of reaction.	
Module -5	,
Hydraulic Turbines: Classification; Constructional features, Velocity triangles and Efficiencies of Pelton Turbine, Francis Turbine and Kaplan Turbine, and simple problems. Function of a Draft tube, types of draft tubes.	10 Hours
Steam Turbines: Classification, Single stage impulse turbine - Condition for maximum blade efficiency, stage efficiency, Compounding, need for compounding, methods of compounding. Reaction turbine - Parson's reaction turbine, condition for maximum blade efficiency, reaction staging, simple problems.	

At the end of the course, the student will be able to:

- · Appreciate the fluid mechanics fundamentals, including concepts of mass and energy conservation.
- · Apply the fundamentals to flow measurement problems.
- · Perform dimensional analysis for problems in fluid mechanics.
- . Appreciate the understanding of turbomachines and principles of energy transfer in turbomachines.
- · Apply the fundamentals for energy transfer problems in various turbomachines.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.

- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.

The students will have to answer 5 full questions, selecting one full question from each module

Text Books:

- 1. Fluid Mechanics, Oijush.K.Kundu, IRAM COCHEN, ELSEVIER, 3rd Ed. 2005.
- 2. Fluid Mechanics and Fluid Machines, Dr. Bansal, R.K.Lakshmi Publications, 2004.
- 3. Textbook of Turbomachines, M S Govinde Gowda, M M Publishers, 2011

- 1. Fluid Mechanics and hydraulics, Dr.Jagadishlal: MetropolitanBook Co-Ltd., 1997.
- 2. Fluid Mechanics (SI Units), Yunus A. Cengel John M.Oimbala, 2ndEd., Tata McGraw Hill, 2006.
- 3. Fluid Mechanics, John F.Douglas, Janul and M.Gasiosek and john A.Swaffield, Pearson Education Asia, 5th ed., 2006
- 4. Fluid Mechanics and Fluid Power Engineering, Kumar.D.S, Kataria and Sons., 2004
- 5. Fluid Mechanics -. Merle C. Potter, Elaine P.Scott. Cengage learning.

INSTRUMENTATION AND MEASUREMENTS [As per Choice Based Credit System (CBCS) scheme] SEMESTER - IV Subject Code 15MT46 IA Marks 20 Exam Marks 80 Number ofLecture Hours/Week 04 Exam Hours 03 50 Total Number of Lecture Hours **CREDITS - 04 Course objectives:** • To provide the fundamental knowledge of transducers, instrumentation and measurement systems. • To understand the functional elements of instrumentation/measurement systems. • To impart the knowledge of static and dynamic characteristics of instruments, and understand the factors in selection of instruments for measurement. • To discuss the principle, design and working of transducers for the measurement of displacement, level, strain, resistance capacitance inductance, pressure, sound and speed. Modules Hours RevisedBloom's Teaching Taxonomy(RBT) Level Module -1 Classification and Functional Elements of Instrument/ measurement system: Measurement, significance of measurement, instruments and measurement systems. 10 Hours mechanical, electrical and electronic instruments, Deflection & Null type instruments and their comparison, Analog and digital modes of operation, functions of instruments and measurement systems, applications of measurement systems, Elements of generalized measurement system, Input-output configuration of measuring instruments and measurement systems, methods of correction for interfering and modifying inputs. Transducers, Classifications of transducers-primary & secondary, active & passive, analog and digital transducers. Module -2 Static and Dynamic Characteristics: Static calibration and error calibration curve, accuracy 10 Hours and precision, indications of precision, static error, scale range and scale span, reproducibility and drift, repeatability, signal to noise ratio, sensitivity, linearity, hysteresis, threshold, dead zone and dead time, resolution, signal to noise ratio, factors influencing the choice of transducers/instruments. Dynamic response - dynamic characteristics, time domain analysis & different types of inputs, frequency domain analysis. Time domain response - zero order system, first order electrical system, response of a first order system to step & ramp input, Second order system, response of a second order system to step input, time domain specifications, frequency response of first and second order system. Module -3 **Measurement of Displacement:** Introduction, Principles of Transduction, Variable resistance 10 Hours devices, variable Inductance Transducer, Variable Capacitance Transducer, Hall Effect Devices,

Proximity Devices, Digital Transducer

detector, thermal level sensors

<u>Measurement of Level</u>: Capacitance probes, conductivity probes, differential pressure level detector, float level devices, optical level switches, radiation level sensor, ultrasonic level

Module -4		
Measurement of Strain: Introduction, Factors affecting strain measurements, Types of Strain Gauges, Theory of operation of resistance strain gauges, Types of Electrical Strain Gauges – Wire gauges, unbounded strain gauges, foil gauges, semiconductor strain gauges (principle, types & list of characteristics only), Materials for Strain Gauges, Strain gauge Circuits – Wheatstone bride circuit, Applications. Measurement of resistance, induction and capacitance: Whetstone's bridge, Kelvin Bridge; ACbridges, Capacitance Comparison Bridge, Maxwell's bridge, wein's bridge, Wagners's earth connection.	10 Hours	
Module -5		
<u>Transducers – I:</u> Introduction, Electrical transducers, Selecting a transducer, Resistive transducers,Resistive position transducer, Strain gauges, Resistance thermometer, Thermistor, Inductive transducer,Differential output transducers and LVDT. <u>Transducers – II:</u> Piezoelectric transducer, Photovoltaic transducer,	10 Hours	

After studying this course, students will able to:

• Define the transducer, instrument, measurement and classify different types of transducers

Semiconductor photo devices, Temperature transducers-RTD, Thermocouple(b) Display Devices: Digital display system, classification of display, Display devices, LEDs, LCD displays

- Explain the functional elements of instrumentation / measurement systems
- Discuss the input-output configuration of measurement systems
- Define, interpret and analyze the static and dynamic characteristics of instruments
- Explain the principle, design and analyze the transducers for the measurement of displacement, level, strain, force, torque, pressure, sound and speed

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Electrical and Electronic Measurements and Instrumentation A. K. Sawhney, 17th Edition (Reprint 2004), DhanpatRai& Co. Pvt. Ltd., 2004. (Module 1 & 2)
- 2. Instrumentation: Devices and Systems- C. S. Rangan, G. R. Sarma, V. S. V. Mani, 2nd Edition (32nd Reprint), McGraw Hill Education (India), 2014. (Module 3-Displacement measurement, Module 4,
- 3. Process Measurement Instrument Engineers Handbook- Bela G. Liptak, Revised Edition, Chilton Book Company, 1982. (Module 3 Level measurement.)
- 4. "Electronics Instrumentation", H.S. Kalsi, TMH, 2004-Module 5

- 1. Transducers and Instrumentation D.V.S.Murty, 2nd Edition, PHI, 2009.
- 2. Introduction to Measurements and Instrumentation A. K. Ghosh, 2nd Edition, PHI, 2007.
- 3. Instrumentation Measurement and Analysis- B.C.Nakra and K.K.Choudhry, 3rd Edition, McGraw Hill Education (India) Pvt.Ltd. 2009.
- 4. Measurement Systems Application and Design- Ernest O.Doeblin and Dhanesh N Manik, 5th Edition, McGraw Hill, 2007

		IANUFACTURING To ased Credit System (CE			
Subject Code	15MT44	IA Marks	, <u>-</u>	20	
Number of Lecture		Exam Marks	80		
Hours/Week	04				
Total Number of Lecture Hours	50	Exam Hours	03		
		CREDITS -	- 04		
Course objectives	S:				
To introduce stude	ents to the fundame	entals of modern manuf	acturing opera	ations.	
			RevisedBloom'sTaxonomy(RBT) Level		
Module -1					
process, its import Classification of M Casting:Introduct components produ Patterns: Definiti Sand Moulding: Types.Types of ba	tance. Manufacturing produced by casting produced by casting produced and types. Binders and Addituse sand, requiremental pefinition, Need and s.	cess &steps involved. Vocess, Advantages & Linives: Definition, Need a ents of base sand. Types nd Types. Concept of G	Various mitations. and of Sand	10 Hours	
Introduction to a processes, charact of metalworking proging: Classific parameters. Forging forging. Rolling: Classific Rolling variables,	eristics of wrough processes. cation, Forging mangdefects, Residual ation, Types of rol Applications of Rog equipment & die	assification of metal wo t products, advantages a achines & equipment. D al stresses in forging, Ap alling mills, Defects in ro olling. es,drawing variables, Tu	nd limitations ie-design oplications of alled products.		

Extrusion: Types of extrusion processes, extrusion equipment & dies, Extrusion of seamless tubes, lubrication & defects in extrusion, Extrusion variables, Applications Sheet & Metal Forming: Forming methods dies & punches, progressivedie, compound die, combination die. Rubber forming. Open back inclinablepress (OBI press), piercing, blanking, bending, deep drawing, defects of drawn products, stretch forming, Roll bending & contouring, Applications. Advanced Welding processes: Classification, Advantages & limitations of welding. Metal Arc welding (MAW), Flux Shielded Metal Arc Welding (FSMAW), Inert Gas Welding (TIG & MIG) Submerged Arc Welding	10 Hours
(SAW) and Atomic Hydrogen Welding processes (AHW), Resistance	
welding, Applications.	
Module -4	
Non-traditional Machining Processes: Need for non-traditional machining, Principle, equipment & operation of Laser Beam, Plasma Arc Machining, Electro Chemical Machining, Ultrasonic Machining, Abrasive Jet Machining, Water Jet Machining, Electron Beam Machining, Electron Discharge Machining and Plasma Arc Machining.	10 Hours
Module -5	
Introducing to CNC machines: Basics of Turning tool Geometry, ATC, Programming methods. – Manual part programming, Milling, Turning, (Simple Programs), Computer Aided part programming (Simple problems, DNC, Types, Applications, Types of CNC Programming Software's, Over view CNC machining centers, Turning centre.	10 Hours

Course outcomes:

At the end of this course students should be able to

- 1. Understand the principles and techniques of casting, forging, rolling & drawing.
- 2. Apply the knowledge of metal working process.
- 3. To express the different techniques of joining process for metal & non metals.
- 4. Understanding and applying knowledge to execute CNC machining programs.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.

• The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. **Manufacturing Technology,** Serope Kalpakjain, Steuen.R.Sechmid, Pearson Education Asia, 5th Ed. 2006.
- Manufacturing Technology Vol 1&2, PN Rao, Tata McGraw Hill, 2001
 NC Machine Programming and Software Design, ChnoHwachang, Michel. A. Melkanoff, Prentice Hall, 1989

- 1. **Process and Materials of Manufacturing,** Roy A Lindberg, 4th Ed. Pearson Ed. 2006.
- 2. Workshop technology, Hazara Choudhry, Vol-I &II, Media Promoters & Publishers Pvt Ltd. 2004.
- 3. **Production technology,** HMT, Tata McGraw Hill, 2001.
- 4. Manufacturing Science, AmitabhGhosh and Mallik, affiliated East West press, 2003.
- 5. Fundamentals of metal Machining and machine Tools, G. Boothroyd, McGraw Hill. 2000.
- 6. **Automation Production system and Computer Integrated Manufacturing** Mikell. O. Grover, PHI, New Delhi, 2002.

		MECHANICAL LAB -	- II
	[As per Choice Bas	sed Credit System (CBCS) sc	cheme] SEMESTER – IV
Subject Code	15MTL47	IA Marks	20
		Exam Marks	80
Hours/Week	03		
Total Number of Lecture Hours	-	Exam Hours	03
	1	CREDITS – 02	
Course objectives	s:		
To study the		-	Revised Bloom's Taxonomy (RBT) Level
a. Ori b. Ve c. V-1 2. Performan a. Pel b. Fra	n of flow measuring fice Plate meter, nturimeter, notch ce testing of Turbin ton wheel uncis Turbine plan Turbine		
		Part-B	
2. Sequencin3. Regenerati	g Circuit on Hydrauve Circuit on Hydra	raulic/Pneumatic Trainer lic/Pneumatic Trainer nulic/Pneumatic Trainer raulic/Pneumatic Trainer	

Course outcomes:

By the end of the course the student will be able to:

- Determine the co-efficient of discharge of flow measuring devices.
- Select the type of turbine required with reference to available head of water and discharge.
- Apply the working principle of impulse and reaction turbine.
- Design hydraulic circuit for various industrial applications.

Graduate Attributes (as per NBA):

Scheme of Examination:

One Question From Part – A: **35marks** One Question From Part – B: **35 Marks**

Viva- Voice: 10 Marks Total: 80 Marks

	[As per Choice Based	MICROCONTROLLE I Credit System (CBCS) sc		R – IV		
		, , , , , , , , , , , , , , , , , , ,				
Subject Code	15MT43	IA Marks	IA Marks 20			
		Exam Marks	80			
Number of						
Lecture Hours/Week	04					
TIOUIS/ WCCK		Exam Hours		03		
Total Number	50	Zimii Houis				
of Lecture						
Hours						
		CREDITS – 04				
Course objectives						
		tand an in-depth operation				
	-	chniques. The emphasis is	_			
programming.	nches, displays, moto	ors, and A/D converters, thr	ough assembly ia	nguage and C language		
programming.						
Modules		Hours		m'sTaxonomy(RBT)		
		Teachin	ng Level			
Module -1						
Microprocessors a	and microcontroller.	Introduction, Microproces	sors and			
-		rvey. RISC & CISC CPU A		10 Hours		
		ture. The 8051 Architectur	,			
		Output Pins, Ports and Circ				
Memory, Counter	and Timers, Serial Da	ta Input / Output, Interrupt	S.			
Module -2				1		
	10 4 7					
Addressing Mode	g and (Inerations: In	troduction Addressing mo	des External	10 Hours		
_	_	troduction, Addressing mo		10 Hours		
data Moves, Code	Memory, Read Only	Data Moves / Indexed Add	ressing mode,	10 Hours		
data Moves, Code PUSH and POP Op	Memory, Read Only locodes, Data exchange	_	ressing mode, ations, Bit level	10 Hours		
data Moves, Code PUSH and POP Op Logical Operations Incrementing and I	Memory, Read Only Decodes, Data exchanges, Rotate and Swap Opportunity Decrementing, Additional Control of the	Data Moves / Indexed Add es, Byte level logical Oper	ressing mode, ations, Bit level ations: Flags,	10 Hours		
data Moves, Code PUSH and POP Op Logical Operations Incrementing and I Division, Decimal	Memory, Read Only Decodes, Data exchanges, Rotate and Swap Opportunity, Additional Arithmetic.	Data Moves / Indexed Add es, Byte level logical Oper- perations, Arithmetic Oper- on, Subtraction, Multiplica	ressing mode, ations, Bit level ations: Flags, tion and	10 Hours		
data Moves, Code PUSH and POP Op Logical Operations Incrementing and I Division, Decimal Jump and Call In	Memory, Read Only I pecodes, Data exchanges, Rotate and Swap Of Decrementing, Additional Arithmetic. structions: The JUM	Data Moves / Indexed Add es, Byte level logical Oper- perations, Arithmetic Oper- on, Subtraction, Multiplica P and CALL Program rang	ressing mode, ations, Bit level ations: Flags, tion and	10 Hours		
data Moves, Code PUSH and POP Op Logical Operations Incrementing and I Division, Decimal Jump and Call In and Subroutines, In	Memory, Read Only Decodes, Data exchanges, Rotate and Swap Opportunity, Additional Arithmetic.	Data Moves / Indexed Add es, Byte level logical Oper- perations, Arithmetic Oper- on, Subtraction, Multiplica P and CALL Program rang	ressing mode, ations, Bit level ations: Flags, tion and	10 Hours		
data Moves, Code PUSH and POP Op Logical Operations Incrementing and I Division, Decimal Jump and Call In and Subroutines, In	Memory, Read Only I pecodes, Data exchanges, Rotate and Swap Of Decrementing, Additional Arithmetic. structions: The JUM	Data Moves / Indexed Add es, Byte level logical Oper- perations, Arithmetic Oper- on, Subtraction, Multiplica P and CALL Program rang	ressing mode, ations, Bit level ations: Flags, tion and	10 Hours		
data Moves, Code PUSH and POP Op Logical Operations Incrementing and I Division, Decimal Jump and Call In and Subroutines, In Module -3	Memory, Read Only I pecodes, Data exchanges, Rotate and Swap Opecrementing, Additional Arithmetic. structions: The JUM Interrupts and Returns.	Data Moves / Indexed Add es, Byte level logical Oper- perations, Arithmetic Oper- on, Subtraction, Multiplica P and CALL Program rang	ressing mode, ations, Bit level ations: Flags, tion and ge, Jumps, calls	10 Hours		

Timer / Counter Programming in 8051: Programming 8051 Timers, Counter Programming, programming timers 0 and 1 in 8051 C.

Module -4		
8051 Serial Communication and Interrupts: Basics of Serial Communication, 8051 connections to RS-232, 8051 Serial communication Programming, Programming the second serial port, Serial port programming in C. Interrupts Programming,8051 Interrupts, Programming Timer Interrupts, Interrupt Priority in the 8051/52.	10 Hours	
Module -5		
Module -5		
UNIT 5: 8051 Interfacing and Applications: Hardware & Software (Assembly code / C code) Interfacing of 8051 to simple switches and LEDs, LCD, ADC, Stepper motor, DC motor, Temperature sensor, Wave form generation.	10 Hours	

Course outcomes: Student will be able to

- 1. Understand the difference between microprocessor and microcontroller, operation of Peripherals of controller, and be able to program a microcontroller system in assembly code and C.
- 2. Design and Develop a microcontroller based system.
- 3. Interface the system to switches, keypads, displays, A/D and D/A converters and build a microcontroller based Robot.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. "The 8051 Microcontroller Architecture, Programm ing & Applications", 2e Kenneth J. Ayala ;, Penram International, 1996 / Thomson Learning 2005
- 2. "The 8051 Microcontroller and Embedded Systems using assembly and C"-, Muhammad Ali Mazidi and Janice Gillespie Mazidi and Rollin D. McKinlay; PHI, 2006 / Pearson, 2006

- 1. "Programming and Customizing the 8051 Microcontr oller" Predko; -, TMH
- 2. Microcontrollers: Architecture, Programming, Interfacing and System Design", Raj Kamal, "Pearson Education, 2005

- 3. "Microcontrollers- Theory and Applications", Aja y V.Deshmukh; TMH,2005
- 4. "Microcontroller and its applications", Dr.Raman i Kalpathi and Ganesh Raja; Sanguine Technical publishers, Bangalore-2005.

MICRO & SMART SYSTEMS TECHNOLOGY LABORATORY

[As per Choice Based Credit System (CBCS) scheme]

SEMESTER - V

Subject Code	15MTL58	IA Marks	20
Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	-	Exam Hours	03

CREDITS - 02

Course objectives: Students will be able to

- Analyse the behavior of Mechanical Components for various kinds of loads.
- Analyse the behavior of Pressure Sensor for various kinds of Pressures applied.

Laboratory Experiments:	Revised Bloom's Taxonomy
	(RBT)Level

PART – A

- 1. Static structural analysis
- a) 2 D Mechanical Components.
- b) 3 D Mechanical Components.
- 2. Piezoelectric analysis: cantilever beam

PART - B

- 1. Pressure sensor experiment
 - a) Raw pressure sensor
 - b) compensated pressure sensor

Course outcomes: On the completion of the course the student will:

- Understand, Analyze & gain ability to choose Materials for desired applications.
- Understand, Analyze & gain ability to choose Sensors for desired applications.

Graduate Attributes (as per NBA):		
Scheme of Examinations:		
Scheme of Examinations.		
One Question from Part A:	40 Marks	
One Question from Part B:	30 Marks	
Viva-Voice :	10 Marks	
D TOTAL :	80 Marks	

DESIGN OF MACHINE ELEMENTS [As per Choice Based Credit System (CBCS) scheme] SEMESTER - V **Subject Code** 15MT51 **IA Marks 20 Exam Marks** 80 **Number of Lecture** Hours/Week 05 **Exam Hours** 03 60 **Total Number of Lecture Hours**

CREDITS - 04

Course Objective: Students will be able to

- 1. gain knowledge of theories of failures, stress concentration and machine elements.
- 2. understand the techniques in machine elements.
- 3. determine the parameters of machine elements subjected to various load condition.
- 4. design of various machine elements

Modules	Hours Teaching		ed Bloom's nomy(RBT)
Module -1	•		
Module - 1 Introduction: Machine design, classification of machine design consideration, Tri axial stresses, Stress Tensor. Codes and Standards Safety, design procedure for simple and combined stresses (No Mattroduction to Stress Concentration, Stress concentration Factor and (Simple problems). Introduction to Theories of failure: Maximum Normal Stress Theory, Shear Stress Theory, Distortion Energy Theory.	. Factor of Numerical). its effects	12 Hours	
Module -2			
Design of Keys, Couplings and Joints: Keys: Types of keys, Design of Couplings: Flange coupling, Bush and Pin type coupling. cotter and knuckle joint. Power Screws: Stresses in Power Screws, Efficiency and Self-locking.	Design of	12 Hours	
Power Screws, Stresses in Fower Screws, Efficiency and Sen-locking, Power Screw, Design of Screw Jack.	, Design of		
Module -3	<u> </u>		
Design of Shafts : Design for strength and Rigidity with Steady loading BIS codes for Power Transmission shafting, Shafts under Fluctuating combined loads.	,, 1181112 &	12 Hours	

Module -4		
Design of Spur Gears: Beam strength of spur gear, Stresses in gear teeth (Lewis equation), dynamic tooth load, design for wear	12 Hours	
Design of helical gears: Beam strength of helical gear, Stresses in gear teeth (Lewis equation), dynamic tooth load, design for wear.		
Module -5	1	
Design of Journal Bearings: Types of bearings, bearing characteristic number, coefficient of friction, minimum oil film thickness, Heat Generated, Heat dissipated, Bearing Materials.	12 Hours	
Design of springs : Types of springs - stresses in Helical coil springs of circular cross sections. Tension and compression springs only.		

- 1. have knowledge of theories of failures, stress concentration, power screws, shafts, keys, couplings, gears, bearings and springs.
- 2. understand the technique of theories of failure, stress concentration, fatigue strength etc.
- 3. calculate the stresses, parameters of machine elements subjected to various loads also make proper assumptions with respect to material, FOS for various machine components.
- 4. design machine elements like power screws, shafts, keys, couplings, gears, bearings ad springs

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

TEXT BOOKS:

- 1. Mechanical Engineering Design, Joseph E Shigley and Charles R. Mischke. McGraw Hill International edition, 6thEdition 2009.
- 2. Design of Machine Elements, V.B. Bhandari, Tata McGrawHill Publishing Company Ltd., New Delhi, 3rdEdition 2010.
- 3. Machine Design, by Dr. P C Sharma and Dr. D K Aggarwal, S. K. Kataria& Sons, 11th Edition 2009.

DESIGN DATA HANDBOOK:

- 1. Design Data Hand Book, K. Lingaiah, McGraw Hill, 2ndEdition.
- 2. Data Hand Book, K. Mahadevan and Balaveera Reddy, CBSPublication.
- 3. Design Data Hand Book, H.G. Patil, I. K. International Publisher, 2010.

- 1. Machine Design, Robert L. Norton, Pearson Education Asia, 2001.
- 2. Design of Machine Elements, M. F. Spotts, T. E. Shoup, L. E. Hornberger, S. R. Jayram and C. V. Venkatesh, Pearson Education, 2006.
- 3. Machine Design, Hall, Holowenko, Laughlin (Schaum's Outlines series) Adapted by S.K. Somani, Tata McGraw Hill Publishing Company Ltd., New Delhi, Special Indian Edition, 2008.

Virtual Instrumentation

[As per Choice Based Credit System (CBCS) scheme] SEMESTER – V

Subject Code	15MT52	IA Marks	20
-		Exam Marks	80
Number of Lecture			
Hours/Week	04		
		Exam Hours	03
Total Number of	50		
Lecture Hours			

CREDITS - 04

Course objectives: Students will be able to

- gain knowledge to learn the concepts of developing basic skills necessary for importance Virtual Instrumentation and Lab View
- understand the basic programming concepts and various Operation using DAQ Devices used in Virtual Instrumentation and Lab View.
- diagnosis the problem related types of I/O module, Data Acquisition System and Communication Networks (Bus Systems) using Standard Protocol

Modules Hours Teaching		Revised Bloom's Taxonomy(RBT) Level
Module -1		
CONCEPT OF VIRTUAL INSTRUMENTATION — Historical persponded of VI — Advantages of VI — Define VI — Block diagram & Architectu — Data flow techniques — Graphical programming in data flow — Comwith conventional programming.PC based data acquisition — Typical of DAQ card — Resolution and sampling frequency — Multiplexing of analomatic — Single-ended and differential inputs — Different strategies for same multi-channel analog inputs. Concept of universal DAQ card — Module -2 DATA ACQUISITION BASICS: Introduction to data acquisition on PC, S fundamentals, Input/Output techniques and buses. ADC, DAC, Dig	ure of VI nparison on board og inputs npling of	Hours
counters and timers, DMA, Software and hardware installation, Cali Resolution, Data acquisition interface requirements.		
Module -3		
GRAPHICAL PROGRAMMING ENVIRONMENT IN VI Concepts of graphical programming – Lab-view software – Concept of sub VI ,Loops(While Loop and For Loop) , Structures(Case, Formula no sequence structures) Arrays Operations, Strings Operations, and Examples on each.	VIs and ode, and	Hours
Module -4		<u>.</u>

CLUSTER OF INSTRUMENTS IN VI SYSTEM	10 Hours			
Interfacing of external instruments to a PC – RS232, RS 422, RS 485 and USB standards - IEEE				
488 standard – ISO-OSI model for serial bus – Introduction to bus protocols of MOD bus and				
CAN bus.				
Module -5				
USE OF ANALYSIS TOOLS AND APPLICATION OF VI Fourier transform - Power	10 Hours			
spectrum - Correlation – Windowing and filtering tools – Simple temperature indicator				
- ON/OFF controller - P-I-D controller - CRO emulation - Simulation of a simple				
second order system – Generation of HTML page.				

- 1. have a knowledge of Virtual Instrumentation and Lab View domain on various I/O Module , Sensor, DAQ Devices ,Communication and Measurement System
- 2. understanding the basic programming concepts and various logical Instructions, DAQ Operation used in Virtual Instrumentation and Lab View .
- 3. determine the extent and nature of electronic circuitry in Virtual Instrumentation and Lab View including Signal monitoring and control circuits for Communication and Interfacing.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. "Virtual Instrumentation using LabVIEW" Jovitha Jerome, PHI publication
- 2."Virtual Instrumentation, LABVIEW", Sanjay Gupta, TMH, NewDelhi, 2003

- 1. "PC Interfacing for Data Acquisition and Process Control", S. Gupta and JP Gupta Instrument Society of America, 1994 and JP Gupta Instrument Society of America, 1994 and JP Gupta Instrument Society of America, 1994 and 1995 and 1995 are sometiment of the Society of America, 1994 and 1995 are sometiment of the Society of America, 1994 and 1995 are sometiment of the Society of America, 1994 and 1995 are sometiment of the Society of America, 1994 and 1995 are sometiment of the Society of America, 1994 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 are sometiment of the Society of America, 1995 and 1995 are sometiment of the Society of America, 1995 are sometiment of
- 2. Kevin James, PC Interfacing and Data Acquisition: Techniques for Measurement, Instrumentation and Control, Newnes, 2000.

		DRAULICS AND PNEUM d Credit System (CBCS) sci		STER – V	
Subject Code	15MT53	IA Marks		20	
Number of Lecture Hours/Week	04	Exam Marks		80	
Total Number of Lecture Hours	50	Exam Hours	03		
Course objectives	: Students will be able	CREDITS – 04			
2. understand	ing the working princ	raulic and pneumatic systen iples of hydraulics and pneumatic systems	umatics compo	nents Revised Bloom's	
			Teaching	Taxonomy(RBT) Level	
Module -1					
limitations, applica problems on Pasca The source of Hy oof positive displace pumps, Piston pum	ations, Pascal's law, st l's law. draulic Power: Pum ement pumps, constru nps, fixed and variable	ructure of hydraulic system, ructure of hydraulic control ps Classification of pumps, action and working of Gear per displacement pumps, Pum	Pumping theopumps, Vane		
characteristics, pur Module -2	mp Selection factors,	problems on pumps.			
Hydraulic Actuat Linear Hydraulic A Mechanics of Hyd special types of cy rotary actuators su Torque, Power and	Actuators [cylinders], raulic Cylinder Loadi linders, problems on c ch as gear, vane, pisto	ssification cylinder and hyd single and double acting cy ng, mounting arrangements cylinders, construction and con on motors, Hydraulic Motor c Motor Performance, proba- dinders and motors).	linder, , cushioning, working of Theoretical		
_	-	stems: Classification of conepresentation, constructiona			

poppet, sliding spool, rotary type valves solenoid and pilot operated DCV, shuttle	
valve, check valves, Pressure control valves - types, direct operated types and pilot	
operated types. Flow Control Valves -compensated and non-compensated FCV,	
needle valve, temperature compensated, pressure compensated, pressure and	
temperature compensated FCV, symbolic representation.	
Module -3	
Hydraulic Circuit Design And Analysis: Control of Single and Double -Acting	10 Hours
Hydraulic Cylinder, Regenerative circuit, Pump Unloading Circuit, Double Pump	10 Hours
Hydraulic System, Counter balance Valve Application, Hydraulic Cylinder	
Sequencing Circuits, Automatic cylinder reciprocating system, Locked Cylinder	
using Pilot check Valve, Cylinder synchronizing circuit using different methods,	
factors affecting synchronization, Speed Control of Hydraulic Cylinder, Speed	
Control of Hydraulic Motors, Safety circuit, Accumulators, types, construction and	
applications with circuits.	
approutions with enemis.	
Maintenance of Hydraulic System: Hydraulic Oils - Desirable properties, general	
type of Fluids, Sealing Devices, Reservoir System, Filters and Strainers, wear of	
Moving Parts due to solid - particle Contamination, temperature control (heat	
exchangers), Pressure switches, trouble shooting.	
Module -4	
Introduction to Pneumatic Control: Definition of pneumatic system, advantages,	10 Hours
limitations, applications, Choice of working medium. Characteristic of compressed	
air. Structure of Pneumatic control System, fluid conditioners and FRL unit.	
Pneumatic Actuators: Linear cylinder - Types, Conventional type of cylinder-	
working, End position cushioning, seals, mounting arrangements- Applications.	
Rod - Less cylinders types, working, advantages, Rotary cylinders- types	
construction and application, symbols.	
Pneumatic Control Valves: DCV such as poppet, spool, suspended seat type slide	
valve, pressure control valves, flow control valves, types and construction, use of	
memory valve, Quick exhaust valve, time delay valve, shuttle valve, twin pressure	
valve, symbols. Simple Pneumatic Control: Direct and indirect actuation pneumatic	
cylinders, speed control of cylinders - supply air throttling and Exhaust air	
throttling and Exhaust air throttling.	
Module -5	1
Signal Processing Elements: Use of Logic gates - OR and AND gates in	
Signal Flocessing Elements. Osc of Logic gates - Ok and AND gates in	10 Hours
pneumatic applications. Practical Examples involving the use of logic gates,	10 Hours
	10 Hours
pneumatic applications. Practical Examples involving the use of logic gates,	10 Hours
pneumatic applications. Practical Examples involving the use of logic gates, Pressure dependant controls- types - construction - practical applications, Time	10 Hours
pneumatic applications. Practical Examples involving the use of logic gates, Pressure dependant controls- types - construction - practical applications, Time dependent controls principle, Construction, practical applications.	10 Hours

reversing valves).

Electro- Pneumatic Control: Principles - signal input and output, pilot assisted solenoid control of directional control valves, Use of relay and contactors. Control circuitry for simple signal cylinder application.

Course outcomes: On completion of the course the student will

- 1. have knowledge of hydraulic and pneumatic system and its components.
- 2. understand the working principle of various hydraulic and pneumatic components .
- 3. apply working principles of Hydraulic and Pneumatic Systems for various applications. determine cause for hydraulic and pneumatic system break down and performance of hydraulic pumps, motors.

Graduate Attributes (as per NBA):

Question paper pattern:

Text Books:

- 1. "Fluid Power with Applications", Anthony Esposito, Sixth edition, Pearson Education, Inc, 2000.
- 2. 'Pneumatics and Hydraulics', Andrew Parr, Jaico Publishing Co

- 1. 'Oil Hydraulic systems', Principles and Maintenance S. R. Majurr, Tata McGraw Hill Publishing Company Ltd. 2001
- 2. 'Industrial Hydraulics', Pippenger, Hicks" McGraw Hill, New York
- 3. 'Hydraulic & Pneumatic Power for Production', HarryL. Stewart
- 4. 'Pneumatic Systems', S. R. Majumdar, Tata McGraw Hill Publish 1995
- 5. 'Hydraulic & Pneumatics' CMTI Data Book

MICRO & SMART SYTEMS TECHNOLOGY [As per Choice Based Credit System (CBCS) scheme] SEMESTER - V **Subject Code** 15MT54 **IA Marks** 20 **Exam Marks** 80 **Number of Lecture** Hours/Week 04 **Exam Hours** 03 50 **Total Number of Lecture Hours CREDITS - 04** Course Objectives: Students will be able to 1. gain knowledge of Smart Materials, Sensors & Actuators, Microsystems. 2. understand the Operation of Smart Devices & Systems, Electronic Circuits & Control for MEMS, Methodology of Micro-manufacturing. Modules Hours **Revised Bloom's** Teaching Taxonomy(RBT) Level Module -1 Introduction to Micro and Smart systems: Miniaturization, Microsystems versus 10 Hours MEMS, Micro-fabrication, Smart Materials, Structures & Systems, Integrated Microsystems, Application of Smart Materials & Microsystems. Module -2 Micro and Smart Devices and Systems: Principles and Materials: Definitions 10 Hours and salient features of sensors, actuators, and systems. Sensors: silicon capacitive piezoresistive pressure sensor, Portable accelerometer. analyzer. conductometric gas sensor. Actuators: Micromirror Array for Video Projection, Piezo-electric based inkjet print head, electrostatic comb-drive, Magnetic microrelay. Module -3 Micromachining Technologies: Silicon as a Material for Micromachining, Silicon 10 Hours wafer preparation, thin-film deposition techniques, Lithography, Etching, Silicon micromachining:surface micromachining bulk micromachining. Specialized Materials for Microsystems. Module -4 Electronics Circuits for Micro and Smart Systems. Semiconductor devices: 10 Hours Diode, Schottky diode, Tunnel diode, BJT , MOSFET, CMOS circuits , Electronics

Amplifiers ,Op-Amp based circuits ,Practical Signal Conditioning Circuits for

Microsystems. Circuits for Conditioning Sensed Signals.

Module -5			
Implementation of Controllers for MEMS & Case Studies of Integrated Microsystems. Design Methodology, PID controller, Circuit Implementation, Digital controller, Microcontroller & PLC. Case Studies of Integrated Microsystems: BEL pressure sensor, design considerations, performance parameters, practical implementations, design of electronics circuits, Integration of pressure Sensor and Smart Structure in vibration control.			

- 1. have knowledge of Smart Materials, Sensors & Actuators , Microsystems.
- 2. understand the Working Methodology of Smart Devices & Systems, Electronics Circuits & Control for MEMS, Methodology of Micro-manufacturing.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1.Micro and Smart Systems: G.K.Ananthasuresh, K.J.Vinoy, S.Gopalakrishnan, K.N.Bhat, V.K.Aatre, Wiley India 2010.

- 1. Design and Development Methodogies, Smart Material Systems and MEMS: V. Varadan, K. J. Vinoy, S. Goplakrishnan, Wiley.
- 2. MEMS- Nitaigour Premchand Mahalik, TMH 2007.
- 3. MEMS & Microsystems: Design and Manufacture, Tai-Ran Hsu, Tata Mc-Graw-Hill.

WIRELESS NETWORKS AND COMMUNICATION [As per Choice Based Credit System (CBCS) scheme] SEMESTER - V **Subject Code** 15MT551 20 **IA Marks Exam Marks** 80 **Number of Lecture** Hours/Week 03 **Exam Hours** 03 **Total Number of** 40 **Lecture Hours** CREDITS - 03 Course Objective: Students will be able to 1. gain knowledge of the fundamental concepts of wireless communication and networks. 2. understand the operation of modern network architectures from a design and performance perspective. Revised Bloom's Modules Hours **Teaching** Taxonomy(RBT) Level Module -1 **Review of Fundamentals of Wireless Communication and Networks:** 8 Hours Wireless Communications, Wireless Communication channel specifications, Wireless Communication problems, wireless networks, Switching technology, wireless network issues and standards. Module -2 Wireless body area networks 8 Hours Properties, Network Architecture, components, technologies, design issues protocols and applications. Wireless personal area networks Components, Requirements, Technologies and Protocols, Bluetooth & Zigbee. Module -3 **Wireless Modulation** 8 Hours Wireless modulation techniques and hardware, characteristics of air interface, path loss models, wireless coding techniques, Digital modulation techniques, OFDM, UWB radio techniques, Diversity techniques, GSM hardware.

Module -4

WLAN architecture, Components, Requirement, WLAN protocols, Applications WMAN architecture, components, Requirements, WMAN protocols, Application

Wireless LAN, WMAN, WWAN

8 Hours

WWAN architecture, components, requirements, WWAN protocols, Application.		
Module - 5	•	
Wireless Adhoc networks	8 Hours	
Mobile adhoc networks, Sensor networks, Mesh networks, VANETs.		

- 1. have knowledge of fundamental concepts of wireless communication and networks.
- 2. understand the Working of modern network architectures from a design and performance perspective.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

TEXT BOOKS:

- 1. SS Manvi, MS Kakkasageri, "Wireless and Mobile Network concepts and protocols". Willy, first edition. 2010.
- 2. Wireless Telecom systems and networks, Mullet: Thomson Learning 2006.

REFERNCE BOOKS:

- 1. P Kavesh, Krishnamurthy, "Principals of wireless networks: A unified approach', PHI, 2006.
- 2. Iti Saha Mishra, "Wireless communication and networks 3G and beyond", MGH, 2009.
- 3. Mullet, "Introduction to wireless telecommunication systems and networks", cengage, 2009.
- 4. DP Agarwal, Qing An Zeng, "Introduction to wireless and mobile systems", Cengage, 2008.
- 5. Ivan Stojmenovic, "Handbook of wireless networks and mobile computing', Willy, 2009.

OPERATIONS RESEARCH

[As per Choice Based Credit System (CBCS) scheme] ${\sf SEMESTER-V}$

Subject Code	15MT552	IA Marks	20
	10111001		-
		Exam Marks	80
Number of Lecture			
Hours/Week	03		
		Exam Hours	03
Total Number of	40		
Lecture Hours			

CREDITS - 03

Course Objective: Students will be able to

- 1. gain knowledge of basics of operation research.
- 2. understanding various techniques of operation research for solving business decision and engineering problems.
- 3. determination of optimization solutions, effective decision making, model formulation and applications.

Modules Hou Tea		Revised Bloom's Taxonomy(RBT Level
Module -1		
Introduction: Evolution of OR, definition of OR, scope of OR, application	on areas of 8	3 Hours
OR, steps (phases) in OR study, characteristics and limitations of OR, m		
in OR, linear programming (LP) problem-formulation and solution by	y graphical	
method.		
Solution Of Linear Programming Problems: The simplex method car	nonical and	
standard form of an LP problem.		
Module -2		
Transportation Problem: Formulation of transportation problem, ty	pes, initial 8	Hours
basic feasible solution using different methods, optimal solution by MOI	DI method,	
degeneracy in transportation problems, application of transportatio	n problem	
concept for maximization cases.		
Module -3		
Pert-CPM Techniques: Introduction, network construction - rules, I	Fulkerson's 8	Hours
rule for numbering the events, AON and AOA diagrams; Critical path	method to	
find the expected completion time of a project, floats; PERT for findin	g expected	
duration of an activity and project, determining the probability of co		
project, predicting the completion time of project; crashing of simple project	jects.	
Module -4		
Queuing Theory: Queuing systems and their characteristics, Pure-birth	and Pure- 8	Hours
death models (only equations), empirical queuing models - M/M/1 a	nd M/M/C	
models and their steady state performance analysis.		

Module -5		
Game Theory: Formulation of games, types, solution of games with saddle point, graphical method of solving mixed strategy games, dominance rule for	8 Hours	
solving mixed strategy games.		
Sequencing: Basic assumptions, sequencing 'n' jobs on single machine using priority rules, sequencing using Johnson's rule-'n' jobs on 2 machines, 'n' jobs		
on 3 machines, 'n' jobs on 'm' machines. Sequencing 2 jobs on 'm' machines using graphical method.		

- 1. have knowledge of linear programming, Transportation, PERT-CPM, Sequencing, Queuing Theory, and Game theory.
- 2. understanding the techniques of linear programming, Transportation, PERT-CPM, Sequencing, Queuing Theory, and Game theory for various engineering problems.
- 3. determination of optimization of solutions, effective decision making model formulation and applications that are used in solving business decision problems.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

TEXT BOOKS:

- 1. Operations Research, P K Gupta and D S Hira, Chand Publications, New Delhi 2007
- 2. Operations Research, Taha H A, Pearson Education.
- 3. Operations Research S.D. Sharma, LedarnathRamanath& Co, 002

REFERNCE BOOKS:

- 1. Operations Research, A P Verma, S K Kataria&Sons, 2008
- 2. Operations Research, Paneerselvan, PHI
- 3. Operations Research, A M Natarajan, P Balasubramani, Pearson Education, 2005
- 4. Introduction to Operations Research, Hillier and Liberman, 8th Ed., McGraw Hill
- 5. Operations Research, S. Kalavathy, Vikas Publishing House Pvt Ltd, 2002

Linear Integrated Circuits [As per Choice Based Credit System (CBCS) scheme] SEMESTER - V **Subject Code** 15MT553 **IA Marks** 20 **Exam Marks** 80 **Number of Lecture** Hours/Week 03 **Exam Hours** 03 40 **Total Number of Lecture Hours CREDITS - 03** Course objectives: Students will be able to 1. gain knowledge of Operational Amplifiers, Oscillators. 555 Timers, 2. understand the Operation of Op-Amp as Amplifiers, Oscillators. Filters, & 555 timer operation as multi vibrators. Modules Revised Bloom's **Hours Teaching** Taxonomy(RBT) Level Module -1 **Operational Amplifier Fundamentals:** Basic Op-amp circuit, 8 Hours parameters - Input and output voltage, CMRR and PSRR, offset voltages and currents, Input and output impedances, Slew rate and Frequency limitations. Module -2 Op-Amps as AC Amplifiers: Capacitor coupled voltage follower, High input impedance – Capacitor coupled voltage follower, Capacitor coupled non inverting amplifiers, High input impedance – Capacitor coupled Non 8 Hours inverting Amplifiers. **OP-Amp Applications:** Voltage sources, current Sources and current sinks, current amplifiers, instrumentation amplifier, precision rectifiers. (Text1) Module -3 **More Applications:** Limiting circuits, Clamping circuits, Peak detectors, 8 Hours Sample and hold circuits, V to I and I to V converters, Differentiating Circuit, Integrator Circuit, Phase shift oscillator, Wein bridge oscillator, Crossing

Module -4

8 Hours

detectors, inverting Schmitt trigger. (Text 1)

Bandpass Filter, Bandstop Filter. (Text 1)

Log and antilog amplifiers, Multiplier and divider. (**Text2**)

Active Filters: First order and second order active Low-pass and high pass filters,

Voltage Regulators: Introduction, Series Op-amp regulator, IC voltage regulators.

723 general purpose regulators. (Text 2)		
Module -5	•	
Phase locked loop: Basic Principles, Phase detector/comparator, VCO.	8 Hours	
DAC and ADC convertor : DAC using R-2R, ADC using Successive		
approximation.		
Other IC Application: 555 timer, Basic timer circuit, 555 timer used as astable		
and monostable multi vibrator. (Text 2)		

- 1. have knowledge of Operational Amplifiers, Oscillators. 555 Timers
- 2. understand the Operation of Op-Amp as Amplifiers, Oscillators. Filters & 555 timer operation as multi vibrators.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Operational Amplifiers and Linear IC"s", David A. Bell, 2nd edition, PHI/Pearson, 2004. ISBN 978-81-203-2359-9.
- 2. "Linear Integrated Circuits", D. Roy Choudhury and Shail B. Jain, 4th edition, Reprint 2006, New Age International ISBN 978-81-224-3098-1.

- 1. Ramakant A Gayakwad, "Op-Amps and Linear Integrated Circuits," Pearson, 4th Ed, 2015. ISBN 81-7808-501-1.
- 2. B Somanathan Nair, "Linear Integrated Circuits: Analysis, Design & Applications," Wiley India, 1st Edition, 2015.
- 3. James Cox, "Linear Electronics Circuits and Devices", Cengage Learning, Indian Edition, 2008, ISBN-13: 978-07-668-3018-7.
- 4. Data Sheet: http://www.ti.com/lit/ds/symlink/tl081.pdf.

		DRIVES AND CONTR	OLS		
		d Credit System (CBCS)		STER – V	
Subject Code	15MT554	IA Marks		20	
Number of		Exam Marks		80	
Lecture Hours/Week	03				
Total Number of Lecture Hours	40	Exam Hours		03	
		CREDITS - 03			
Course objectives	Students will be abl	e to			
		ves, Motor Power Rating ves in various Application			ds of motors.
Modules			Hours Teaching	Revised Bloom Taxonomy(RE Level	
Module -1					
Advantages of electronic Dynamics D	trical drives, fundar nulti quadrant operati	dynamics: electrical drives, choice onental torque equation, on. Components of load to	and speed torq	ue	
Module -2				<u> </u>	
determination of r	of motor for heating	g and cooling, Classes ations of time and energy qualization.		-	
control of separate control of dc sepa	ransient analysis of si ly excited dc motor. Trately excited motor, from fully controlled	ingle phases half and full Three phase half and full multi quadrant operatio ed rectifier. Chopper con	controlled rectifing of dc separate	ier ely	

Module -4

Induction motor Drives:	8 Hours	
Operation with unbalanced source voltage and single phasing, operation with		
unbalanced rotor impedances, analysis of induction motor fed from non-sinusoidal		
voltage supply, starting, braking and transient analysis. Stator voltage control,		
variable voltage frequency control voltage source inverter control, current source		
inverter control, rotor resistance control, slip power recovery		
Module 5		

Module -5

Industrial Drives:	8 Hours	
Application in steel mills, Paper mills, Cement Industry, Textile Mills, Sugar mills,		
Electric Traction(Requirements of Electric traction and suitability of series		
Motors), coal mining.		

Course outcomes: On completion of the course the student will

- 1. have knowledge of Electrical Drives, Motor Power Rating, Industrial Drives.
- 2. understand the Operation of Drives in various Applications & Performance of various kinds of motors.

Graduate Attributes (as per NBA):

Question paper pattern:

TEXT BOOKS:

- 1) Fundamentals of Electrical Drives, G.K Dubey, Narosa publishing house, 2nd Edition, 2002.
- 2) Fundamentals of Industrial Drives Sarkar B N, 2012 PHI (ISBN-978-81-203-4433-4)

REFERENCE BOOKS:

- 1) Electrical Drives, N.K De and P.K. Sen-PHI, 2009.
- 2) A First Course On Electric Drives, S.K Pillai-Wiley Eastern Ltd 1990.
- 3) Power Electronics, Devices, Circuits and Industrial Applications, V.R. Moorthi, "Oxford University Press, 2005.
- 4) Electric Motor Drives, Modeling, Analysis and Control, R. Krishnan, PHI, 2008.

Object Oriented Programming in C++ [As per Choice Based Credit System (CBCS) scheme]

SEMESTER - V

Subject Code	15MT555	IA Marks	20
-		Exam Marks	80
Number of Lecture			
Hours/Week	03		
		Exam Hours	03
Total Number of	40		
Lecture Hours			

CREDITS - 03

Course objectives: Students will be able to

- 1. gain knowledge of fundamentals of object-oriented programming, Operators in C++, Functions, Classes, Overload Operators.
- 2. understand the Syntax of C++.
- 3. develop an ability to write Programs for various applications in C++.

	Hours Feaching	Revised Bloom's Taxonomy(RBT) Level
Module -1		•
C++, AN OVERVIEW: Getting started, the C++ program, Prep Directives, The Built-In Array Data Type, Dynamic Memory Allocat Pointers, An Object – based Design, An Object-Oriented Design, An Exc based Design, An array. THE BASIC LANGUAGE: Literal Constant, Variables, Pointer Type Types, const Qualifier, Reference Types, the bool type, Enumeration type types. The vector container type.	ion and eption –	B Hours
Module -2	,	<u> </u>
OPERATORS: Arithmetic Operators, Equality, Relational and Logical of Assignment operators, Increment and Decrement operator, The conformation Operator, Bitwise operator, bitset operations. Statements: if, switch, for while, break, goto, continue statements.	nditional	3 Hours
Module -3		1
FUNCTIONS: Prototype, Argument passing, Recursion and linear function. EXCEPTION HANDLING: Throwing an Exception, Catching an ex Exception Specification and Exceptions and Design Issues.		3 Hours
Module -4		
CLASSES: Definition, Class Objects, Class Initialization, Class constructions destructor, Class Object Arrays and Vectors.	tor, The 8	Hours
Module -5	•	•

Overload Operators, Operators ++ and, Operators new and delete.	8 Hours	
Multiple Inheritances, public, private & protected inheritance, Class scope		
under Inheritance.		

- 1. have knowledge of fundamentals of object-oriented programming, Operators in C++, Functions ,Classes, Overload Operators.
- 2. understand the Syntax of C++.
- 3. write Programs for various applications in C++.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

TEXT BOOK:

- 1. C++ Primer, S. B. Lippman & J. Lajoie, 3rd Edition, Addison Wesley, 2000.
- 2. Object Oriented Programming with C++, Balaguruswamy, Tata McGraw-Hill Education, 2008 C++

REFERENCE BOOKS:

- 1. Introduction to Object Oriented Programming & C++, Yashawant P Kanetkar, BPB Publication, 2003
- 2. C++ Program Design: An Introduction to Programming and Object- Oriented Design. Cohoon and Davidson, 3rd Edn. TMH publication. 2004.
- 3. Object Oriented Programming using C++, R. Lafore, Galgotia Publications, 2004.

	[As per Choice Base	Mechatronics Enginee d Credit System (CBCS)		STER – V
Subject Code	15MT561	IA Marks		20
Number of Lecture Hours/Week	03	Exam Marks		80
Total Number of Lecture Hours	40	Exam Hours		03
		CREDITS – 03		
sensors 2. understandi Modules	ing the working of M	echatronics components,	signal condition	ing & sensors Revised Bloom's
Modules			Teaching	Taxonomy(RBT) Level
			L	
Module -1				
Introduction: Defi &Simulation of Ph functioning, measu Transducers: Pneur	ysical systems Overvarement systems. Con matic and Hydraulic S	on to Mechatronics Systemiew of Mechatronics Protected Systems, simple Consystems, Mechanical Actoriacing and Hardware constructions	ducts and their trollers. Study o uation System,	8 Hours
Introduction: Defi &Simulation of Ph functioning, measu Transducers: Pneur Electrical Actual S	ysical systems Overvarement systems. Con matic and Hydraulic S	riew of Mechatronics Pro- trol Systems, simple Con Systems, Mechanical Act	ducts and their trollers. Study o uation System,	0 0 10
Introduction: Defi &Simulation of Ph functioning, measu Transducers: Pneur Electrical Actual S Mechatronics. Module -2 Electrical Actuation switches, solenoids Mathematical mode	ysical systems Overvarement systems. Con matic and Hydraulic Systems, Real time into on Systems: Electrical Systems, DC & AC motors, Sels: mechanical systems	riew of Mechatronics Pro- trol Systems, simple Con Systems, Mechanical Act	ducts and their strollers. Study of the stud	f
Introduction: Defi &Simulation of Ph functioning, measu Transducers: Pneur Electrical Actual S Mechatronics. Module -2 Electrical Actuation switches, solenoids Mathematical mode building blocks, electroduced	ysical systems Overvarement systems. Con matic and Hydraulic Systems, Real time into on Systems: Electrical Systems, DC & AC motors, Sels: mechanical systems ectromechanical systems.	riew of Mechatronics Pro- trol Systems, simple Con Systems, Mechanical Act erfacing and Hardware co al systems, Mechanical systems, Mechanical systems, building blocks, electronical systems.	ducts and their strollers. Study o uation System, omponents for witches, Solid st Models: ical system systems.	ate 8 Hours

Sensors Fundamentals: Basic sensor technology, Sensor Systems, Sensor	8 Hours	
Characteristics, System Characteristics, Instrument Selection, Data acquisition,		
Installation. process of developing sensors, sensor arrays smart sensors, Industrial		
sensor networking basic Elements.		
Module -5		
Types of sensors and applications, over view: Process of developing sensors,	8 Hours	
trends in sensor Technology and IC Sensors, sensor array's and multi sensor		
systems, smart sensors, sensor networks in R & D, sensors and networks, industrial		
network and automation.		

- 1. have knowledge of Mechatronics system, transducers, actuators, signal conditioning, sensors
- 2. understand the working of Mechatronics components, signal conditioning & sensors

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. W. Bolton, "Mechatronics" Addison Wesley Longman Publication, 1999
- 2. HSU "MEMS and Microsystems design and manufacture"- Tata McGraw-Hill Education, 200
- 3. wireless sensor network:a networking perspective by jun abas jamalipur. john wiley 2009

- 1. **Sensor Technology Hand Book** By Jon's Wilson.
- 2. Kamm, "Understanding Electro-Mechanical Engineering an Introduction to Mechatronics"- IEEE Press, 1 edition ,1996
- 3. Shetty and Kolk "Mechatronics System Design"- Cengage Learning, 2010
- 4. Mahalik "Mechatronics"- Tata McGraw-Hill Education, 2003
- 5. HMT "Mechatronics"- Tata McGraw-Hill Education, 1998

Automation in Manufacturing [As per Choice Based Credit System (CBCS) scheme] SEMESTER - V **Subject Code** 15MT562 **IA Marks** 20 **Exam Marks** 80 **Number of Lecture** Hours/Week 03 **Exam Hours** 03 40 **Total Number of Lecture Hours** CREDITS - 03 **COURSE OBJECTIVES**: Students will be able to 1. gain knowledge of fundamental concepts of automation in manufacturing. 2. understand the techniques of automation in manufacturing for industry operations. Modules Hours Revised Bloom's **Teaching** Taxonomy(RBT) Level Module -1 Introduction: Production System Facilities, Manufacturing Support systems, 8 Hours Automation in Production systems, Automation principles & Strategies. Manufacturing Operations: Manufacturing Operations, Product/Production Relationship, Production concepts and Mathematical Models & Costs of Manufacturing Operations. Module -2 8 Hours Industrial Control System: Basic Elements of an Automated System, Advanced Automation Functions & Levels of Automation, Continuous versus Discrete control, Computer Process control, Forms of Computer Process Control. Quality Control Systems: Traditional and Modern Quality Control Methods, Taguchi Methods in Quality Engineering. Introduction to SQC Tools. Module -3 8 Hours Automated Manufacturing Systems: Components of a Manufacturing systems, Classification of Manufacturing Systems, overview of Classification Scheme, Single Station Manned Workstations and Single Station Automated Cells. Manufacturing Support System: Process Planning, Computer Aided Process Planning, Concurrent

Module -4

8 Hours

Engineering & Design for Manufacturing, Advanced Manufacturing Planning, Just-in Time

Inspection Technologies: Automated Inspection, Coordinate Measuring Machines Construction,

Production System, Basic concepts of lean and Agile manufacturing.

operation & Programming, Software, Application & Benefits, Flexible Inspection System,			
Inspection Probes on Machine Tools, Machine Vision, Optical Inspection Techniques & Non-			
contact Non-optical Inspection Technologies.			
Module - 5			
Group Technology & Flexible Manufacturing Systems: Part Families, Parts Classification and	8 Hours		
coding, Production Flow Analysis, Cellular Manufacturing, Flexible Manufacturing Systems: What			
is an FMS, FMS Components, FMS Applications & Benefits, and FMS Planning &Implementation			
Issues.			

- 1. have knowledge of fundamental concepts of automated flow lines, traditional and modern quality control methods, manufacturing supporting system, AMS, Inspection Technologies, group technologies, FMS
- 2. understand various automated flow lines, assembly systems and line balancing methods, importance of automated material handling and storage systems and the importance of adaptive control systems, automated inspection systems.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

TEXT BOOKS:

- 1. Automation, Production Systems and Computer Integrated Manufacturing, M. P. Groover, Pearson education. Third Edition, 2008
- 2. Principles of CIM, Vajpayee, PHI.

REFERENCE BOOKS:

- 1. Anatomy of Automation, Amber G.H & P. S. Amber, PrenticeHall.
- 2. Performance Modeling of Automated Manufacturing Systems, Viswanandham, PHI
- 3. Computer Based Industrial Control, Krishna Kant, EEE-PHI

VIRTUAL INSTRUMENTATION LAB

[As per Choice Based Credit System (CBCS) scheme]

SEMESTER - V

Subject Code	15MTL57	IA Marks	20
Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	-	Exam Hours	03

CREDITS - 02

Course objectives: Students will be able to

- Understanding Virtual Instrument concepts and data acquisition operation
- Creating Virtual Instruments for practical works

Laboratory Experiments:	Revised Bloom's Taxonomy			
	(RBT)Level			

PART -A

- 1. Creating Virtual Instrumentation for simple applications- Invert The State Of Boolean Indicator Twice A See Until Program Is Stopped By User.
- 2. Programming exercises for loops in virtual instrumentation-Continuous Monitoring of Temperature (Generated using Random no 0<t<100). for every 250 ms.
- 3. Programming exercises for graphs- **Display Random Number Into 3 different CHARTS** (STRIP, SLOPE,SWEEP) and understand the difference between these in the UI.
- 4.Programming Exercises on case and sequence structures:-**Design the simple Calculator**, making use of the inherent GUI present in the virtual instrumentation software.
- 5.Programming Exercises on Arrays— Take a 2D array input from the user and perform various array(and matrix) manipulations on it.
- 6. Programming Exercises on File Input output System Read and write from ASCII and TDMS files.

PART-B

- 1. Real time temperature acquisition and continuous monitoring using Virtual Instrumentation.
- 2. Developing voltmeter using DAQ cards Acquiring a voltage and displaying it on a 'meter' indicator on the UI, thus designing a voltmeter
- 3. Developing Signal Generator using DAQ Card Using analog output; amplitude, shape and frequency controlled by user
- 4. Data acquisition through Virtual Instrumentation Read voltage and current of the 50 Hz supply to compute power and power factor
- 5.Design and Development of Filter Analysis using DAQ card Acquire audio and filter out bands using different filters and compare effects
- 6.Real time sequential control of any batch process Water level control or Temperature control

Course outcomes: On the completion of the course the student will:

- understand, design and develop data acquisition systems for Various Sensor using DAQ Cards.
- analyze the importance & applications of LabVIEW in real time Environment.

Graduate Attributes (as per NBA):

Scheme of Examination:

PART A- 35 MARKS **PART-B 35 MARKS** Viva- Voice: 10 Marks

Total: 80 Marks

	POW	ER ELECTRONICS LABORA	TORY
	[As per Choice Ba	sed Credit System (CBCS) scheme	e] SEMESTER – VI
Subject Code	15MTL68	IA Marks	20
		Exam Marks	80
Hours/Week	03		
Total Number of		Exam Hours	03
Lecture Hours	40		
	1	CREDITS – 02	

Course objectives: Students will be able to

- 1) verify the characteristics of different power electronic devices.
- 2) understand the usage of power devices to control the operation of electronic systems.

Laboratory Experiments:	Revised Bloom's Taxonomy
	(RBT)Level

LIST OF EXPERIMENTS

- 1. Static characteristics of SCR and DIAC.
- 2. Static characteristics of MOSFET and IGBT.
- 3. Controlled HWR and FWR using RC triggering circuit.
- 4. SCR turn off using i) LC circuit and ii) Auxiliary Commutation
- 5. SCR turn-on circuit using synchronized UJT relaxation oscillator.
- 6. SCR Digital triggering circuit for a single-phase controlled rectifier
- 7. Single-phase full-wave rectifier with R and R-L loads.
- 8. A.C. voltage controller using TRIAC and DIAC combination connected to R and R-L loads.
- 9. Speed control of a separately excited D.C motor using an IGBT or MOSFET chopper.
- 10. MOSFET OR IGBT based single-phase full-bridge inverter connected to R load.

Course outcomes:

On the completion of the course students will

- 1. understand and verify the characteristics of different power electronic devices .
- 2. use the power devices to control the operation of electronic systems.

Graduate Attributes (as per NBA):

Scheme of Examination:

Experiment: 70 Marks
Viva-Voice: 10 Marks
Total: 80 Marks

	PLC AND SCADA LABORATORY				
[As per Choice Based Credit System (CBCS) scheme] SEMESTER – VI					
Subject Code 15MTL67 IA Marks 20					
		Exam Marks	80		
Hours/Week	03				
Total Number of		Exam Hours	03		
Lecture Hours	40				
	CREDITS – 02				

Course objectives: Students will be able to

- 1. Analyse the logic Program on SCADA and PLC Interface
- 2. Design various applications with programmable logic controllers using relay ladder logic.

Laboratory Experiments:	Revised Bloom's Taxonomy
	(RBT)Level

LIST OF EXPERIMENTS

- 1. Study of various logic Execution in ladder diagram.
- 2. Interfacing of Lamp&button with PLC for ON&OFF Operation. Verify all logic gates.
- 3. PLC based thermal ON/OFF Controller.
- 4. Develop ladder logic to develop MUX and DE-MUX
- 5. Combination of counter &timer for lamp ON/OFF Operation.
- 6. Study& implement ON delay timer in PLC
- 7. Study& implement OFF delay timer in PLC
- 8. To study&implement of counter in PLCprogramming.(counter-up)
- 9. To study&implement of counter in PLCprogramming.(counter-down)
- 10. PLC based temperature sensing using RTD
- 11. Parameter reading of PLC in SCADA
- 12. Temperature sensing using SCADA

Course outcomes: On completion of the course the student will:

CO 1: Analyze the Importance & Applications of PLC and SCADA in real time Environment.

CO 2: Design and Develop PLC and SCADA Modules for Various Sensor Technologies.

Graduate Attributes (as per NBA):

Scheme of Examination:

Experiment: 70 Marks
Viva- Voice: 10 Marks
Total: 80 Marks

[/	As per Choice B	Power Elect ased Credit System (Cl		MESTER – VI	
Subject Code	15MT63	IA Marks		20	
Number of Lecture Hours/Week	04	Exam Marks		80	
Total Number of Lecture Hours	50	Exam Hours		03	
components. 2. understand the link	edge of variou k between effici	s conversion techniquent usage of power and terters for different app	conservation of e	energy resources	
3. use various power		odules	ireations in mouse	Hours Teaching	Revised Bloom's Taxonomy(RBT) Level
Electronics, Power	semiconductor of cs circuits, Pe	ctor Devices: Applic devices, Control Char- ripheral effects. Pow	acteristics, Types er MOSFETs –		

Module -2					
Isolation of gate and	l base drives,	Simple de	sign of ga	te and base drive	es.
U	, 0	,	,		

Thyristors: Introduction, characteristics, Two Transistor Model. Turn-on	10 Hours	
and turn-off, di/dt and dv/dt protection, Thyristor types, Thyristors firing		
circuits, Simple design of firing circuits using UJT.		
Commutation Techniques: Introduction. Natural Communication, Forced		
commutation: self commutation, impulse commutation, resonant pulse		
commutation and complementary commutations.		

Module -3

AC Voltage Controllers: Introduction. Principle of ON-OFF and phase
control. Single-phase bidirectional controllers with resistive and inductive
loads. Controlled Rectifiers: Introduction. Principle of phase controlled
converter operation. Single phase semi-converters. Full converters. Three-
phase half-wave converters. Three-phase full-wave converters.

10 Hours

Module -4

DC Choppers: Introduction. Principle of step-down and step-up chopper with R-L load. Performance parameters. Choppers classification. Analysis of impulse commutated thyristor chopper (only qualitative analysis)	
Module -5	
Inverters: Introduction, Principle of operation. Performance parameters.	10 Hours
Single-phase bridge inverters. Three phase inverters. Voltage control of	
single-phase Inverters single pulse width, multiple pulse width, and	
sinusoidal pulse width modulation.	

Course outcomes: On completion of the course student will:

CO1: have knowledge of power semiconductor devices, thyristors, AC voltage controllers, choppers and inverters.

CO2: understand the characteristics and working principle of thyristors, AC voltage controllers, choppers and inverters.

CO3: apply control techniques to meet desired switching objectives.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module

Text Books:

1. "Power electronics", m h. Rashid 2nd edition, p. H.i/pearson, new delhi, 2002.

- 1. "Power Electronics converters, Application and Design", Net Mohan, Tore M. Undeland, and William P. Robins, Third Edition, John Wiley and Sons.
- **2.** "Thyristorised Power Controllers", G. K. Dubey, S. R. Doradla, A. Joshi and R M K. Sinha, New Age International Publishers.
- 3. "Power Electronics", M. D. Singh and Khanchandani K.B. T.M.H., 2001.
- 4. "Power Electronics", Cyril Lander, 3rd Edition, McGraw-Hill.
- 5. "Power Electronics: Principles and Applications", J.M. Jacob, Thomson-VikasPublicaions.
- **6.** "Power Electronics: A Simplified Approach", R.S. Ananda Murthy and V. Nattarasu, Sanguine Technical Publisher.

Process Instrumentation [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VI Subject Code 15MT662 20 IA Marks Exam Marks 80 Number of Lecture Hours/Week 03 Exam Hours 03 Total Number of 40 Lecture Hours **CREDITS - 03 Course objectives:** Students will be able to Gain the Knowledge of basic principles of transducers systems. Understand the significant material on important specific areas such as pressure, temperature, measurement, Heat-flux sensors, flow meters etc. • Use the Instrumentation & Controls for various industrial applications. Modules Hours RevisedBloom's Teaching Taxonomy(RBT) Level Module -1 Functional Generalized Configuration, **Description** Performance 8 Hours Characteristics Of Measuring Instruments: Functional elements of an instrument: analog & digital modes of operation: null & deflection methods: I/O configuration of measuring instruments & instrument system- methods of correction for interfering & modifying inputs. Measurement Of Displacement: Principle of measurement of displacement, resistive potentiometers, variable inductance & variable reluctance pickups, LVDT, capacitance pickup. Module -2 Measurement Of Force, Torque & Shaft Power: Principle of measurement of 8 Hours Force, Torque, Shaft power standards and calibration: basic methods of force measurement; characteristics of elastic force transducer- Bonded strain gauge, differential transformer, piezo electric transducer, variable reluctance/ FM-Oscillator digital systems, loading effects; torque measurement on rotating shafts, shaft power measurement (dynamometers). Module -3 Temperature Measurement: Standards & calibration: thermal expansion me 8 Hours bimetallic thermometers, liquid-in-glass thermometers, pressure thermon thermoelectric sensor (thermocouple)- common Thermocouples, reference ju consideration, special materials, configuration & techniques; electrical resistance se conductive sensor (resistance thermometers), bulk semiconductors sensors (thermi

Module -4

junction semiconductor sensors; digital thermometers.

Pressure Measurement : Standards & calibration: basic methods of pressure measurement; dead weight gauges & manometer, manometer dynamics; elastic transducers, high pressure measurement; low pressure (vacuum) measurement-McLeod gauge, Knudsen gauge, momentum-transfer (viscosity) gauges, thermal conductivity gauges, ionization gauges, dual gauge technique.	8 Hours	
Module -5		
Flow Measurement: Local flow velocity, magnitude and direction. Flow visualize Velocity magnitude from pitot static tube. Velocity direction from yaw tube, pivoted vane, served sphere, dynamic wind vector indicator. Hot wire and hot film anemometer. Hot film shock-tube velocity sensors.	8 Hours	

Course outcomes:

On completion of the course students will

CO1: have the knowledge of design instruments with good precision and Calibrate the designed instruments.

CO2: understand measurement as applied to research & development operations & also to monitoring & control of industrial & military systems & processors.

CO3: illustrate the various applications in the field of DCS & SCADA.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

TEXT BOOKS:

1. Measurement systems application and design- ERNEST O DOEBELIN, 5th Edition Tata McGraw Hill.

- 1. Instrumentation Devices & Systems- Rangan, Mani and Sharma 2nd Edition, Tata McGraw Hill.
- 2. Process Instruments & Controls Hand Book Considine- D.M. Mc Graw Hill.
- 3. Transducers & Instrumentation- DVS Murthy, Prentice Hall of India.
- 4. Instrumentation & Process Measurements- W.Bolton, Universities Press.

ROBOTICS & AUTOMATION [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VI 15MT661 Subject Code IA Marks 20 Exam Marks Number ofLecture Hours/Week 03 **Exam Hours** 03 Total Number of 40 Lecture Hours **CREDITS - 03** Course objectives: Students will be able to 1. gain fundamental knowledge of Robotics and Automation describe Control system, different motions of robots and Material handling system Hours RevisedBloom's **Modules Teaching** Taxonomy(RBT) Level Module -1 **Basic Concepts:** 8 Hours Definition and origin of robotics – different types of robotics – various generations of robots – degrees of freedom – Asimov's laws of robotics – dynamic stabilization of robots. Module -2 **Power Sources And Sensors:** 8 Hours Hydraulic, pneumatic and electric drives – determination of HP of motor and gearing ratio – variable speed arrangements – path determination – micro machines in robotics – machine vision – ranging – laser – acoustic – magnetic, fiber optic and tactile sensors. Module -3 Manipulators, Actuators And Grippers: 8 Hours Construction of manipulators – manipulator dynamics and force control – electronic and pneumatic manipulator control circuits – end effectors – U various types of grippers – design considerations. Module -4 8 Hours **Industrial Automation:** • List basic Devices in Automated Systems • Distinguish Different Controllers

Module -5

Employed In Automated Systems.

Identify Safety in Industrial Automation

Material handling and Identification Technologies:	8 Hours	
Overview of Material Handling Systems, Principles and Design Consideration,		
Material Transport Systems, Storage Systems, Overview of Automatic		
Identification Methods.		

Course outcomes:

On completion of course students will

CO1: have the knowledge of Joints, Links, Sensors, Control units, Actuators. and elements of Automation

CO2: describe motions and control system of Robots.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Mikell P. Weiss G.M., Nagel R.N., Odraj N.G., Industrial Robotics, McGraw-Hill
- 2. Singapore, 1996.
- 3. Ghosh, Control in Robotics and Automation: Sensor Based Integration, Allied
- 4. Publishers, Chennai, 1998.

- 1. Deb.S.R., Robotics technology and flexible Automation, John Wiley, USA 1992.
- 2. Asfahl C.R., Robots and manufacturing Automation, John Wiley, USA 1992.
- 3. Klafter R.D., Chimielewski T.A., Negin M., Robotic Engineering An integrated approach, Prentice Hall of India, New Delhi, 1994.
- 4. Mc Kerrow P.J. Introduction to Robotics, Addison Wesley, USA, 1991.
- 5. Issac Asimov I Robot, Ballantine Books, New York, 1986.

SATELLITE COMMUNICATION [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VI Subject Code 15MT654 IA Marks 20 Number ofLecture 03 80 Exam Marks Hours/Week 40 03 Total Number of **Exam Hours** Lecture Hours

CREDITS - 03

Course objectives: Students will be able to

- gain Knowledge of various kinds of Satellites, Satellite Subsystems & Orbits, Trajectory, Multiple Access Techniques .
- understand the Operation of Satellites in space for various applications.

Modules	Hours Teaching	RevisedBloom's Taxonomy(RBT) Level
Module -1		•
SATELLITE ORBITS AND TRAJECTORIES : Definition, Basic Principles, Orbital parameters, Injection velocity and satellite trajectory, Types of Satellite orbits, Orbital perturbations, Satellite stabilization, Orbital effects on satellite's performance, Eclipses, Look angles: Azimuth angle, Elevation angle.	8 Hours	
Module -2		1
SATELLITE SUBSYSTEM : Power supply subsystem, Attitude and Orbit control, Tracking, Telemetry and command subsystem, Payload. Earth Station: Types of earth station, Architecture, Design considerations, Testing, Earth station Hardware, Satellite tracking.	8 Hours	
Module -3		
MULTIPLE ACCESS TECHNIQUES : Introduction, FDMA (No derivation), SCPC Systems, MCPC Systems, TDMA, CDMA, SDMA. Satellite Link Design Fundamentals: Transmission Equation, Satellite Link Parameters, Propagation considerations.	8 Hours	
Module -4		
COMMUNICATION SATELLITES : Introduction, Related Applications, Frequency Bands, Payloads, Satellite Vs. Terrestrial Networks, Satellite Telephony, Satellite Television, Satellite radio, Regional satellite Systems, National Satellite Systems.	8 Hours	
Module -5		
REMOTE SENSING SATELLITES : Classification of remote sensing systems, orbits, Payloads, Types of images: Image Classification, Interpretation, Applications. Weather Forecasting Satellites: Fundamentals, Images, Orbits, Payloads, Applications. Navigation Satellites: Development of Satellite Navigation Systems, GPS system, Applications.	8 Hours	
Course outcomes: On completion of course students will		

CO 1: have Knowledge of various kinds of Satellites, Satellite Subsystems & Orbits, Trajectory, Multiple Access techniques.

CO 2: understand the Operation of Satellites in space for various applications

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. Anil K. Maini, Varsha Agrawal, Satellite Communications, Wiley India Pvt. Ltd., 2015, ISBN: 978-81-265-2071-8.

Reference Books:

- 1. Dennis Roddy, Satellite Communications, 4th Edition, McGraw-Hill International edition, 2006
- 2. Timothy Pratt, Charles Bostian, Jeremy Allnutt, Satellite Communications, 2nd Edition, Wiley India Pvt. Ltd , 2017,

ISBN: 978-81-265-0833-4

PLC AND SCADA [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VI Subject Code 15MT61 IA Marks 20 Exam Marks 80 Number of Lecture Hours/Week 04 Exam Hours 03

CREDITS - 04

Course objectives: Students will be able to

50

Total Number of

Lecture Hours

- Gain the Knowledge of various skills necessary for Industrial applications of Programmable logic controller(PLC)
- Understand the basic programming concepts and various logical Instructions used in Programmable logic controller (PLC)
- Solve the problems related to I/O module, Data Acquisition System and Communication Networks using Standard Devices.
- Design and analysis of general structure of an automated process for real time applications using Programmable logic controller (PLC) and SCADA

Modules	Hours Teaching	RevisedBloom's Taxonomy(RBT) Level
Module -1		
what is A PLC, Technical Definition of PLC, What are its advantages, characteristics functions of A PLC, Chronological Evolution of PLC, Types of PLC, Unitary PLC, Modular PLC, Small PLC, Medium PLC, Large PLC, Block Diagram of PLC: Input/output (I/O) section, Processor Section, Power supply, Memory central Processing Unit: Processor Software / Executive Software, Multi asking, Languages, Ladder Language.	10 Hours	
Module -2		
Bit Logic Instructions: introduction: Input and Output contact program symbols, Numbering system of inputs and outputs, Program format, introduction to logic: Equivalent Ladder diagram of AND gate, Equivalent ladder diagram of or Gate, equivalents Ladder Diagram of NOT gate, equivalent ladder diagram of XOR gate, equivalent ladder diagram of NAND gate, equivalent ladder diagram of NOR gate, equivalent ladder diagram to demonstrate De Morgan theorem. Ladder design. Examples: Training Stopping, Multiplexer, DE multiplexers	10 Hours	
Module -3		

PLC Timers and Counters: On Delay and OFF delay timers, Timer-on Delay,	10 Hours		
Timer off delay, Retentive and non-retentive timers. Format of a timer			
instruction. PLC Counter: Operation of PLC Counter, Counter Parameters,			
Counters Instructions Overview Count up (CTU) Count down (CTD).			
Advanced instructions: Introduction: Comparison instructions, discussions on			
comparison instructions, "EQUAL" or "EQU" instruction, "NOT EQUAL" or			
"NEQ" instruction, "LESS THAN" or "LESS" instruction, "LESS THANOR EQUAL"			
or "LEQ" instruction, GREATER THAN" OR "GRT" instruction, "GREATER THAN			
OR EQUAL TO" or "GRO" instruction, "MASKED COMPARISON FOR EQUAL" or			
"MEQ" instruction, "LIMIT TEST" or "LIM" instruction.			
MEG instruction, divite that of divit instruction.			
Module -4	l l		
PLC input output (I/O) modules and power supply: Introduction:	10 Hours		
Classification of I/O, I/O system overview, practical I/O system and its			
mapping addressing local and expansion I/O, input-output systems, direct I/O,			
parallel I/O systems serial I/O systems. Sinking and sourcing. Discrete input			
module. Rectifier with filter, threshold detection, Isolation, logic section,			
specifications of discrete input module, types of analog input module, special			
input modules, analog output module, I/O modules in hazardous locations			
power supply requirements, power supply configuration, filters.			
Module -5			
Module -5			
SCADA SYSTEMS	10 Hours		
Introduction, definition and history of Supervisory Control and Data			
Acquisition, typical SCADA System Architecture, Communication			
Requirements, Desirable properties of SCADA system, Features, advantages,			
disadvantages and applications of SCADA. SCADA Architecture(First			
generation-Monolithic, Second Generation-Distributed, Third generation-			
Networked Architecture), SCADA systems in operation and control of			
interconnected power system, Power System Automation, Petroleum Refining			
Process, Water Purification System, Chemical Plant			
Course outcomes:	1		
On completion of the course students will			
CO 1. have be ended as of Duc	alaal O	don and West	
CO 1: have knowledge of Programmable Logic Controller domain on various Lo			
Advanced Logical Instruction, I/O Module, Sensor, Actuator, Communication and		•	
CO 2: Understand the basic programming concepts and various logical Instruct	lions usea in	rrogrammable	
logic controller (PLC).	o logic sast	uallan (DI C) az J	
CO 3: Compute the extent and nature of electronic circuitry in Programmable logic controller (PLC) and			
SCADA including monitoring and control circuits for Communication and Interfacing.			
CO 4: Design and analyse the general structure of an automated process for real industrial applications	i uiiie		
industrial applications Graduate Attributes (as per NBA):			
Question paper pattern:			

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. "PLC and Industrial application", MadhuchhandanGupts and SamarjitSen Gupta, pernram international pub. (Indian) Pvt. Ltd., 2011.

2.Ronald L Krutz, "Securing SCADA System", Wiley Publication

- 1.1.GaryDunning,"Introduction to Programmable Logic Controllers", Thomson,2nd Edition.
- 2.John W Webb, Ronald A Reis,"Programmable Logic Controllers: Principles and Application", PHI Learning, Newdelhi, 5th Edition
- 3.Stuart A Boyer, "SCADA Supervisory Control and Data Acqusition", ISA, 4th Revised edition

Computer Aided Machine Drawing [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VI Subject Code 15MT64 IA Marks 20 2 Hours Theory Exam Marks Number of Lecture and 4 Hours Lab Hours/Week Exam Hours 03 Total Number of 70 Lecture Hours **CREDITS - 04** Course objectives: Students will be able to 1. gain knowledge about Engineering Drawing 2. understand the sections of solids, orthographic views, threads, fasteners, couplings, joints and machine drawing **Modules** Hours RevisedBloom's **Teaching** Taxonomy(RBT) Level Part - A Sections of Solids: Sections of Pyramids, Prisms, Cones and resting only on their 20 Hours bases (No problems on axis inclinations, spheres and hollow solids). True shape of sections. Orthographic Views: Conversion of pictorial views into orthographic projections of simple machine parts without sections. (Bureau of Indian Standards conventions are to be followed for the drawings). Thread Forms: Thread terminology, sectional views of threads. ISO Metric (Internal & External) square. **Fasteners:** Hexagonal headed bolt and nut with washer (assembly). Part - B 20 Hours **Keys & Joints:** Parallel key, Taper key, Feather key, Gib head key and Woodruff key (Only Practice) Cotter joint, knuckle joint for two rods. **Couplings:** Protected type flanged coupling, flexible coupling Part - C 30 Hours **Assembly Drawings** (Part drawings should be given) 1. Plummer block (Pedestal Bearing) 4. Screw jack (Bottle type)

5. Tailstock of lathe

Geometric Dimensioning and Tolerances (Not for Exam): Types of Geometric tolerances, terminology for geometrical deviations, representation of geometrical tolerance on a drawing, dimensional tolerances, terminology for dimensional tolerances, selection of tolerances, representation of dimensional tolerances on a drawing.

Course outcomes:

On completion of course students will:

CO 1: have knowledge about Engineering Drawing

CO 2: understand the concepts of sections of solids, orthographic views, threads, fasteners, couplings, joints and assembly drawing

Graduate Attributes (as per NBA):

Scheme of Examination:

One Question from Part - A: **20 marks** One Question from Part - B: **20 Marks** One Question from Part - C: **40 Marks**

Text Books:

1. 'A Primer on Computer Aided Machine Drawing-2007', Published by

VTU, Belgaum.

2. 'Machine Drawing', N.D.Bhat &V.M.Panchal

Reference Books:

1. 'A Text Book of Computer Aided Machine Drawing', S. Trymbaka

Murthy, CBS Publishers, New Delhi, 2007

2. 'Machine Drawing', K.R. Gopala Krishna, Subhash Publication

L	s per Choice Based	Modeling and Simulation I Credit System (CBCS) scheme] SEMESTER – VI
Subject Code	15MT651	IA Marks	20
Number of		Exam Marks	80
Lecture Hours/Week	03		
Total Number of Lecture Hours	40	Exam Hours	03
Tiours		CREDITS – 03	
Course objectives: St		e to epts and methodologies of mode	ling and simulation

- 2. understand the concepts of discrete event simulation, random number generation, test for random numbers & random varieties used in simulation study.
- 3. develop simulation model by simulation package for queuing system, production system and maintenance system

Modules	Hours Teaching	Revised Bloom's Taxonomy(RBT) Level
Module -1	•	
System and system environment: Component of a system — discrets systems — Types of model; Steps in Simulation study; event occurrence using random number table — Single server q queue-inventory systems. Discrets Event Simulation: Concepts in discreet event sin simulation using event scheduling, single channel queue, two s simulation of inventory problem.	simulation of ueue- two ser nulation, man	an 08 Hours ual
Module -2		
Random number generations: Properties of random numbers Pseudo – Random numbers – techniques of generating pseudo random number; the Chisquare test-the kolmogrov smimo – Gap test – poker test. FCV, symbolic representation.	random numbe	ers;
Module -3		
Random – Viriate Generation: Inverse transform technique Uniform. Triangular, weibull, empirical, uniform and discrepance rejection method for Poisson and gamma discrepance transformation for normal distribution.	rete distributi	on.

Module -4		
Analysis of simulated Data: Data collection, identifying the distribution, parameter estimations, and goodness of fit tests, verification and validation of simulation models.	08 Hours	
Module -5		
Comparison and selection of GPSS, SIMSCRIPT, SLAM: Arena simulation languages: development of simulation models using arena simulation package for queuing system, Productions systems, maintenance system.	08 Hours	

Course outcomes:

On completion of the course students will

- CO 1: have fundamental knowledge of modeling and simulation.
- CO 2: understand the techniques of discrete event simulation, random number generation, test for random number, random variants used in simulation study & simulation packages.
- CO 3: apply simulation packages for queuing system, production system and maintenance system.

Graduate Attributes (as per NBA):

Question paper pattern:

Text Books:

- **1. Discrete, Event system Simulation,** Banks J., Carson J.S. and Nelson B.L., 3rd Edition, Pearson education, Inc 2004 (ISBN 81-7808-505-4).
- 2. System Simulation, Geoffrey Gorden, Prentice Hall of India, 2003.

- 1. System Simulations, Geoffery Gorden, Prentice Hall of India, 2003.
- 2. System Simulations and Modeling, Narsingh deo., Prentice Hall of India 2003.
- 3. Computer simulations and Modeling, Francis Neelamkovil, , john Wiley & Sons, 1987
- 4. Simulation Modeling with Pascal, Rath M.Davis & Robert M O Keefe, Prentice Hall Inc. 1989.

RAPID PROTOTYPING [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VI 15MT652 Subject Code IA Marks 20 Exam Marks Number ofLecture Hours/Week 03 Exam Hours 03 Total Number of 40 Lecture Hours **CREDITS - 03** Course objectives: Students will be able to 1. gain knowledge of Selective Laser Sintering, Fusion Deposition Modeling Solid Ground Curing, 3D Printers, 2. understand the working Principles of various Rapid Prototyping Manufacturing process, 3. know the applications of RP Technology

Modules	Hours	RevisedBloom's
	Teaching	Taxonomy(RBT) Level
Module -1		
Introduction: Need for the compression in product development, history of RP		
systems, Growth of RP industry, and classification of RP systems.	8 Hours	
Stereo Lithography Systems : Principle, Process parameter, data files and machine details, Application.		
Module -2		
	0.11	T
Fusion Deposition Modelling : Principle, Process parameter, Path generation, Applications.	8 Hours	
Solid Ground Curing: Principle of operation, Machine details, Applications.		
Laminated Object Manufacturing: LOM materials. application.		
Module -3		
Selective Laser Sintering: Type of machine, Principle of operation, process	8 Hours	
parameters, Data preparation for SLS, Applications. Thermal jet printer, ,		
3-D printer		
Module -4		
. Rapid Tooling: Indirect Rapid tooling, Silicon rubber tooling, Aluminium filled	8 Hours	
epoxy tooling, Spray metal tooling, 3Q keltool, etc. Direct Rapid Tooling, Quick		
cast process, Sand casting tooling, Laminate tooling soft Tooling vs. Hard tooling.		
Module -5		
Software for RP: STL files, Overview of Solid view, magics, imics, magic-	8 Hours	
communicator, etc. Internet based software		
Rapid Manufacturing Process Optimization: factors influencing accuracy. Data		

preparation errors, Part building errors, Error in finishing.

Course outcomes:

On completion of course students will

CO 1: have fundamental knowledge of Rapid Prototyping process, Selective Laser Sintering, Fusion Deposition Modeling, Solid Ground Curing, 3D Printers, Rapid Tooling, Software and Errors.

CO 2: understand the working Principles of Selective Laser Sintering, Fusion Deposition Modeling Solid Ground Curing, 3D Printers,.

CO 3: Know the applications of Selective Laser Sintering, Fusion Deposition Modeling, Solid Ground Curing, 3D Printers, also software tools like Magic, MMIC.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Stereo Lithography and other RP & M Technologies, Paul F.Jacobs: SME, NY 1996.
- 2. Rapid Manufacturing, Flham D.T & Dinjoy S.S Verlog London2001.

- 1. Rapid Prototyping, Terry Wohler's Report 2000"Wohler's Association 2000.
- 2. Rapid Prototyping Materials, Gurumurthi, IISc Bangalore.
- 3. Rapid Automated, Lament wood. Indus press New York

		nputer Integrated Manufac d Credit System (CBCS) sch	_	STER – VI	
Subject Code	15MT655	IA Marks		20	
		Exam Marks		80	
Number of Lecture	03				
Hours/Week	03				
Total Number	40	Exam Hours		03	
of Lecture					
Hours					
	_	CREDITS – 03			
	Students will be able				
	ledge of basics conc	epts CIM volume production, flow lin	na analysis an	d lina balancina	automated
		manufacturing planning & C		i ille balancing	, automateu.
		ding manufacturing solutions			
Modules		<u> </u>	Hours	Revised Bloor	n's
			Teaching	Taxonomy(RI	BT)
		M 11 1		Level	
		Module -1			
Introduction, Aut	comation definition,	Types of automation, CIM	l, processing	in	
manufacturing, 1	Production concept	s, Mathematical Models-	-Manufacturi	ng 8 Hours	
lead time, produc	tion rate, componer	nts of operation time, capa	city, Utilizatio	on	
and availability, V	Work-in-process, WII	P ratio, TIP ratio,			
High Volume Pro	oduction				
Introduction Aut	omated flow line-sy	mbols, objectives, Work j	part transpo	rt-	
continuous, Inter	mittent, synchronor	us, Pallet fixtures, Transf	er Mechanisı	m-	
Linear-Walking b	oeam,. roller chain o	drive, Rotary-rack and pi	nion, Rachet	&	
Pawl, Geneva w	vheel, Buffer stora	ge, control functions-sec	quence, safe	ty,	
Quality, A	Automation	for machining	operatio	on.	
		Module -2			
				8 Hours	
•		& Line BalancingProp			
	•	of Tranfer Line without			
		oach and problems, Analy f storage, buffer capacit			
	_	in storage, burier capacity			
•	Manual Aggambly lin	•	*********************************		

than two stages, Manual Assembly lines
Minimum Rational Work Element

Work station process time, Cycle time, precedence constraints. Precedence				
diagram, Balance delay methods of line balancing-largest Candidate rule,				
Kilbridge and Westers method, Ranked positional weight method				
Module -3	·			
Automated Assembly Systems Design for automated assembly systems,types	8 Hours			
of automated assembly system, Parts feeding devices-elements of				
partsdelivery system-hopper, part feeder, Selectors, feed back, escapement				
andplacement analysis of Multistation Assembly Machine analysis of				
singlestation assembly. Automated Guided Vehicle System:				
Introduction, Vehicle guidance and routing, System management, Quantitative				
analysis of AGV\'s with numerical problems and application.				
Module -4				
Computerized Manufacturing Planning System Introduction, Computer	8 Hours			
Aided Process Planning, Retrieval types of process planning, Generative type of				
process planning, Material requirement planning, Fundamental concepts of				
MRP inputs to MRP, Capacity planning.				
Module -5	<u>.</u>			
CNC Machining Centers	8 Hours			
Introduction to CNC, elements of CNC, CNC machining centers, part				
programming, fundamental steps involved in development of part				
programming for milling and turning.				
Course outcomes:	<u>.</u>			

On completion of the course student will

- **CO 1:** have fundamental knowledge of CIM
- **CO 2:** understand the concepts of high volume production, flow line analysis and line balancing, automated, assembly system, computerized manufacturing planning & CNC centers.
- CO 3: apply CIM technology for providing manufacturing solutions

Graduate Attributes (as per NBA):

Question paper pattern:

Text Books:

- 1. Automation, Production system & Computer Integrated manufacturing, M. P. Groover Person India, 2007 2nd edition.
- 2. Principles of Computer Integrated Manufacturing, S. Kant Vajpayee, Prentice Hall India.

- 1. Computer Integrated Manufacturing, J. A. Rehg & Henry. W. Kraebber.
- 2. CAD CAM by Zeid, Tata McGraw Hill.

EMBEDDED SYSTEMS (ARM)[As per Choice Based Credit System (CBCS) scheme] SEMESTER - VI

Subject Code	15MT62	IA Marks	20
		Exam Marks	80
Number of Lecture			
Hours/Week	04		
Total Number of Lecture Hours	50	Exam Hours	03

CREDITS - 04

Course objectives: Students will be able to

- gain the knowledge of various RISC and CISC architectures of processors.
- understand the embedded system based ARM processor, its programming with Embedded C and assembly language,

Modules	Hours Teaching	RevisedBloom's Taxonomy(RBT) Level
Module -1		
Introduction: The RISC design philosophy; The ARM design philosophy; Embedded system hardware and software. ARM processor fundamentals: Registers; Current Program Status Register; Pipeline; Exceptions, interrupts and the Vector Table; Core extensions; Architecture revisions; ARM processor families.	10 Hours	
Module -2		
Arm Instruction Set And Thumb Instruction Set: ARM instruction set: Data processing instructions; Branch instructions; Load-store instructions; Software interrupt instruction; Program Status Register functions; Loading constants; ARMv5E extensions; Conditional execution. Thumb instruction set: Thumb register usage; ARM –Thumb interworking; Other branch instructions; Data processing instructions; Single-Register Load-Store instructions; Multiple-Register Load-Store instructions; Stack instructions; Software interrupt instruction Module -3	10 Hours	
Writing And Optimizing ARM Assembly Code: Writing assembly code; Profiling and cycle counting; Instruction scheduling; Register allocation; Conditional execution; Looping constructs; Bit manipulation; Efficient switches; Handling unaligned data. Module -4	10 Hours	
	T	T
Caches: The memory hierarchy and the cache memory; Cache architecture; Cache policy; Coprocessor 15 and cache; Flushing and cleaning cache memory; Cache lockdown; Caches and software performance	10 Hours	

Module -5		
Exception And Interrupt Handling: Exception handling; Interrupts and interrupt	10 Hours	
handling Schemes		
Course outcomes		

Course outcomes:

On completion of the course students will

CO 1: have knowledge of embedded system based on the ARM processor, various cache methods and instruction set.

CO 2: understand the various instruction set for writing and optimizing ARM assembly and C code

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. ARM System Developer's Guide – Designing and Optimizing System Software – by Andrew N. Sloss, Dominic Symes, Chris Wright, Elsevier, 2004.

- 1. ARM Architecture Reference Manual by David Seal (Editor), 2nd Edition, Addison-Wesley, 2001.
- 2. ARM System-on-Chip Architecture by Steve Furber, 2nd Edition, AddisonWesley, 2000.

[.	As per Choice Based	Mechanical Vibrations Credit System (CBCS) sch	neme] SEMES	STER – VI
Subject Code	15MT653	IA Marks		20
•		Exam Marks		80
Number of Lecture Hours/Week	03			
Total Number of Lecture Hours	40	Exam Hours		03
<u>, </u>		CREDITS – 03		
	•	ent vibration systems. double and multi degree vi	brations using Hours Teaching	Revised Bloom's Taxonomy(RBT) Level
(S.H.M.), Work do SHM, Beats. Undamped Free Vi Methods of Analysis	ne by harmonic for ibrations (Single Dos, Natural frequencies)	Definitions, Simple Harce, Principle of super poses of simple systems, Springers of simple systems, Springers	sition applied mass systems	to ,
parallel, simple prob Module -2	olems.			
Damped free vibra	ons for over, critica	: Types of damping, Analy l and under damped system		
Module -3				
constant harmonic unbalances, excitati	excitation - magni ion of support (rela	oduction, Analysis of force fication factor, rotating artive and absolute amplitued due to damping, simple p	nd reciprocati ides), force a	ng
Module -4				1
•	-	les of vibrations, Normal m g) – Simple spring mass sys		

tightly stretched strings, Problems.		
Module -5		
Numerical Methods for Multi DOF systems: Introduction, Maxwell's reciprocal	8 Hours	
theorem, influence coefficients, Rayleigh's method, Dunkerley's method, Stodola		
method, method of matrix iteration (up to two iterations) and Problems.		

Course outcomes:

On completion of the course student will:

CO1: have knowledge of different vibrations, degrees of freedom, damping systems, magnification factor and transmissibility etc.

CO2: understand the mobility of different vibration systems.

CO3: determine the mobility of single, double and multi degree vibrations using different methods.

Graduate Attributes (as per NBA):

Question paper pattern:

Text Books:

- 1. Mechanical Vibrations, S. S. Rao, Pearson Education Inc, 4th edition, 2003.
- **2. Mechanical Vibrations,** G. K. Grover, Nemchand and Bros, 6th edition, 1996.
- 3. Mechanical Vibrations, V. P. Singh, Dhanpat Rai & Company, 3d edition, 2006.

- **1. Theory of Vibration with Applications,** W. T. Thomson, M. D. Dahleh and C. Padmanabhan, Pearson Education Inc, 5th edition, 2008.
- **2. Mechanical Vibrations:** S. Graham Kelly, Schaum's outline Series, Tata McGraw Hill, Special Indian Edition, 2007.
- **3.** Theory and Practice Mechanical Vibrations: J. S. Rao & K. Gupta, New Age International Publications, New Delhi, 2001.
- **4. Mechanical Vibrations:** Dr. A. R. K Swamy & Prof. Y. Krishna Murthy, 1st edition 2009.

SIGNAL PROCESSING LABORATORY

[As per Choice Based Credit System (CBCS) scheme]

SEMESTER - VII

		ODI-IDOI DIC VII	
Subject Code	15MTL77	IA Marks	20
Number of Lecture Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	40	Exam Hours	03

CREDITS - 02

Course objectives: Students will be able to

- 1. gain knowledge of Scientific Programming using Matlab.
- 2. understand different functions in Matlab and TMS320C67XX board in signal processing.
- 3. use in different functions to solve engineering problems.

PART – A	Hours	Revised Bloom's
LIST OF EXPERIMENTS USING MATLAB	Teaching	Taxonomy(RBT) Level

- 1. Generation of basic elementary signals and operations on these signals.
- 2. Verification of sampling theorem.
- 3. Impulse response of a given system.
- 4. Solving a given difference equation.
- 5. Computation of N point DFT and IDFT of a given sequence and to plot magnitude and phase spectrum.
- 6. Design and implementation of FIR filter to meet given specifications.
- 7. Design and implementation of IIR filter to meet given specifications.
- 8. Removal of noise from an audio signal.
- 9. Different operations on image signal.

PART - B

LIST OF EXPERIMENTS USING DSP PROCESSOR

- 1. Linear convolution of two given sequences.
- 2. Circular convolution of two given sequences.
- 3. Computation of N- Point DFT of a given sequence
- 4. Realization of an FIR filter (any type) to meet given specifications .The input can be a Signal from function generator / speech signal.

- 5. Noise: Add noise above 3kHz and then remove; Interference suppression using 400 Hz tone.
- 6. Impulse response of first order and second order system.

Course outcomes: On completion of the course the student will

CO1: have knowledge of Scientific Programming using Matlab.

CO2: understand the programming in Matlab software and hardware.

CO3: use DSP board for real time applications.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TWO questions.
- One From PART A and one from PART B.

Text Books:

Reference Books:

- 1. **Digital signal processing using MATLAB Sanjeet Mitra, TMH, 2001**
- 2. **Digital signal processing using MATLAB** J. G. Proakis & Ingale, MGH, 2000
- 3. **Digital Signal Processors**, B. Venkataramani and Bhaskar, TMH,2002

Scheme of Examination:

Experiment:

Part A: 35 Marks

Part B: 35 Marks

Viva-Voice: 10 Marks

Total: 80 Marks

		THERMAL ENGINE	ERING
	[As p	er Choice Based Credit Syster SEMESTER – VII	
Subject Code Number ofLecture	15MT72	IA Marks Exam Marks	20 80
Hours/Week	04		
Total Number of Lecture Hours	50	Exam Hours	03

CREDITS - 04

Course objectives: Students will be able to

- gain fundamental knowledge of thermodynamics, and heat transfer.
- understand the laws of thermodynamics and heat transfer.
- formulate and determine thermodynamic and heat transfer parameters.

Hours	RevisedBloom's
Teaching	Taxonomy(RBT)
	Level
10 Hours	
10 Hours	
20 110 415	
	Teaching 10 Hours

law of Thermodynamics; PMM II and PMM I, Claussius statement of second law		
of Thermodynamics, equivalence of the two statements; reversible hat engines, Carnot cycle, Carnot principles. Thermodynamic temperature scale, simple		
problems.		
Module -3		
Air Standard cycles: Carnot, Otto, Diesel, Dual and Stirling cycles, P-V and T-S diagrams, description, efficiencies and mean effective pressures, Comparison of Otto, Diesel and dual cycles, simple problems.		
Heat Transfer - Introductory Concepts and Definitions: Modes of heat transfer: Basic laws governing conduction, convection, and radiation heat transfer; Thermal conductivity; convective heat transfer coefficient; radiation heat transfer; combined heat transfer mechanics. Boundary conditions of 1 st , 2 nd and 3 rd Kind, simple problems.	10 Hours	
Module -4		
Conduction: Derivation of general three dimensional conduction equations in Cartesian coordinate, special cases, discussion on 3-D conduction in cylindrical and spherical coordinate systems (No derivation). One dimensional conduction equations in rectangular, cylindrical and spherical coordinates for plane and composite walls. Overall heat transfer coefficient. Thermal contact resistance, Simple problems. Free or Natural Convection: Application of dimensional analysis for free convection- physical significance or Grashoff number; use of correlations of free convection in vertical, horizontal and inclined flat plates, vertical and horizontal cylinders and spheres, Simple problems.	10 Hours	
Module -5		
Forced Convections: Applications of dimensional analysis for forced convection. Physical significance of Reynolds, Prandtl, Nusselt and Stanton numbers, Simple problems. Radiation Heat Transfer: Thermal radiation; definitions of various terms used in radiation heat transfer, Stefan-Boltzman law, Kircoff's law. Planck's law and Wein's displacement law. Radiation heat exchange between two parallel infinite black surface, between two parallel infinite gray surfaces; effect of radiation shield; intensity of radiation and solid angle, Simple problems.	10 Hours	
Course outcomes: On completion of course students will CO1: have knowledge of thermodynamics and heat transfer. CO2: understand the concepts of system, energy interaction, temperature distribution CO3: applications of laws of thermodynamics to open and closed system and of he and types of materials. Determine the thermodynamic performance, heat transfer and	at transfer to	o different shapes
Graduate Attributes (as per NBA):		
Question paper pattern:		
The question paper will have TEN questions.		

- Each full question carries 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Basic and applied Thermodynamics, P. K. Nag, Tata McGraw Hill Pub. 2002.
- 2. Heat & Mass transfer, Tirumaleshwar, Pearson education 2006.
- **3.** Engineering Thermodynamics, R K Rajput, Laxmi Publications, 2007

- 1. Engineering Thermodynamics, J. B. Jones and G. A. Hawkins, John Wiley and Sons.
- **2.** Basic Engineering Thermodynamics data hand book, by B. T. Nijaguna. (To be supplied in the examination)
- **3.** Thermodynamics, An Engineering Approach, Yunus a. Cenegal and Michael a. Boles, Tata McGraw Hill publications, 2002.
- 4. **Heat and Mass Transfer,** R K Rajput, S. Chand, 2007.
- **5. Heat transfer,** P. K. Nag, Tata McGraw Hill 2002.
- 6. Heat transfer-A basic approach, Ozisik, Tata McGraw Hilll 2002.
- 7. Heat transfer, a practical approach, Yunus a- Cengel Tata McGraw Hill.

ANALYTICAL INSTRUMENTATION

[As per Choice Based Credit System (CBCS) scheme] SEMESTER – VII

Subject Code	15MT745	IA Marks	20
Number of Lecture Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	40	Exam Hours	03

CREDITS - 03

Course objectives: Students will be able to

- gain knowledge of developing basic skills necessary for importance Analytical Instrumentation
- understand the basic concepts and various Operation using Analytical Devices used in Biomedical Industry.

Modules	Hours Teaching	Revised Bloom's Taxonomy(RBT) Level
Module -1		
Visible ultraviolet spectrophotometers: Electromagnetic radiation, Beer Lambert law, absorption instruments, colorimeters, spectrophotometers, infrared spectroscopy theory, instrument and its types.	8 Hours	
Module -2		•
Chromatography: Gas chromatograph - basic concepts, parts of gas chromatograph. Method of peak areas, liquid chromatography- basic concepts, types if liquid chromatography, the liquid chromatograph.	8 Hours	
Module -3		
Mass spectrometer & NMR spectrometer: Basic concept, types of mass spectrometer, components of mass spectrometer, resolution and applications. Principle of NMR, constructional details, sensitivity enhancement for analytical NMR spectroscopy. Use of computers with NMR spectrometers.	8 Hours	
Module -4		
Fluorimeters & phosphorimeters : Principle of fluotrscence, measurement of fluotrscence, spectro fluotrscence, microprocessor based spectro fluotrscence, Measurement of Phosphorescence.	8 Hours	
Module -5		
Blood gas analyzer: Principle of pH measurement, electrode of pH measurement, Blood pH measurement, measurement of Blood pCO2, measurement of Blood pO2, complete Blood gas analyzer, commercially available Blood gas analyzers Course outcomes: On completion of the course the student will	8 Hours	

- **CO 1:** have knowledge of Analytical Instrumentation on various Biomedical Module and Different Types of Measurement Meters and Measurement System
- **CO 2:** understanding the basic concepts of Analytical Instrumentation and various Measurement Meters and Measurement System used in Biomedical Industry.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. Hand book of analytical Instruments by R. S. Khandpur, TMH Publications 1st Ed 1989, New Delhi

- 1. Instrumental methods of analysis by H. H. Willard, L. L. Merritt & J. A. Dean, CBS Publications 7th Ed 1988
- 2. Principles of Instrumental analysis by S. J. Holler & T. A. Nilman Saunders college Publications 5st Ed 1998

	[As p	ARTIFICIAL NEURAL NETV er Choice Based Credit System (SEMESTER – VII			
Subject Code	15MT755	IA Marks		20	
Number ofLecture Hours/Week	03	Exam Marks		80	
Total Number of Lecture Hours	40	Exam Hours		03	
		CREDITS - 03			
Function, At understand th	tractor Neural Netv ne working methodo d Radial Basis Fun	Networks, Supervised Learn vorks, Self-organization Fea ology of Artificial Neural Net ction, Attractor Neural Netv Modules	ture Map. works, Supervise	d Learning,	Support Vector re Map. RevisedBloom's Taxonomy(RBT)
		Module -1			Level
functions – Architecture and Linear Separabi Networks. Learning	cture: Feed forward ility, Non-Linear S : Learning Algorith jective of TLNs, I	rtificial Neural Model - Typd and Feedback, Convex Seeparable Problem. Xor Problems, Error correction and Correction Learning Algorithms.	ets, Convex Hull blem, Multilayer Gradient Descent	8 Hours	
		Module -2		1	
Square Learning, approximate to grad	MSE Error surflient descent, Applarchitecture, Back	rning and Non Separable seface, Steepest Descent Sication of LMS to Noise Coropagation Learning Algorithms 2	Search, µ-LMS ancelling, Multi-	8 Hours	
		Module -3			
Statistical Learning Classification, Radi	Theory,Support Vial Basis Function	l Basis Function: Learning ector Machines, SVM applarization theory, Goplication to face recognition	ication to Image eneralized RBF	8 Hours	

Module -4

8 Hours

Attractor Neural Networks: Associative Learning Attractor Associative Memory,

Linear Associative memory, Hopfield Network, application of Hopfield Network, Brain State in a Box neural Network, Simulated Annealing, Boltzmann Machine,

Bidirectional Associative Memory

Module -5	
Self-organization Feature Map : Maximal Eigenvector Filtering, Extracting Principal Components, Generalized Learning Laws, Vector Quantization, Self-organization Feature Maps, Application of SOM, Growing Neural Gas.	8 Hours

Course outcomes:

On completion of course students will

C01: have Knowledge of Artificial Neural Networks, Supervised Learning, Support Vector Machines and Radial Basis Function, Attractor Neural Networks, Self-organization Feature Map.

CO2: understand the working methodology of Artificial Neural Networks, Supervised Learning, Support Vector Machines and Radial Basis Function, Attractor Neural Networks, Self-organization Feature Map.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. Neural Networks A Classroom Approach—Satish Kumar, McGraw Hill Education (India) Pvt. Ltd, Second Edition.

- 1. Introduction to Artificial Neural Systems-J.M. Zurada, Jaico Publications 1994.
- 2. Artificial Neural Networks-B. Yegnanarayana, PHI, New Delhi 1998.

AUTOMATION IN PROCESS CONTROL

[As per Choice Based Credit System (CBCS) scheme] SEMESTER – VII

Subject Code	15MT741	IA Marks	20
Number of Lecture Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	40	Exam Hours	03

CREDITS - 03

Course objectives: Students will be able to

- gain knowledge of developing basic skills necessary for importance Process controller (Digital and Analog Controller) Using in Various Industry.
- understand the concepts and various Operation using Automation Process System by using various Process Control System.

• determine and Diagnosis the Principles of Various Digital and Analog Controller and ADC, DAC.

 determine and Diagnosis the Principles of Various Digital and Analog Controller and Al 	JC, DAC.	
Modules	Hours Teaching	Revised Bloom's Taxonomy(RBT) Level
Module -1		
INTRODUCTION TO PROCESS CONTROL : process control block diagram, control system evolution. Final control: introduction to final control operation, signal conversions, actuators, control elements. Alarm and annunciators, control drawing: P & ID symbols and diagrams, flow sheet symbols, inter logic symbols, graphic symbols.	8 Hours	
Module -2		
CONTROLLER PRINCIPLES: Introduction, process characteristics, control system parameters, discontinuous control modes, continuous control modes, and composite control modes.	8 Hours	
Module -3		
DISCRETE-STATE PROCESS CONTROL: Introduction, definition and characteristics of discrete state process control. Control-loop characteristics: Introduction, control system configuration, multivariable control systems, control system quality, stability, and process loop tuning. Module -4	8 Hours	
ANALOG CONTROLLERS: Introduction, general features, electronic controllers, pneumatic controllers, designs considerations.	8 Hours	
Module -5	l .	1
Module -5		

-A conversion techniques (R-2R & binary weighted) multiplying DAC applications.	
a-D conversion techniques (flash, successive approximation, single slope, dual slope), over	
ampling converters.	

Course outcomes: On completion of the course the student will

- **CO 1:** have a knowledge of Process Control System on various Process Parameter (P,PI,PID) and Converter.
- **CO 2:** understanding the concepts of Automation in Process Control Involved in Measurement System and Controller used in Industry.
- **CO 3:** Application of Digital and Analog Controller used in various Automated Application based on Controller Parameters.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Process Control Instrumentation Technology-C D Johnson.
- 2. Design with operational amplifiers and analog integrated circuits-3rd Edition, SERGIO FRANCO, Tata McGraw Hill

- 1. Instrument Engineers Handbook-(Vol 1 & 2)-B G Liptak, Chilton Book Company
- 2. Chemical process control an introduction to theory and practice-Stephanopoulos
- 3. A Users Handbook of D/A and A/D converters-.E.R.HNATEK, Wiley publications
- 4. Computer Aided Process Control- S K Singh, Prentice Hall of India.
- 5. Process control: Concepts, dynamics & Application-S.K. Singh, PHI.

	[As pe	BIOMEDICAL SIGNAL PROC r Choice Based Credit System (SEMESTER – VII			
	1				
Subject Code	15MT751	IA Marks		20	
Number ofLecture Hours/Week	03	Exam Marks		80	
Total Number of Lecture Hours	40	Exam Hours		03	
		CREDITS - 04			
Compression To understand the	ge of Biomedical S echniques, Cardiolog e operation of Bio ata Compression Tec	ignals, ECG, Signal Conversion fical signal processing, Neurolo formedical Signal Processing ,E Signal & Signal	gical signal processi CG Signal Conversi	ng. on & Averag	
		Module -1			Level
					_
of Biomedical Signal Electrocardiograph characteristics.	s, Objectives and ones. Simple signal contracts:		nalysis. ems, ECG signal	8 Hours	
		Module -2			
typical averager, sof Adaptive Noise Ca	ftware for signal ancelling:Principal	eraging, signal averaging as averaging, limitations of s noise canceller model, her applications of adaptive	signal averaging. 60-Hz adaptive	8 Hours	
		Module -3			
algorithm, Huffman	coding, data red	ng point algorithm, AZTE uction algorithms The Forum estimation, Frequency	ourier transform,	8 Hours	
		Module -4			
acquisition, ECG lea	ad system, ECG s	Basic Electrocardiographic signal characteristics (para	meters and their	8 Hours	

estimation), Analog filters, ECG amplifier, and QRS detector, Power spectrum of

the ECG, Band pass filtering techniques, Differentiation techniques, Template matching techniques, A QRS detection algorithm, Realtime ECG processing

algorithm, ECG interpretation, ST segment analyzer, Portable arrhythmia monitor. (Text -2)		
Module -5		
Neurological signal processing : The brain and its potentials, The electrophysiological origin of brain waves, The EEG signal and its characteristics (EEG rhythms, waves, and transients), Correlation. Analysis of EEG channels: Detection of EEG rhythms, Template matching for EEG, spike and wave detection (Text-2).	8 Hours	

Course outcomes:

On completion of course students will

CO1: Have Knowledge of Biomedical Signals, ECG, Signal Conversion & Averaging ,Adaptive Noise Cancellation, Data Compression Techniques, Cardiological signal processing, Neurological signal processing.

CO 2: Understand the operation of Biomedical Signal Processing ,ECG Signal Conversion & Averaging ,Adaptive Noise Cancellation, Data Compression Techniques, Cardiological signal & Neurological signal processing.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Biomedical Digital Signal Processing-Willis J. Tompkins, PHI 2001.
- 2. Biomedical Signal Processing Principles and Techniques- D C Reddy, McGrawHill publications 2005

Reference Book:

1. Biomedical Signal Analysis-Rangaraj M. Rangayyan, John Wiley & Sons 2002

DIGITAL IMAGE PROCESSING [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VII 15MT754 **Subject Code IA Marks** 20 **Number of Lecture** 03 80 **Exam Marks** Hours/Week **40 Exam Hours** 03 **Total Number of Lecture Hours CREDITS - 03** Course objectives: Students will be able to 1. gain knowledge of image, sampling, quantization, enhancement, and restoration of image. 2. understand different methods of image enhancement and restoration. 3. transform image using different transformations. Hours Revised Bloom's Taxonomy(RBT) **Modules Teaching** Level Module -1 Digital image fundamentals: What is Digital image processing? Fundamental 8 Hours steps in digital image processing, components of an image processing system, elements of Visual Perception.

Module -2				
Images sensing and Acquisition: images sampling and Quantization's, Some	8 Hours			
Basic Relationships between Pixels, Linear and Nonlinear Operations.				
Module -3	-			
Image Transforms: Two-dimensional orthogonal & unitary transforms, properties	8 Hours			
of unitary transforms, two dimensional discrete Fourier transform. Discrete cosine				
transform, Hadamard transform, Haar transform,				
Module -4				
Image Enhancement: Image Enhancement in Spatial domain, Some Basic Gray	8 Hours			
Level Transformations, Histogram Processing, Enhancement using				
Arithmetic/Logic Operations. Basics of Spatial Filtering Image enhancement in the				
Frequency Domain filters, Smoothing Frequency Domain filters, Sharpening				
Domain filters, homomorphic filtering.				
Module -5				
Model of image degrading/restoration process: noise models, Restoration in the	8 Hours			
Present of Noise, Linear Position-Invariant Degradations, inverse filtering,				
minimum mean square error (Weiner) filtering. Color Fundamentals. Color Models,				

Pseudo color. Image Processing., processing basics of full color image processing

Course outcomes: On completion of the course the student will

CO1: have knowledge of different images, enhancement and restoration.

CO2: understand how images are formed, sampled, quantized and represented digitally.

CO3: process the images by applying different operations and transformation

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. "Digital Image Processing", Rafael C. Gonzalez and Richard e. Woods, Pearson Eucation, 2001, 2nd edition.

- 1. "Fundamentals of Digital Image Processing", Anil K, Jain, Pearson Edun, 20010
- 2. "Digital Image Processing and Analysis", B. Chanda and D. Dutta Majumdar, PHI, 2003

INDUSTRIAL ROBOTICS [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VII 15MT71 20 IA Marks Subject Code Number ofLecture Exam Marks 80 Hours/Week 04 Total Number of **Exam Hours** 03 50 Lecture Hours **CREDITS - 04**

- 1. gain knowledge of Robotics and automation.
- **2.** understand the working methodology of robotics and automation.
- **3.** write the program for robot for various applications.

Modules	Hours Teaching	RevisedBloom's Taxonomy(RBT) Level
Module -1		
Fundamentals of Automation: Automation and robotics, history of robotics, robotics market and future prospects. Fundamentals of Robotics: robot anatomy, work volume, robot drive systems, control systems, precision of movement, end effectors, robotic sensors, robot programming and work cell control, robot applications, problems. Basic control systems and components: Basic control systems concepts and models, control system analysis, robot sensors and actuators.		
Module -2		
Robot Motion Analysis: Introduction to manipulator kinematics, homogeneous transformations and robot kinematics, manipulator path control, robot dynamics, configuration of a robot controller.	10 Hours	
Robot End Effectors : types of end effecters, mechanical grippers, other types of grippers, tools as end effectors, robot/end effector interface, consideration in gripper selection and design, problems.		
Sensors in Robotics : Transducers and sensors, sensors in robotics, tactile sensors, proximity and range sensors, uses of sensors in robotics, problems.		
Module -3		
Machine Vision, : Introduction to machine vision, sensing and digitizing function in machine vision, image processing and analysis, training the vision system, robotic applications, problems.	10 Hours	
Robot Programming : Methods of robot programming, lead -through programming methods, a robot program as a path in space, motion interpolation, wait, signal and delay commands, branching, capabilities and limitations of lead-through methods, problems.		
Artificial Intelligence (AI): Introduction & goals of AI in research, AI techniques, LISP programming, AI & robotics, LISP in factory, robotic paradigms, problems.		
Module -4		
Robot Cell Design & Control : Robot cell layouts, multiple robots and machine interference, considerations in work -cell design, work-cell control, interlocks, error detection and recovery, work -cell controller, robot cycle time analysis, graphic simulation of robotic work-	10 Hours	

cells, problems. Material Transfer, Machine Loading/Unloading :Material Transfer, Machine Loading/Unloading: General considerations in robot material handling, material transfer applications, machine loading and unloading.		
Module -5		
Robots in Automatic Processing Operations: Introduction, spot welding, continuous arc		
welding, spray coating, other processing operations.	10 Hours	
Assembly & Inspection: Assembly and robotic assembly automation, parts presentation		
methods, assembly operations, compliance and remote centre compliance (RCC) device,		
assembly system configurations, adaptable programmable assembly system, designing for		
robotic assembly, inspection automation.		

Course outcomes:

On completion of course students will

CO1: have knowledge of Robotics, automation, robotics motion, sensors and control, machine vision, robotic programming and roles of robots in industry

CO2: understand the working methodology of robotics and automation, motion and control, machine vision and programming, application of robots in industry.

CO3: write the program for robot for various applications

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Mikell P. Groover, Mitchel Weiss, Roger N. Nagel, Nicholas G. Odrey and Ashish Dutta, "Industrial Robotics: Technology, Programming and Applications", 2 nd Edition, Tata McGraw Hill, 2012.
- 2. Roland Siegwart, Illah R. Nourbakhsh, and Davide Scaramuzza, "Introduction to Autonomous Mobile Robots", 2 nd Edition, PHI, 2011.

Machine Learning [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VII Subject Code 15MT752 20 IA Marks Number ofLecture 03 80 Exam Marks Hours/Week Total Number of 40 **Exam Hours** 03 Lecture Hours

CREDITS - 03

- gain Knowledge of Machine Learning, Decision Tree Learning, Artificial Neural Networks, Bayesian Learning, Evaluating Hypothesis.
- understand the working methodology of Machine Learning, Decision Tree Learning, Artificial Neural Networks, Bayesian Learning, evaluating Hypothesis.

		T
Modules	Hours Teaching	RevisedBloom's Taxonomy(RBT)
		Level
Module -1		
Introduction: Well posed learning problems, Designing a Learning system,		
Perspective and Issues in Machine Learning.	8 Hours	
Concept Learning: Concept learning task, Concept learning as search, Find-S		
algorithm, Version space.		
Module -2		•
Decision Tree Learning : Decision tree representation, Appropriate problems for	8 Hours	
decision tree learning, Basic decision tree learning algorithm, hypothesis space		
search in decision tree learning.		
Module -3		
Module -3		
Artificial Neural Networks: Introduction, Neural Network representation,	8 Hours	
Appropriate problems, Perceptrons, Backpropagation algorithm.		
Module -4		
Described Learning Land of the Described Descr	O Hauma	T
Bayesian Learning: Introduction, Bayes theorem, Bayes theorem and concept	8 Hours	
learning, ML and LS error hypothesis, ML for predicting probabilities, MDL		
principle, Naive Bayes classifier. Module -5		
Module - 3		
Evaluating Hypothesis: Motivation, Estimating hypothesis accuracy, Basics of	8 Hours	
sampling theorem, General approach for deriving confidence intervals, Difference		
in error of two hypothesis, Comparing learning algorithms.		
Course outcomes:		

On completion of course students will

CO1: Have Knowledge of Machine Learning ,Decision Tree Learning , Artificial Neural Networks, Bayesian Learning, Evaluating Hypothesis.

CO2: Understand the working methodology of Machine Learning ,Decision Tree Learning , Artificial Neural Networks, Bayesian Learning, Evaluating Hypothesis.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. Tom M. Mitchell, Machine Learning, India Edition 2013, McGraw Hill Education.

- 1. Trevor Hastie, Robert Tibshirani, Jerome Friedman, The Elements of Statistical Learning, 2nd edition, springer series in statistics.
- 2. Ethem Alpaydın, Introduction to machine learning, second edition, MIT press.

NANO TECHNOLOGY

[As per Choice Based Credit System (CBCS) scheme] SEMESTER – VII

Subject Code	15MT742	IA Marks	20
Number of Lecture Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	40	Exam Hours	03

CREDITS - 03

- 1. gain knowledge of nano structure, properties, manufacturing, and applications of silicon and carbon materials,.
- 2. understand what nanotechnology is about and Fabrication methods in nanotechnology (top down & bottom up), characterization methods in nanotechnology (optical, electrical, AFM, SEM, and TEM)

	Hours Teaching	Revised Bloom's Taxonomy(RBT)
	reacting	Level
Module -1		
An Overview of Nano science & Nanotechnology: Historical background	noturo 8 H	ours
•••	11000010,	ours
scope and content of the subject – multidisciplinary aspects – industrial, e and societal implications. Experimental techniques and methods: For inve		
and manipulating materials in the nano scale – electron microscope –	-	
probe microscope – optical and other microscopes	Scaiiiiig	
Module -2		
	<u> </u>	
Fullerenes: Discovery, synthesis and purification – chemistry of fullerene condensed phase – orientational ordering – pressure effects – conducti	vity and	urs
superconductivity – ferromagnetism – optical properties. Carbon Nan		
Synthesis and purification – filling of nano tubes – mechanism of g	•	
electronics structure – transport properties – mechanical and physical pro- applications	perties –	
Module -3		
self-Assembled Monolayer's: Monolayer's on gold – growth process	- phase 8 Ho	urs
transitions - patterning monolayer's - mixed Monolayer's - appl	lications.	
Semiconductor Quantum dots: Synthesis – electronic structure of nano c	rystals –	
how quantum dots are studied – correlation of properties with size – uses		
Module -4		
Monolayer – Protected Metal Nano particles: Method of prepar	ration – 8 Ho	urs
characterization – functionalized metal nano particles – applications- super		
Core-Shell Nano particles: Types – characterization – properties – applications.		
Nano shells – Types – Characterization – Properties – Applications.		

Module -5		
Nano biology - Interaction between bio molecules and nano particle surfaces -	8 Hours	
materials used for synthesis of hybrid nano-bio assemblies – biological applications		
- nano probes for analytical applications - nano biotechnology - future		
perspectives. Nano sensors: What make them possible – nano scale organization		
for sensors – characterization – nano sensors based on optical properties – nano		
sensors based on quantum size effects – electrochemical sensors – sensors based on		
physical		

Course outcomes: On completion of the course the student will

CO1: have the knowledge of essential concepts used in nanotechnology.

CO2:understand the methods used to characterize different nano materials

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- **1.** NANO: The Essentials, Understanding Nano science and Nanotechnology; T. Pradeep (Professor, IIT Madras); Tata McGraw-hill India (2007)
- 2. Nanotechnology, Richard Booker & Earl Boysen; Wiley (2005).

- 1. Introduction to Nano scale Science and Technology [Series: Nanostructure science and Technology], Di Ventra, et al (Ed); Springer (2004).
- 2. Nanotechnology Demystifies, Linda Williams & Wade Adams; McGraw-Hill (2007)
- 3. Introduction to Nanotechnology, Charles P Poole Jr. Frank JH Ownes, Wiley Pvt. Ltd., New Delhi, 2007.

Object Oriented Programming Using C++ [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VII Subject Code 15MT744 20 IA Marks Number ofLecture 80 Exam Marks 03 Hours/Week Total Number of 40 03 **Exam Hours** Lecture Hours

CREDITS - 03

- gain Knowledge of fundamentals of C++, classes, objects, constructors & destructors, function prototypes, private and public access and class implementations with inheritance and polymorphism.
- understand the C++ Programming using classes, objects, constructors & destructors, function prototypes, private and public access and class implementations with inheritance and polymorphism.

access and class implementations with inheritance and polymorphism.		
Modules	Hours Teaching	RevisedBloom's Taxonomy(RBT)
	reaching	Level
Module -1		1
Paginning with Colon and its features: What is Colon Applications and structure of		
Beginning with C++ and its features: What is C++, Applications and structure of	8 Hours	
C++ program, Different Data types, Variables, Different Operators, expressions,	0 110 113	
operator overloading and control structures in C++ (Topics from Ch -2,3 of Text).		
W-1-1- 2		
Module -2		
Functions, classes and Objects: Functions, Inline function, function overloading,	8 Hours	
friend and virtual functions, Specifying a class, C++ program with a class, arrays		
within a class, memory allocation to objects, array of objects, members, pointers to		
members and member functions (Selected Topics from Chap-4,5 of Text).		
Module -3		
Constructors, Destructors and Operator overloading: Constructors, Multiple	8 Hours	
constructors in a class, Copy constructor, Dynamic constructor, Destructors,		
Defining operator overloading, Overloading Unary and binary operators,		
Manipulation of strings using operators (Selected topics from Chap-6, 7 of Text).		
Module -4		
Inheritance, Pointers, Virtual Functions, Polymorphism: Derived Classes,	8 Hours	
Single, multilevel, multiple inheritance, Pointers to objects and derived classes, this		
pointer, Virtual and pure virtual functions (Selected 6 topics from Chap-8, 9 of		
Text).		
Module -5		
Streams and Working with files: C++ streams and stream classes, formatted and	8 Hours	1
unformatted I/O operations, Output with manipulators, Classes for file stream	5 110 415	
umormatica to operations, Output with manipulators, Classes for the stream		

operations, opening and closing a file, EOF (Selected topics from Chap-10, 11 of Text)

Course outcomes:

On completion of course students will

CO1: have Knowledge of fundamentals of C++, classes, objects, constructors & destructors, function prototypes, private and public access and class implementations with inheritance and polymorphism.

CO2: understand the C++ Programming using classes, objects, constructors & destructors, function prototypes, private and public access and class implementations with inheritance and polymorphism.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. Object Oriented Programming with C++, E.Balaguruswamy, TMH, 6th Edition, 2013.

Reference Books:

1. Object Oriented Programming using C++, Robert Lafore, Galgotia publication 2010.

ROBOTICS LABORATORY [As per Choice Based Credit System (CBCS) scheme] SEMESTER – VII			
Subject Code	15MTL77	IA Marks	20
Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	40	Exam Hours	03
CDEDITE 00			

CREDITS - 02

Course objectives: Students will be able to

- 1: Understand the Importance & Applications of Robots in Virtual Environment
- 2: Design the Robots system for Industrial Application

Laboratory Experiments:	Revised Bloom's Taxonomy
	(RBT)Level

LIST OF EXPERIMENTS

PART-A

- 1. Design the Robot programming for Point to Point using two Cubes.
- 2. Design the Robot programming for Drilling Operation using Cube and Cylinder.
- 3. Design the Robot programming using Smart Components.
- 4. Design the Robot programming for Mutimove Operation.
- 5. Design the Robot programming for Conveyor Tracking System.
- 6. Design the Robot programming for Continuous Path Operation on Cylinder

PART-B

- 1. Design a Robot System for Pick and Place Operation.
- 2. Design a Robot System for Point to Point operation. [Cube]
- 3. Design a Robot System for Continuous Path Operation.
- 4. Design a Robot System for Circle Path Operation.
- 5. Design a Robot System for Drilling Operation of Cube.
- 6. Design a Robot System for Continuous Path Operation for any 3 Objects [Cube, Box, Circle]

Note:

Part A: Experiments to be conducted using Software.

Part B: Experiments to be conducted using Robot system.

Course outcomes: On completion of the course the student will:

CO 1: Understand the importance of Robot system in Industrial Process in Virtual Environments

CO 2: Design and Develop a Robot System for Real time Industrial Process.

Scheme of Examination:

Experiment : Part A : 35 Marks

Part B: 35 Marks Viva- Voice: 10 Marks Total: 80 Marks

REAL TIME SYSTEMS

[As per Choice Based Credit System (CBCS) scheme] SEMESTER – VII

Subject Code	15MT743	IA Marks	20
Number of Lecture Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	40	Exam Hours	03

CREDITS - 03

- gain knowledge of real time systems, computer control, hardware & software requirements, operating systems, RTS developing methodologies.
- understand the operation of real time systems, computer control, hardware & software implementation for RTS, operating systems, RTS developing methodologies.

operating systems, RTS developing methodologies.		
Modules	Hours Teaching	Revised Bloom's Taxonomy(RBT) Level
Module -1	-	
Introduction to Real-Time systems: Historical background, RTS definition,	8 Hours	
Classification of Real-time systems, Time constraints, Classification of		
Programs.		
Concepts of computer control: Introduction, Sequence Control, Loop control,		
Supervisory control, Centralized computer control, Distributed system,		
Human-computer interface, Benefits of computer control systems.		
Module -2	<u> </u>	1
		1
Computer Hardware requirements for RTS: Introduction, General purpose	8 Hours	
computer, single chip microcontroller, specialized processors, Process-related		
Interfaces, Data transfer techniques, Communications, Standard Interface.		
Module -3		
Languages for Real-Time applications: Introduction, Syntax layout and	8 Hours	
readability, declaration and Initialization of Variables and Constants,		
Modularity and Variables. Compilation. Data types ,Control Structure,		
Exception Handling, Low-level facilities, Co routines, Interrupts and Device		
handling, concurrency, Real-time support, Overview of real-time languages.		
Module -4		
Operating Systems: Introduction, Real-time multi-tasking OS, Scheduling	08 Hours	
strategies. Priority Structures, Task management, Scheduler and real-time		
clock interrupt handles. Memory Management, Code sharing, Resource control,		
task co-operation and communication, Mutual exclusion, Minimum OS kernel.		
Module -5		1

Design of RTSS- General Introduction: Introduction, Specification	08Hours	
documentation, Preliminary design, single-program approach,		
Foreground/background systems.		
RTS development methodologies: Introduction, Yourdon Methodology,		
Ward and Mellor Method, Hately and Pirbhai method.		

Course outcomes: On completion of the course the student will

CO1: have knowledge of real time systems, computer control, hardware & software requirements, operating systems, RTS developing methodologies.

CO2: understand the operation of real time systems, computer control, hardware & software implementation for RTS, operating systems, RTS developing methodologies.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. Real – time Computer Control – an introduction, Sturt Bennel, 2ne Edn. Pearson Education. 2005.

- 1. Real-Time Systems Design and Analysis, Philip, a. Laplante, second edition, PHI, 2005.
- 2. Real-Time Systems Development, Rob Williams, 2006.
- 3. Embedded Systems, Raj Kamal, Tata McGraw Hill, India, 2005.

SAFETY AND SECURITY OF AUTOMOTIVE SYSTMES [AS PER CHOICE BASED CREDIT SYSTEM (CBCS) SCHEME]

VII SEMESTER

Subject Code	15MT753	IA Marks	20
Number ofLecture Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	40	Exam Hours	03

CREDITS - 03

- 1. gain knowledge of IC Engines, Fuel, Ignition, Lighting System
- 2. understand the working Principles of Transmission system ,Gear box, Lubrication system , CMV safety rules.

Tules.		
Modules	Hours Teaching	RevisedBloom's Taxonomy(RBT) Level
Module -1		
Types of automobiles: Limiting Dimensions as per Central Motor Vehicles Rules. Engines – classification, Construction, Materials of engine components. Prototype Testing as per Central motor Vehicles Rules. Fuel system – Fuel tank, Fuel filter, Types of fuel system. Carburetor – Simple and Modern, Fuel injection System. Emission standards as per CMV Rules.	8 Hours	
Module -2		
Electrical System: Storage battery Operations and Maintenance, Ignition System – Coil and Magneto Ignition System. Starting System, Lighting system, Horn System. Wiper motors, fans, heaters, trafi cators, automobile air conditioning. Central motor vehicles rules regarding lighting, windshields, Wipers. Module -3	8 Hours	
Transmission system : clutches – operation and fault finding of clutches, fluid flywheel, Gear box-types, steer systems, chassis springs, suspension.	8 Hours	
Module -4		
Differential, dead and Live axles: Rims, Tyre etc. Brakes – types, construction and fault finding, CMV rules – brakes, Steering & tyre. Module -5	8 Hours	
Lubrication systems: types, components, lubricating oil, cooling system – details	8 Hours	

of components, study of systems, types.

Miscellaneous – special gadgets and accessories for fire fighting vehicles. Automobile accidents. CMV rules regarding safety devices for drivers, passengers.

Course outcomes:

On completion of course students will

CO1: have knowledge of IC Engines, Fuel, Ignition, Lighting System

CO2: understand the working Principles of Transmission system, Gear box, Lubrication system, CMV safety rule

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. CBS Narang, Automobile Engineering.
- 2. Kirpal Singh, Automobile Engineering.

- 1. William H. Crouse, **Automobile Chassis and Body constructions**, operation and Maintenance.
- 2. William H. Crouse, Automobile machines Principles & operations.
- 3. Joseph Heitner, Automotive Mechanics-Principles & Practices
- 4. P. L. Kohli, Automotive Electrical Equipments.
- 5. The central Motor Vehicles Rules, 1989.

SIGNAL PROCESS [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VII 15MT73 **Subject Code** 20 **IA Marks Number of Lecture Exam Marks** 80 Hours/Week 04 03 50 **Total Number of Exam Hours Lecture Hours CREDITS - 04** Course objectives: Students will be able to 1. gain knowledge of signal, system, transformation and filter. 2. understand time domain, frequency domain signals, analog and digital systems. 3. operate on signals and systems to bring out its characteristics and desired information. 4. design analog and digital filers and implement discrete time systems. Modules Revised Bloom's Hours Teaching Taxonomy(RBT) Level Module -1 Introduction: Definitions of a signal and a system, classification of signals, basic 10 Hours Operations on signals, Basic elementary signals, properties of systems. Module -2 Time-domain representations for LTI systems: Convolution, impulse response 10 Hours representation, Convolution Sum and Convolution Integral. Properties of impulse response representation, Module -3 Discrete Fourier Transforms (DFT): Introduction to DFT, Properties of DFT, 10 Hours multiplication of two DFTs- the circular convolution, additional DFT properties, use of DFT in linear filtering, overlap-save and overlap-add method. Fast-Fourier-Transform (FFT) algorithms: Direct computation of DFT, need for efficient computation of the DFT (FFT algorithms). Radix-2 FFT algorithm computation of DFT and IDFT-decimation-in-time and Decimation-in-frequency algorithms Module -4 IIR filter design: Characteristics of commonly used analog filters – Butterworth 10 Hours

and Chebyshev filters, analog to analog frequency transformations. Design of IIR filters from analog filters (Butterworth and Chebyshev) - impulse invariance method. Mapping of transfer functions: Approximation of derivative (bilinear transformation) method, Verification for stability and linearity during mapping

FIR filter design: Introduction to FIR filters, design of FIR filters using - 10 Hours	
Rectangular, Hamming, Hanning and Kaiser windows, FIR filter design using	
frequency sampling Technique.	
Implementation of discrete-time systems: Structures for IIR and FIR systems-direct	
form I and direct form II systems, cascade, lattice and parallel realization.	

Course outcomes: On completion of the course the student will

CO1: have knowledge of signal, system, transformation, filter design.

CO2: understand the difference between time domain, frequency domain, analog and digital filters.

CO3: transform the signals from one domain to other domain using transformation techniques.

CO4: design analog and digital filters for specific applications.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. **Digital signal processing Principles Algorithms & Applications**, Proakis & Monalakis, Pearson education, 4th Edition, New Delhi, 2007.
- 2. "Signals and Systems", Simon Haykin and Barry Van Veen John Wiley & Sons, 2001.

- 1. **Discrete Time Signal Processing**, Oppenheim & Schaffer, PHI, 2003.
- 2. **Digital Signal Processing**, S. K. Mitra, Tata Mc-Graw Hill, 2nd Edition, 2004.
- 3. **Digital Signal Processing**, Lee Tan: Elsivier publications, 2007
- 4. Alan V Oppenheim, Alan S, Willsky and A Hamid Nawab, "Signals and Systems" Pearson Education Asia / PHI, 2nd edition, 1997. Indian Reprint 2002
- 5. H. P Hsu, R. Ranjan, "Signals and Systems", Scham's outlines, TMH, 2006
- 6. B. P. Lathi, "Linear Systems and Signals", Oxford University Press, 2005.
- 7. Ganesh Rao and Satish Tunga, "Signals and Systems", Sanguine Technical Publishers, 2004.

RADAR ENGINEERING

[As per Choice Based Credit System (CBCS) scheme] SEMESTER – VIII

Subject Code	15MT835	IA Marks	20
Number ofLecture Hours/Week	03	Exam Marks	80
Total Number of Lecture Hours	40	Exam Hours	03

CREDITS - 03

- gain Knowledge of Radars , The Radar Equation, MTI and Pulse Doppler Radar, Tracking Radar & The Radar Antenna.
- understand the operation of Radars, MTI and Pulse Doppler Radar, Tracking Radar & the Radar Antenna.

Module -1 Basics of Radar: Introduction, Maximum Unambiguous Range, Radar Waveforms, Definitions w.r.t Pulse waveform - PRF, PRI, Duty Cycle, Peak Transmitter Power, Average transmitter Power. Simple form of the Radar Equation, Radar Block Diagram and Operation, Radar Frequencies, Applications of Radar, The Origins of Radar, Illustrative Problems. (Chapter 1 of Text) Module -2 The Radar Equation: Prediction of Range Performance, Detection of signal in Noise, Minimum Detectable Signal, Receiver Noise, SNR, Modified Radar Range Equation, Envelope Detector — False Alarm Time and Probability, Probability of Detection, Radar Cross Section of Targets: simple targets - sphere, cone-sphere, Transmitter Power, PRF and Range Ambiguities, System Losses (Qualitative treatment), Illustrative Problems. (Chapter 2, except 2.4, 2.6 2.8 & 2.11 of Text) Module -3 MTI and Pulse Doppler Radar: Introduction, Principle, Doppler Frequency Shift, Simple CW Radar, Sweep to Sweep subtraction and Delay Line Canceler, MTI Radar with - Power	om's (RBT)
w.r.t Pulse waveform - PRF, PRI, Duty Cycle, Peak Transmitter Power, Average transmitter Power. Simple form of the Radar Equation, Radar Block Diagram and Operation, Radar Frequencies, Applications of Radar, The Origins of Radar, Illustrative Problems. (Chapter 1 of Text) Module -2 The Radar Equation: Prediction of Range Performance, Detection of signal in Noise, Minimum Detectable Signal, Receiver Noise, SNR, Modified Radar Range Equation, Envelope Detector — False Alarm Time and Probability, Probability of Detection, Radar Cross Section of Targets: simple targets – sphere, cone-sphere, Transmitter Power, PRF and Range Ambiguities, System Losses (Qualitative treatment), Illustrative Problems. (Chapter 2, except 2.4, 2.6 2.8 & 2.11 of Text) Module -3 MTI and Pulse Doppler Radar: Introduction, Principle, Doppler Frequency Shift, Simple CW 8 Hours	
The Radar Equation: Prediction of Range Performance, Detection of signal in Noise, Minimum Detectable Signal, Receiver Noise, SNR, Modified Radar Range Equation, Envelope Detector — False Alarm Time and Probability, Probability of Detection, Radar Cross Section of Targets: simple targets – sphere, cone-sphere, Transmitter Power, PRF and Range Ambiguities, System Losses (Qualitative treatment), Illustrative Problems. (Chapter 2, except 2.4, 2.6 2.8 & 2.11 of Text) Module -3 MTI and Pulse Doppler Radar: Introduction, Principle, Doppler Frequency Shift, Simple CW 8 Hours	
Minimum Detectable Signal, Receiver Noise, SNR, Modified Radar Range Equation, Envelope Detector — False Alarm Time and Probability, Probability of Detection, Radar Cross Section of Targets: simple targets – sphere, cone-sphere, Transmitter Power, PRF and Range Ambiguities, System Losses (Qualitative treatment), Illustrative Problems. (Chapter 2, except 2.4, 2.6 2.8 & 2.11 of Text) Module -3 MTI and Pulse Doppler Radar: Introduction, Principle, Doppler Frequency Shift, Simple CW 8 Hours	
MTI and Pulse Doppler Radar: Introduction, Principle, Doppler Frequency Shift, Simple CW 8 Hours	
Amplifier Transmitter, Delay Line Cancelers — Frequency Response of Single Delay- Line Canceler, Blind Speeds, Clutter Attenuation, MTI Improvement Factor, N- Pulse Delay-Line Canceler, Digital MTI Processing – Blind phases, I and Q Channels, Digital MTI Doppler signal processor, Moving Target Detector- Original MTD. (Chapter 3, 3.1, 3.2, 3.5, 3.6 of Text)	
Module -4	
Tracking Radar: Tracking with Radar- Types of Tracking Radar Systems, Monopulse 8 Hours TrackingAmplitude Comparison Monopulse (one-and two-coordinates), Phase Comparison Monopulse. Sequential Lobing, Conical Scan Tracking, Block Diagram of Conical Scan Tracking Radar, Tracking in Range, Comparison of Trackers. (Chapter 4, 4.1, 4.2, 4.3 of Text) Module -5	
The Radar Antenna: Functions of The Radar Antenna, Antenna Parameters, Reflector 8 Hours	

Antennas and Electronically Steered Phased array Antennas. (Chapter 9: 9.1, 9.2 9.4, 9.5 of Text) Radar Receiver: The Radar Receiver, Receiver Noise Figure, Super Heterodyne Receiver, Duplexers and Receivers Protectors, Radar Displays. (Chapter 11 of Text)

Course outcomes:

On completion of course students will

CO 1: have knowledge of Radars, the Radar Equation, MTI and Pulse Doppler Radar, Tracking Radar and the Radar Antenna.

CO 2: understand the operation of Radars, MTI and Pulse Doppler Radar, Tracking Radar & the Radar Antenna.

Graduate Attributes (as per NBA):

Question paper pattern:

The question paper will have TEN questions.

Each full question consists of 16 marks.

There will be 2 full questions (with maximum of FOUR sub questions) from each module.

Each full question will have sub questions covering all the topics under a module.

The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

1. Introduction to Radar Systems-Merrill I Skolnik ,3e,TMH, 2001

- 1. Radar Principles, Technology. Applications Byron Edde, Pearson Education, 2004.
- 2. Radar Principles Peebles. Jr, P.Z. Wiley. New York, 1998.
- 3. Principles of Modem Radar: Basic Principles Mark A. Rkhards, James A. Scheer, William A. Holm. Yesdee, 2013

Management Information Systems [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VIII Subject Code 15MT834 IA Marks 20 Number ofLecture 03 Exam Marks 80 Hours/Week Total Number of 40 **Exam Hours** 03 **Lecture Hours**

CREDITS - 03

- gain the importance of information in business.
- understand the technologies and methods used for effective decision making in an organization.

Modules	Hours Teaching	RevisedBloom's Taxonomy(RBT) Level
Module -1		
INTRODUCTION: Data, Information, Intelligence, Information Technology, Information System, evolution, types based on functions and hierarchy, System development methodologies, Functional Information Systems, DSS, EIS, KMS, GIS, International Information System.	8 Hours	
Module -2		•
SYSTEM ANALYSIS AND DESIGN: Case tools - System flow chart, Decision table, Data flow Diagram (DFD), Entity Relationship (ER), Object Oriented Analysis and Design (OOAD), UML diagram.	8 Hours	
Module -3	,	
DATABASE MANAGEMENT SYSTEMS: DBMS – HDBMS, NDBMS, RDBMS, OODBMS, Query Processing, SQL, Concurrency Management, Data warehousing and Data Mart.	8 Hours	
Module -4		1
SECURITY, CONTROL AND REPORTING: Security, Testing, Error detection, Controls, IS Vulnerability, Disaster Management, Computer Crimes, Securing the Web, Intranets and Wireless Networks, Software Audit, Ethics in IT, User Interface and reporting.	8 Hours	
Module -5		•
NEW IT INITIATIVES: Role of information management in ERP, e-business, e-governance, Data Mining, Business Intelligence, Pervasive Computing, Cloud	8 Hours	

computing, CMM.

Course outcomes:

On completion of course students will

CO1: have knowledge on effective applications of information systems in business.

CO2: understand the technologies and methods used for effective decision making in an organization.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question carries 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- **1. Management Information Systems The Managers View,** Robert Schultheis and Mary Summer, Tata McGraw Hill, 2008.
- **2. Management Information Systems Managing the digital firm**, Kenneth C. Laudon and Jane Price Laudon, PHI Learning / Pearson Education, PHI, Asia, 2012.

- 1. MIS in Business, Government and Society, Rahul de, Wiley India Pvt Ltd, 2012
- 2. **Management Information System: Conceptual Foundations, Structure and Development,** Gordon Davis, Tata McGraw Hill, 21st Reprint 2008.
- 3. **Management Information Systems for the Information Age,** Haag, Cummings and Mc Cubbrey, McGraw Hill, 2005. 9th edition, 2013.
- 4. **Information Technology for Management Transforming Organisations in the Digital Economy,** Turban, McLean and Wetherbe, John Wiley, 6th Edition, 2008.
- 5. **Management Information Systems,** Raymond McLeod and Jr. George P. Schell, Pearson Education, 2007.
- 6. Management Information Systems Managing Information Technology in the E-business enterprise, James O Brien, Tata McGraw Hill, 2004. 22.
- 7. **Information Systems,** Raplh Stair and George Reynolds, Cengage Learning, 10th Edition, 2012
- 8. **Information Assurance for the Enterprise A Roadmap to Information Security,** Corey Schou and Dan Shoemaker, Tata McGraw Hill, 2007.
- 9. **Information Technology Control and Audit,** Frederick Gallegor, Sandra Senft, Daniel P. Manson and Carol Gonzales, Auerbach Publications, 4th Edition, 2013.

ARTIFICIAL INTELLIGENCE [As per Choice Based Credit System (CBCS) scheme] SEMESTER - VIII Subject Code 15MT832 20 IA Marks Number ofLecture 03 80 Exam Marks Hours/Week Total Number of 40 **Exam Hours** 03 Lecture Hours

CREDITS - 03

- gain Knowledge of Artificial Intelligence, Production Rules, Search Algorithms, Expert System & its architectures, Machine Learning.
- understand the working methodology of Search Algorithms, Expert System & Machine Learning.

Modules	Hours Teaching	RevisedBloom's Taxonomy(RBT) Level
Module -1	1	
Artificial Intelligence: Introduction, History of AI, defining, , Importance f AI, Early Work in AI, Scope of AI, AI and Related fields, AI Techniques ,Alan Turing Machine, Intelligent Agents.	8 Hours	
Module -2		
Space Representation : Defining the Problem, Production Rules for water jug problem, Breadth-First Search Algorithm, Depth-First Search Algorithm, Generate & Test Algorithm, Hill Climbing Algorithms: Simple Hill Climbing Algorithm, Steepest-Ascent Hill Climbing Algorithm.	8 Hours	
Module -3	1	1
Expert Systems: Introduction, Characteristics of Expert System, Need of an Expert System, Expert System Architecture, Steps to develop an Expert System ,case studies: MYCIN ,DENDRAL. and Neural Nets: Introduction ,TAN-Toy Adaptive Node ,Network Structures, Application of Neural Nets. Module -4	8 Hours	
Expert Systems Architectures : Introduction ,Rule-Based System Architectures ,Non- Production system Architectures: Semantic Network Architectures, Frame Architectures ,Decision Tree Architectures, Blackboard System Architectures, Analogical Reasoning Architectures, Neural Network Architectures.	8 Hours	
Module -5		
Introduction to Machine Learning: Introduction, Perceptrons, Perceptron Learning Algorithm, Checkers Playing Examples, Learning automata: Automaton	8 Hours	

model, Temperature Control Model, CLA representation of NIM game, Genetic Algorithms, Intelligent editors .

Course outcomes:

On completion of course students will

CO1: have Knowledge of Artificial Intelligence, Production Rules, Search Algorithms, Expert System & its architectures, Machine Learning.

CO2: understand the working methodology of Search Algorithms, Expert System & Machine Learning.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. **Artificial Intelligence**, Elaine Rich & Kevin Knight, M/H 2004.
- 2. Introduction to AI & ES, Dan W. Patterson, Prentice Hall of India, 2012.
- 3. **Artificial Intelligence A Practical Approach**, Er.Rajiv Chopra, S.Chand & Company Ltd, 2012.

- 1. **Principles of Artificial intelligence**, Springer Vertag, Berlin, 1981.
- 2. Artificial intelligence in business, Science & Industry, Wendy B, Ranch
- **3.** A guide to Expert systems, Waterman, D. A. Addison Wesley inc. 1986.
- 4. Building Expert Systems, Hayes, Roth, Waterman, D. A. Addison Wesley, 1983.

AUTOMOTIVE ELECTRONICS AND HYBRID VEHICLES

[As per Choice Based Credit System (CBCS) scheme] SEMESTER – VIII

Subject Code	15MT81	IA Marks	20
Number of Lecture Hours/Week	04	Exam Marks	80
Total Number of Lecture Hours	50	Exam Hours	03

CREDITS - 04

- gain Knowledge of developing basic skills necessary to diagnose automotive electrical problems, to include electrical principles, use of basic electrical test equipment.
- understand the advanced automotive electrical systems, to include body electrical accessories, and basic computer control.
- diagnosis the problem automotive batteries, starting, and charging, lighting systems, body electrical accessories, and basic computer control.

Modules	Hours Teaching	Revised Bloom's Taxonomy(RBT) Level
Module -1		
Automotive Fundamentals Overview:Four Stroke Cycle, Engine Control, Ignition System, Spark plug, Spark pulse generation, Ignition Timing, Drive Train, Transmission, Brakes, Steering System, Battery, Starting System.Air/Fuel Systems Fuel Handling, Air Intake System, Air/ Fuel Management	10 Hours	
Module -2		
Sensors – Oxygen (02/EGO) Sensors, Throttle Position Sensor (TPS), Engine Crankshaft Angular Position (CKP)Sensors, Hall effect Position Sensor, Shielded Field Sensor, Optical Crankshaft Position Sensor, Manifold Absolute Pressure (MAP) Sensor – Strain gauge and Capacitor capsule, Engine Coolant Temperature (ECT) Sensor, Intake Air Temperature (IAT) Sensor, Knock Sensor, Airflow rate sensor, Throttle angle Sensor. Actuators: Fuel Metering Actuator, Fuel Injector, Ignition Actuator. Exhaust After-Treatment Systems – AIR, Catalytic Converter, Exhaust Gas Recirculation (EGR), Evaporative Emission Systems.	10 Hours	
Module -3		
Automotive Instrumentation and Communication: Sampling, Measurement & Signal Conversion of various parameters (Speed, fuel, pressure). Serial Data, Communication Systems, Protection, Body and Chassis is Electrical Systems,	10 Hours	

Remote Keyless Entry, GPS						
Module -4						
Vehicle Motion Control: Cruise control, Chassis, Power Brakes, Antilock Brake System (ABS), Electronic Steering Control, Power Steering, Traction Control, Electronically controlled suspension. Automotive Diagnostics –Timing Light, Engine Analyzer, On-board diagnostics, Off-board diagnostics, Expert Systems.	10 Hours					
Future Automotive Electronics Systems: Alternative Fuel Engines, Collision Avoidance Radar warning Systems, Low tire pressure warning system, Radio navigation, Advance Driver Information System						
Module -5						
Introduction to Alternative Vehicles: Electric Vehicle, Hybrid Electric vehicle, Electric Hybrid Vehicle, Vehicle components, Electric and Hybrid history EV/CEV Comparison. Alternative Vehicle Architecture: Electric Vehicles, Hybrid Electric Vehicles, Plug-in Hybrid Electric Vehicles, Power Train component Sizing, Mass Analysis & Packaging, Vehicle Simulation.	10 Hours					
Course outcomes: On completion of the course the student will						

CO1: have knowledge of automotive electronics domain of various Engine parts, Sensor, Actuator, Communication and Measurement System.

CO2: understanding the engine parameters and a critical awareness of current problems within the automotive electronics domain using Various Measurement Technology.

CO3: determine the extent and nature of electronic circuitry in automotive systems including monitoring and control circuits for engines, transmissions, brakes, steering, suspension, climate control, instrumentation and radios and accessories involved in Automotive Industry.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1) William B. Ribbens: Understanding Automotive Electronics, 6th Edition, SAMS/Elsevier Publishing
- 2) Iqbal Husain "Electric and Hybrid Vehicles: Design fundamentals". CRC Press, 2011.

- 1. Robert Bosch GmbH: Automotive Electronics Systems and Components 5th Edition, John Wiley & Sons Ltd., 2007
- 2. James Laminie and John Lowry. "Electric Vehicle Technology Explained", CRC Press 2010.
- 3. Society of Automobile Engineers, "Hybrid Electric vehicles", CRC Press, 2011.

COMMUNICATION SYSTEM

[As per Choice Based Credit System (CBCS) scheme] SEMESTER – VIII

Subject Code	15MT81	IA Marks	20
Number of Lecture Hours/Week	04	Exam Marks	80
Total Number of Lecture Hours	50	Exam Hours	03

CREDITS - 04

- gain the Knowledge Of different modulation techniques, analog and digital modulation and demodulation, different wave form code techniques and spread spectrum
- understand the concept of methods of generating modulated and demodulated signals, encoding and decoding techniques, multiplexing and demultiplexing of signals

Modules	Hours Teaching	Revised Bloom's Taxonomy(RBT) Level
Module -1		
Introduction To Communication Systems: Information, Transmitter, chanel- noise, Receiver, modulation, need for modulation, band width requirements, sine wave and Fourier series review, frequency spectra of non sinusoidal waves. Basic signal processing operations in digital communication. Sampling Principles: Sampling Theorem	10 Hours	
Module -2		
Amplitude Modulation: Introduction AM Time-Domain description, Frequency – Domain description. Generation of AM wave: square law modulator, switching modulator. Detection of AM waves: square law detector, envelop detector. Double side band suppressed carrier modulation (DSBSC): Time-Domain description, Frequency-Domain representation, Generation of DSBSC waves: balanced modulator, ring modulator. Coherent detection of DSBSC modulated waves. Costas loop.	10 Hours	
Module -3		
Angle Modulation & Demodulation: Basic definitions, FM, narrow band FM, wide band FM, transmission bandwidth of FM waves, generation of FM waves: indirect FM and direct FM, Demodulation of FM waves, FM stereo multiplexing, Phase-locked loop, Nonlinear model of the phase – locked loop, Linear model of the phase – locked loop, Nonlinear effects in FM systems.	10 Hours	
Module -4		

Waveform Coding Techniques: PAM, TDM. Waveform Coding Techniques,	10 Hours		
PCM, Quantization noise and SNR, robust quantization. DPCM, DM, applications. Line			
Codes: Unipolar RZ& NRZ, Polar RZ& NRZ, Bi-Polar RZ & NRZ, Manchester			
Module -5			
Spread Spectrum Modulation: Pseudo noise sequences, notion of spread	10 Hours		
spectrum, direct sequence spread spectrum, coherent binary PSK, frequency hop			
spread spectrum, applications. Digital Multiplexers: FDM ,TDM ,Classification of			
Multiplexers ,T1 Carrier System			

Course outcomes: On completion of the course the student will

CO 1: have Knowledge Of different modulation techniques, analog and digital modulation and demodulation, different wave form code techniques and spread spectrum

CO 2: understand the concept of generation modulated and demodulated signals, encoding and decoding techniques multiplexing and demultiplexing of signals

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Communication Systems, Simon Haykins, 3rd Edition, John Willey, 1996.
- 2. An Introduction to Analog and Digital Communication, Simon Haykins, John Wiley, 2003
- 3. Digital communications, Simon Haykin, John Wiley, 2003.

- 1. Modern digital and analog Communication systems B. P. Lathi, 3rd ed 2005 Oxford University press.
- 2. Communication Systems, Harold P.E, Stern Samy and A Mahmond, Pearson Edn, 2004.
- 3. Communication Systems: Singh and Sapre: Analog and
- 4. Digital and analog communication systems & An introduction to Analog and Digital Communication, K. Sam Shanmugam, John Wiley, 1996. 2.Simon Haykin, John Wiley, 2005

DIGITAL CONTROL SYSTEM

[As per Choice Based Credit System (CBCS) scheme] SEMESTER – VIII

Subject Code	15MT833	IA Marks	20
Number of Lecture Hours/Week	04	Exam Marks	80
Total Number of Lecture Hours	40	Exam Hours	03

CREDITS - 03

- gain knowledge to learn the concepts of developing State model, Linear and Non Linear Control System.
- understand the concepts Linear and Non Linear Digital Control System for observing the Controllability of the system
- determine and diagnosis the problem related Lead and Lag Networks using Plots.

	Hours Teaching	Revised Bloom's Taxonomy(RBT) Level	
Module -1			
STATE SPACE ANALYSIS OF CONTROL SYSTEMS : State space representation of systems, solving the time invariant state equations, transfer matrix, linear time invariant systems, state space representation of discrete time systems and solving discrete time state equation.			
Module -2			•
POLE PLACEMENT: Controllability, Observability for continuous time systems, pole placement design and state observers. Problems on Each		8 Hours	
Module -3			1
OPTIMAL AND ADAPTIVE CONTROL SYSTEMS : optimal control based on quadratic performance index, adaptive control system.	system	8 Hours	
Module -4			
DESCRIBING FUNCTION ANALYSIS OF NONLINEAR CONTROL SYSTEMS: Introd nonlinear systems, describing function analysis of nonlinear control systems, s nonlinear control system.		8 Hours	
Module -5			•
COMPENSATION TECHNIQUES: Lead, lag, lead lag network and compensator des Bode/Root locus techniques.	sign using	8 Hours	
Course outcomes: On completion of the course the student will CO1: have knowledge of State model, Linear and Non Linear Control System, Control	llability and	Observabili	ty.

CO2: understanding the concepts State model, Linear and Non Linear Control System, Controllability and Observability used in Digital Control System.

CO3: determine the extent and nature of Lead Lag Circuitry by Plot.

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- 1. Modern Control Engineering-K. Ogata, Prentice 3rd Edition, Hall of India publication.
- 2. Discrete time Control Systems-K.Ogata, 2nd Edition, Prentice Hall of India publication.

- 1. Digital control and state variable methods-Madan Gopal, 2nd Edition, Prentice Hall of India.
- 2. Modern Control Engineering-Roy Choudhury, Prentice Hall of India.

		r Choice Based Credit System (C SEMESTER – VIII				
Subject Code	15MT831	IA Marks		20		
Number ofLecture Hours/Week	03	Exam Marks	80			
Total Number of Lecture Hours	40	Exam Hours	03			
		CREDITS - 03				
1. gain kno	0	ife-cycle, Product design preering, product design tools	,	-	RevisedBloom's	
Modules		Teaching	Taxonomy(RBT) Level			
		Module -1			•	
_	e: Product policy of esign process, Produc	f an organization. Selection et analysis.	of a profitable	8 Hours		
		Module -2			1	
design, Problem id function. Primary	lentification and sele versus secondary	ign: Advantages, Applicate ection, Analysis of function y versus tertiary/unnecess System Technique (FAST)	ns, Anatomy of sary functions,	8 Hours		
		Module -3		1		
Introduction to product design tools: QFD, Computer Aided Design, Robust design, DFX, DFM, DFA, Ergonomics in product design			8 Hours			
		Module -4			1	
metallic products	to be manufactured	y: Design guidelines for many of the processes of the prototyping, needs, advantage of the prototyping of th	uch as casting,	8 Hours		
		Module -5		I		
digitizing techniqu	ies - construction	dimensional- developing to of surface model - solid application prototyping - ve	d-part material-	8 Hours		

Course outcomes:

On completion of course students will

CO1: have knowledge of Product life-cycle, Product design process, Product analysis.

CO2: understand the value engineering, product design tools and Reverse Engineering

Graduate Attributes (as per NBA):

Question paper pattern:

- The question paper will have TEN questions.
- Each full question consists of 16 marks.
- There will be 2 full questions (with maximum of FOUR sub questions) from each module.
- Each full question will have sub questions covering all the topics under a module.
- The students will have to answer 5 full questions, selecting one full question from each module.

Text Books:

- **1. Product Design** and **Development** by Karl T. Ulrich and Steven D. Eppinger (McGraw-Hill 1995, 2000, 2004, 2008)
- 2. Reverse Engineering, Katheryn, A. Ingle, McGraw-Hill, 1994

- 1. "**Engineering Design**", George E.Dieter, Linda C.Schmidt, McGraw-Hill International Edition, 4th Edition, 2009, ISBN 978-007-127189-9
- 2. "**Product Design and Development**", Anita Goyal, Karl T Ulrich, Steven D Eppinger, 4th Edition, 2009, Tata McGraw-Hill Education, ISBN-10-007-14679-9
- 3. "**Product Design**", Kevin Otto, Kristin Wood, Indian Reprint 2004, Pearson Education,ISBN 9788177588217
- 4. "Engineering Design Process", Yousef Haik, T. M. M. Shahin, 2nd Edition Reprint, Cengage Learning, 2010, ISBN 0495668141
- 5. "Engineering Design: A Project-based Introduction", Clive L.Dym, Patrick Little, 3rd Edition, John Wiley & Sons, 2009, ISBN 978-0-470-22596-7